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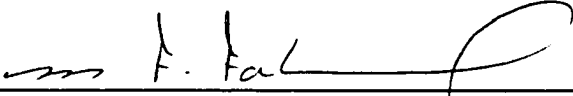
Submitted

In Partial Fulfillment


of the Requirements for the Degree

Doctor of Industrial Technology

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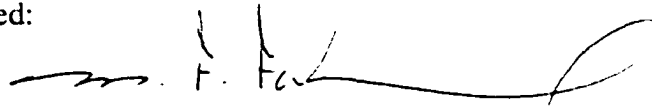
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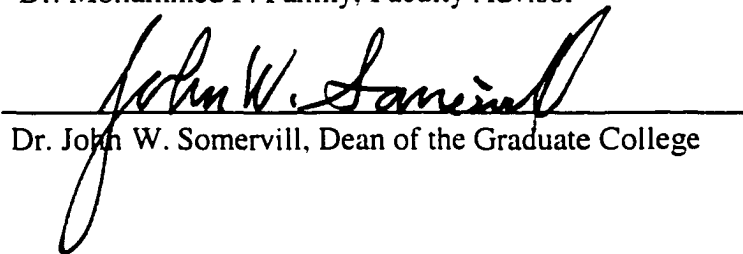
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Dr. John W. Somervill, Dean of the Graduate College

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ABSTRACT

Production planning and control (PP&C) are among the most critical activities in manufacturing. Proper use of PP&C methods can give organizations a competitive advantage in the global economy. The expected results of this research will allow manufacturing organizations to maximize the effectiveness of PP&C methods, thereby improving their competitive position in the global economy.

This research was an extension of a previous unpublished study, which investigated the PP&C methods being used at a midwestern manufacturer of agricultural equipment (MMAE). The current research study identified the constraints inherent in the production planning and control system and then developed and validated a master production scheduling and sequencing optimization model based on constraints management and utilizing genetic algorithms.

The specific objectives of this research were as follows: (a) identify the system's constraint, (b) develop a scheduling and sequencing model to address the identified constraints, (c) develop and validate the proposed model by simulation, and (d) identify and document improvements attributed to the operational change resulting from the implementation of the optimization model.

The research examined the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on five variables for the final assembly line and four downstream processes at an engine manufacturing plant of a MMAE. The variables were cycle time, queue size, utilization of work centers, flow rate of engines, and total output of engines.

A two-part model, based on constraints management philosophy of production planning and control methods, was developed by the researcher in Excel, one part for scheduling and the other for sequencing. Using data from 100 production days during the fall of 1999 and the spring of 2000, simulations for the current scheduling and sequencing method (the control condition) and for the proposed method (the experimental condition) were compared. Output from the simulations for the experimental and control conditions was statistically analyzed.

The results of this research indicated (a) cycle time for the experimental condition was reduced, but the reduction was not statistically significant; (b) queue size for the experimental condition was also reduced, as expected, but once again, the reduction was not statistically significant; (c) total utilization of work centers was increased, as expected, and the increase was statistically significant; (d) the experimental condition's simulation results indicated very minimal improvements for the even flow of engines; and (e) the average total number of engines processed for the experimental condition was increased, as expected, and the increase was statistically significant.

DEDICATION

This doctoral dissertation is dedicated

To my mother, who dedicated

her life for the sake of mine.

To my mother, I am eternally grateful

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CHAPTER I

INTRODUCTION

Background

Manufacturing after World War II

World War II brought about many changes to the manufacturing industry worldwide. Manufacturing in America flourished during the war because its industrial infrastructure base had remained intact whereas the industrial infrastructures in Europe, Russia, and Asia were destroyed. Even Asian countries not directly involved in the war were not able to compete in the international market due to the lack of technological advances in their manufacturing industries. As a result, the only nation left to lead the world in manufacturing was the United States. American manufacturers understood this opportunity and became the undisputed mass production leaders of the world.

From the 1940s to the 1960s, American manufacturers enjoyed a period of prosperity. During this time, mass production was emphasized, but quality was not much of a concern for many manufacturers. In the middle 1960s, a few foreign countries started to compete with American products in the international and U.S. markets. This trend continued so that by the 1970s and 1980s, the United States was beginning to “look like an economic colony of Japan” (Wight, 1984, p. 9). American manufacturers were forced to look critically at their cost structures. During the oil embargo and inflation cycle of the 1970s, American manufacturing firms recognized the need to reduce waste and control costs.

One way for the manufacturing industry to stay competitive was to reduce total costs, focusing particularly on inventory and inventory-related costs. That is the goal of

the production planning and control (PP&C) system, which is one of the most critical activities in the manufacturing environment (Vollmann, Berry, & Whybark, 1988).

Proper use of PP&C methods can give organizations a competitive advantage in the global economy (Bai & Tsai, 1994). Hopp and Spearman (1996) suggest a hierarchical planning framework of production planning and control. Their framework is divided into three basic levels, as depicted in Figure 1: (a) strategy (long-term planning), (b) tactics (intermediate-term planning), and (c) control (short-term planning).

Evolution of the Production Planning and Control Systems

Before the development of computer technology, production planning and control functions were mainly accomplished manually. Some of the common techniques used were the two-bin system, economic order quantity (EOQ), and reorder point (Gilbert & Schonberger, 1983).

During the 1960s, when computers began to be used in the manufacturing industry, the material requirement planning (MRP) technique was developed by Joseph Orlicky (Taylor, 1994). MRP is a tool used for material and priority planning, the basic function of an MRP system is to plan for material requirements based on planned production levels. The remarkable growth in computing power, along with the reduction in the size and price of computers, allowed for the accelerated implementation of MRP in the United States. This system was considered to be far superior to the older reorder point systems (Orlicky, 1975; Wight, 1974), and it became a phenomenal success. Organizations that implemented the MRP technique increased their inventory turnover per year by more than 100% compared with more traditional production planning and control methods (Hall, 1983). MRP has been used in America since the 1970s,

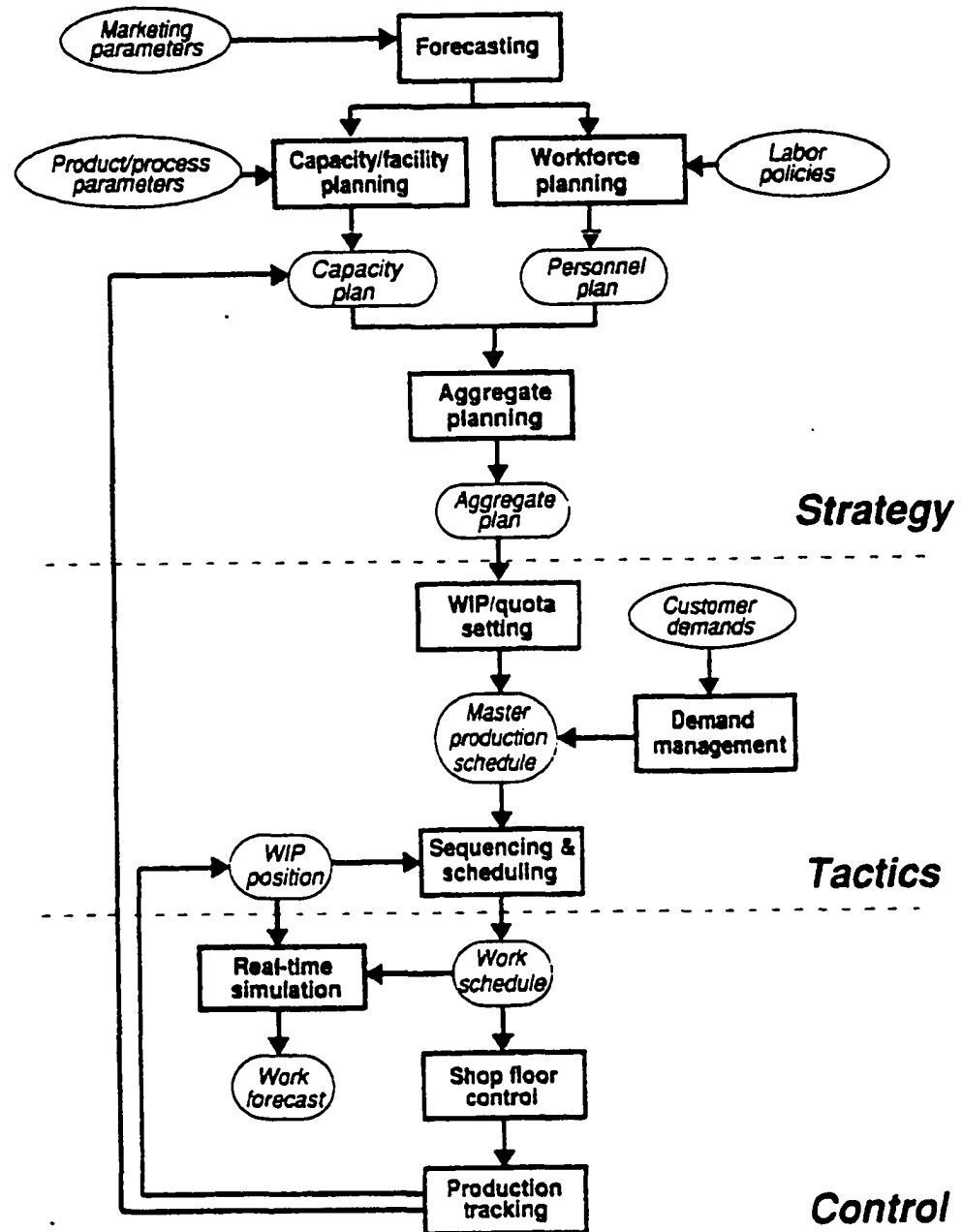


Figure 1. Production planning and control hierarchy for pull system. From Factory Physics: Fundamentals of Manufacturing Management (p. 388), by W. J. Hopp and M. L. Spearman, 1996, Chicago: Irwin. Copyright 1996 by Richard D. Irwin. Adapted by permission.

and now the number of companies who employ MRP is in the hundreds of thousands. More than 100 software companies are engaged in the development of MRP software (Das, 1995).

Even though manufacturers derived many benefits from MRP, some limitations were inherent in the technique. MRP ignored very dynamic elements of the shop-floor environment such as capacity limitations and lead time (Berry, Schmitt, & Vollmann, 1982; Schmitt, Berry, & Vollmann, 1988). Lambrecht and Decaluwe (1988) suggest at the operational level of MRP, many batch sizing and timing decisions are “push” in nature because they are created using fixed planning parameters. Many new modules were added to the original MRP system to minimize these limitations. In the early 1970s a new version of MRP, called manufacturing resource planning (MRP II), was introduced as a more comprehensive, system-wide production planning and control technique. Many new modules were also added in MRP II, but it was still a push system. The problems inherent in MRP stem from the failure to reconcile the differences between pull and push elements in production control systems (Veral, 1995). This underlying condition within the MRP environment has caused many difficulties for a large number of organizations striving to meet ever-changing customer demands.

While Western manufacturers were engaged in developing MRP and MRP II, Japanese organizations were formulating their own production planning and control methods. The just-in-time (JIT) concept emerged from the study of the Japanese automobile industry during the 1970s (Spencer, 1992). JIT is based on the philosophy of eliminating any activities that do not add value. Its goal is to get the material to its next processing station just at the time it is needed (Amerine, Ritchey, Moodie, & Kmec,

1993), in the interests of minimizing the inventories for raw material, work-in-process, and finished goods.

Another production planning and control approach, developed by an Israeli physicist Eli Goldratt in the late 1970s, is the theory of constraints. The concept of theory of constraints has subsequently evolved to become known as constraints management (Spencer & Cox, 1995), and this more contemporary term is used hereafter. Constraints management CM is a set of management principles that help to identify obstacles in achieving the goal of an organization and to establish the changes necessary to remove those obstacles. CM recognizes that the strength of any chain is dependent upon its weakest link, which is what restrains the system's throughput. CM assumes that the goal of manufacturing organizations is to make (more) money now and in the future, and describes three avenues to achieve this goal: (a) increase throughput, (b) reduce inventory, and (c) reduce operating expense.

There seems to be no one right production planning and control system for all manufacturing problems. For some organizations, MRP and MRP II work well; for others JIT or CM are better choices. Deciding which production planning and control system to implement can become time consuming yet difficult to implement for only a "trial period."

These three techniques, MRP, JIT, and CM, are the most commonly used in manufacturing today. However, they are not interchangeable; one system may be appropriate for a particular manufacturing situation but not for another.

Statement of the Problem

Because no single production planning and control (PP&C) technique is suitable for all situations, deciding which system to implement can become time consuming. Yet implementing one for a trial period can be costly and difficult. A technology is needed that can employ various types of PP&C methodologies and generate the optimal production plan.

This research is an extension of a previous unpublished study (Choudhry, 1998), which investigated the PP&C methods being used at a midwestern manufacturing organization involved in the production of agriculture equipment. The current research study identified the constraints inherent in the production planning and control system, and based on these constraints, developed and validated a master production scheduling and sequencing optimization model based on constraints management and utilizing genetic algorithms.

Statement of the Purpose

As noted earlier, production planning and control are among the most critical activities in manufacturing. The expected results of this research will allow manufacturing organizations to maximize the effectiveness of PP&C methods, thereby improving their competitive position in the global economy. To that end, the goal of this research is to develop an optimization model based on constraints management and genetic algorithm to address the constraints in the PP&C methods being used at the factory under study.

This research, based on an analysis of five areas of PP&C (master production scheduling, priority planning, capacity planning, priority control, and capacity control), identifies the constraints in that system, and develops and validates master production scheduling and sequencing optimization model based on constraints management and genetic algorithm. The specific objectives of this research were as follows:

1. Identify the system's constraint.
2. Develop a scheduling and sequencing model to address the identified constraints.
3. Develop and validate the proposed model by simulation using GPSS/H and PROOF, products of the Wolverine Software Corporation located in Annandale, Virginia. GPSS/H is a simulation language, and PROOF is a animation software used within Excel file format.
4. Identify and document improvements attributed to the operational change resulting from the implementation of the optimization model.

Importance of the Research

Which production planning and control technique or methodology is best for a company? This question has puzzled many managers in the past. The three main production planning and control systems are material requirement planning, just-in-time, and constraints management. According to Aggarwal (1985), MRP, JIT, and CM are the three most popular management philosophies in current use. There is no consensus between academicians and practitioners as to which approach is best. According to Spencer (1992), "the three techniques are, to a degree, somewhat mutually exclusive.

There appears to be a need to study the three systems in a framework in which their characteristics and behaviors can be examined in detail” (p. 5). These three techniques are discussed in more detail later in this chapter.

Aggarwal reports in his 1985 article:

During the last 15 years, three important approaches—material requirement planning (MRP), kanban (JIT), and optimized production technology (OPT)—have invaded operations planning and control in quick succession, one after the other. Each new system has challenged old assumptions and ways of doing things....factory managers must decide which approach to adopt to meet current and future needs. Installing any one requires several years to train company personnel and millions of dollars of investment. (p. 99)

Most organizations don't have the resources to try out a method before making a final choice; therefore the managers are left with the grave decision of which one to use.

According to Goldratt and Fox (1986):

The Western manager is challenged to solve a very fundamental problem from this alphabet soup of solutions. To understand each of these new technologies can, by itself, be a time-consuming challenge. Deciding which is best is a formidable task. Figuring out how to put them all together seems beyond our reach. Since we don't have the time, resources or funds to do everything, everywhere, we had better be convinced that we are taking the actions that will leapfrog us back into the race. There is no longer margin for error and no time for risky experiments. (p. 16)

There needs to be a better way of selecting and implementing a production planning system.

This research can assist practitioners who are trying to learn more about the three techniques. The advantages and disadvantages of each management philosophy, as well as problems that might arise during or after implementation, are discussed by examining one company's experiences in an in-depth case study. The developed scheduling model

for optimization, presented after this discussion, could be used in various manufacturing environments.

Research Questions

The previous unpublished study (Choudhry, 1998) focused on the PP&C methods then in use at an engine manufacturing plant (EMP) of a midwestern manufacturer of agricultural equipment. Methods for master production schedule, production priority, and production capacity were explored and documented. Problems in planning and controlling master production schedule, production priority, and production capacity were also identified and documented. The findings of this study are summarized in chapter II.

The current research addresses the following questions. The findings are reported in chapter IV.

1. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the cycle time for the final assembly line and four downstream processes at an engine manufacturing plant (EMP) of a midwestern manufacturer of agricultural equipment (MMAE)?
2. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the queue size for the final assembly line and four downstream processes at EMP?
3. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the utilization of work centers in the final assembly line and four downstream processes at EMP?

4. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the flow rate of engines through the final assembly line and four downstream processes at EMP?

5. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the total output of engines through the final assembly line and four downstream processes at EMP?

Guide (1992) collected and analyzed time in system (cycle time) and work-in-process levels (queue size, inventory levels) to determine if synchronous manufacturing principles produced improved performance in comparison with current production planning and control methodology at a Naval Aviation depot. Taylor (1994) also uses some of these performance measurements to compare the three work-in-process inventory control systems: MRP, JIT, and CM. Performance measurements analyzed by Taylor were: inventory (queue size), throughput (total output of engines), lead time (cycle time), and utilization (utilization of work centers). Manoharan (1997) analyzed total system output (total output of engines), flow time (flow rate of engines), and WIP inventory (queue size) to evaluate the performance of two manufacturing systems, JIT and CM.

Assumptions

The following assumptions were made in pursuit of this research study:

1. That Microsoft Excel is the common production planning tool utilized by various facilities within the total organization.
2. That the production planning and control methods stay the same during the course of this research study at the manufacturing facility under study.

Limitations

This research study was conducted in view of the following limitations:

1. This model was developed in Microsoft Excel and will only work in an Excel environment.
2. For optimization, this research utilizes genetic algorithm-based Evolver software developed by Palisade Inc. This model is limited in application within an Evolver environment.

Definition of Terms

The following terms are defined to clarify their use in the context of this research study.

- Capacity planning: The process of determining the amount of capacity to produce in the future. This process may be performed at an aggregate or product-line level (resource planning), or at the master-scheduling level (rough-cut planning), at the detailed or work-center level (capacity requirements planning). (Cox, Blackstone, & Spencer, 1995, p. 11)
- Capacity control: “The process of measuring production output and comparing it to the capacity plan, determining if the variance exceeds pre-

established limits, and taking corrective actions to get back on plan if the limits are exceeded” (Cox et al., 1995, p. 11).

- **Flow rate:** As defined in the APICS Dictionary, “running rate; the inverse of cycle time” (Cox et al., 1995, p. 33). Flow rate is also defined by number of units per shift or per hour.
- **Genetic algorithm (GA):** Holland (1992) defines genetic algorithm as “a probabilistically guided search method, developed originally in the 1970s as a computer science tool to improve programming structures and performance” (pp. 66-72). Chambers (1991) defines it as a “problem solving method that uses genetics as its model of problem solving” (p. 9).
- **Just-in-time (JIT):** A philosophy of manufacturing based on planned elimination of all waste and continuous improvement of productivity. It encompasses the successful execution of all manufacturing activities required to produce a final product, from design engineering to delivery and including all stages of conversion from raw material onward. The primary elements of zero inventories are to have only the required inventory needed; to improve quality to zero defects; to reduce lead times by reducing setup times, queue lengths, and lot sizes; to incrementally revise the operations themselves; and to accomplish these things at minimum cost. (Cox et al., 1995, p. 42)
- **Material Requirements Planning (MRP):** A set of techniques that use bill of material data, inventory data, and the master production schedule to calculate requirements for materials. It makes recommendations to release replenishment orders for material. Further, because it is time-phased, it makes recommendations to reschedule open orders when due dates are not in phase. Time-phased MRP begins with the items listed on the MPS and determines (a) the quantity of all components and materials required to fabricate those items and (b) the date that the components and materials are required. Time-phased MRP is accomplished by exploding the bill of material, adjusting for inventory quantities on hand or on order, and offsetting the net requirements by the appropriate lead times. (Cox et al., 1995, pp. 49-50)
- **Master production schedule (MPS):** The anticipated build schedule for those items assigned to the master scheduler. The master scheduler maintains this schedule, and in turn, it becomes a set of planning numbers that drives

material requirements planning. It represents what the company plans to produce in specific configurations, quantities, and dates. The master production is not a sales forecast that represents a statement of demand. The master production schedule must take into account the forecast, the production plan, and other important considerations such as backlog, availability of material, availability of capacity, and management policies and goals. (Cox et al., 1995, p. 49)

- Priority control: “The process of communicating start and completion dates to manufacturing departments in order to execute a plan. The dispatch list is the tool used to provide these dates and priorities based on the current plan and status of all open orders” (Cox et al., 1995, p. 63).
- Priority planning: “The function of determining what material is needed and when. Master production scheduling and material requirements planning are elements used for the planning and re-planning process to maintain proper due dates on required materials” (Cox et al., 1995, p. 63).
- Theory of constraints, now known as constraints management (CM): A management philosophy developed by Dr. Eliyahu M. Goldratt that can be viewed as three separate but interrelated areas—logistics, performance measurement, and logical thinking. Logistics include drum-buffer-ropes scheduling, buffer management, and VAT analysis. Performance measurement includes throughput, inventory and operating expense, and the five focusing steps. Thinking process tools are important in identifying the root problem (current reality tree), identifying and expanding win-win solutions (evaporating cloud and future reality tree), and developing implementation plans (prerequisite tree and transition tree). (Cox et al., 1995, p. 85)

CHAPTER II

REVIEW OF LITERATURE

To understand the nature of the ever-changing manufacturing production environment, we need to develop a common set of functions that are not only unique to production itself but can be generalized to all production organizations (Cox & Spencer, 1998). This research is organized around five functions common to production planning and control. These five functions are master production schedule (MPS), priority planning, capacity planning, priority control, and capacity control. According to Cox and Spencer (1998), the origin of the five production planning and control functions is unclear, but the first source of written reference appears in Oliver Wight's 1984 book, Manufacturing Resource Planning (MRP II): Unlocking American Productivity Potential.

The purpose of production planning and control (PP&C) is to plan and control the production process with regard to time and quantity. According to Corsten and May (1996, p. 69), for the PP&C function, the following four questions have to be answered:

- Which products and parts are to be produced and what is their quantity level?
- Which parts are to be delivered by the supplier in what quantity and when?
- Which capacity utilization results from the master production schedule and how can a capacity adjustment take place?
- In what sequence are the production orders to be worked off and at which workstation?

This chapter provides a review and analysis of the literature related to material requirements planning (MRP), just-in-time (JIT), constraints management (CM), and genetic algorithms (GA) and discusses how each relates to five functions common to production management.

Material Requirements Planning

Evolution

MRP is a tool used for material and priority planning. The basic function of an MRP system is to plan for material requirements based on planned production levels.

Wight (1984, p. 47) suggests that MRP tries to answer the following fundamental manufacturing questions:

- What are we going to manufacture?
- What does it take to make it?
- What do we have in our inventory?
- What do we have to acquire?

These fundamental questions, used throughout the manufacturing industry, serve to generate a list of parts needed for the next month in order to avoid part shortages. From this informal system, a powerful one has evolved called material requirements planning. “MRP is simply the logic of the informal system – the shortage list – developed into a formal scheduling system” (Wight, 1984, p. 47).

Although MRP has been in practice informally for many decades in the manufacturing industry, the first published work that formally discussed MRP was Material Requirements Planning, written by Joseph Orlicky in 1975. In his book he states:

In some rudimentary form, MRP has no doubt existed as long as manufacturing. It has been evolving gradually, moving onto successively higher plateaus with every enhancement in data processing capability. MRP had its origin on the firing line of a plant. It has been painstakingly developed into its present stage of relative perfection by practicing inventory managers and inventory planners. (p. 38)

Eventually MRP developed into an overall system called closed loop MRP.

Figure 2, is a schema of a closed loop MRP system. The production plan establishes production volumes for product families. The master schedule takes the production plan in units for product families and breaks it down into component parts. Material requirements planning looks at the parts in inventory and determines what component parts are needed to accomplish the production plan. The capacity requirements plan determines the standard hour requirements for the production plan. Once planning for material and capacity requirements is completed, it must be determined if the plans are realistic. If they are realistic, then both material and capacity plans need to be monitored to ensure that the plans are being executed.

Despite the formalization of the MRP system, its limitations were still confining to the organization's ability to perform better production planning and control functions. Finance, a big piece of the puzzle, was still missing in the closed loop MRP; financial systems were not tied to the closed loop MRP. In the 1970s, manufacturing resource planning (MRP II) evolved out of the closed loop MRP, tying the financial system to the operating system. As Wight (1984, p. 49) noted, "tying the financial and the operating systems together was the big step from closed loop MRP to MRP II." Figure 3 is a schema of an MRP II system.

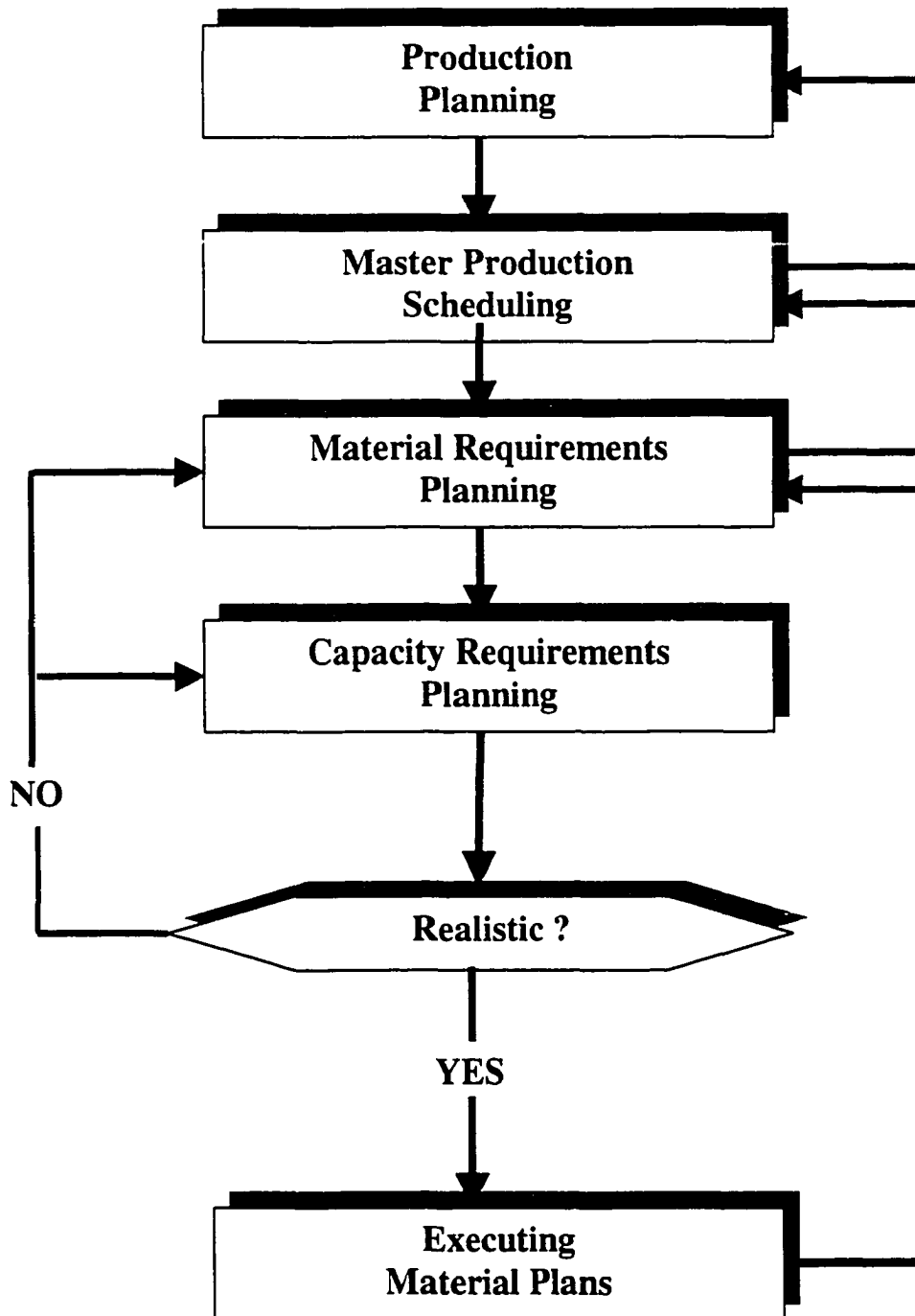


Figure 2. Closed loop MRP.

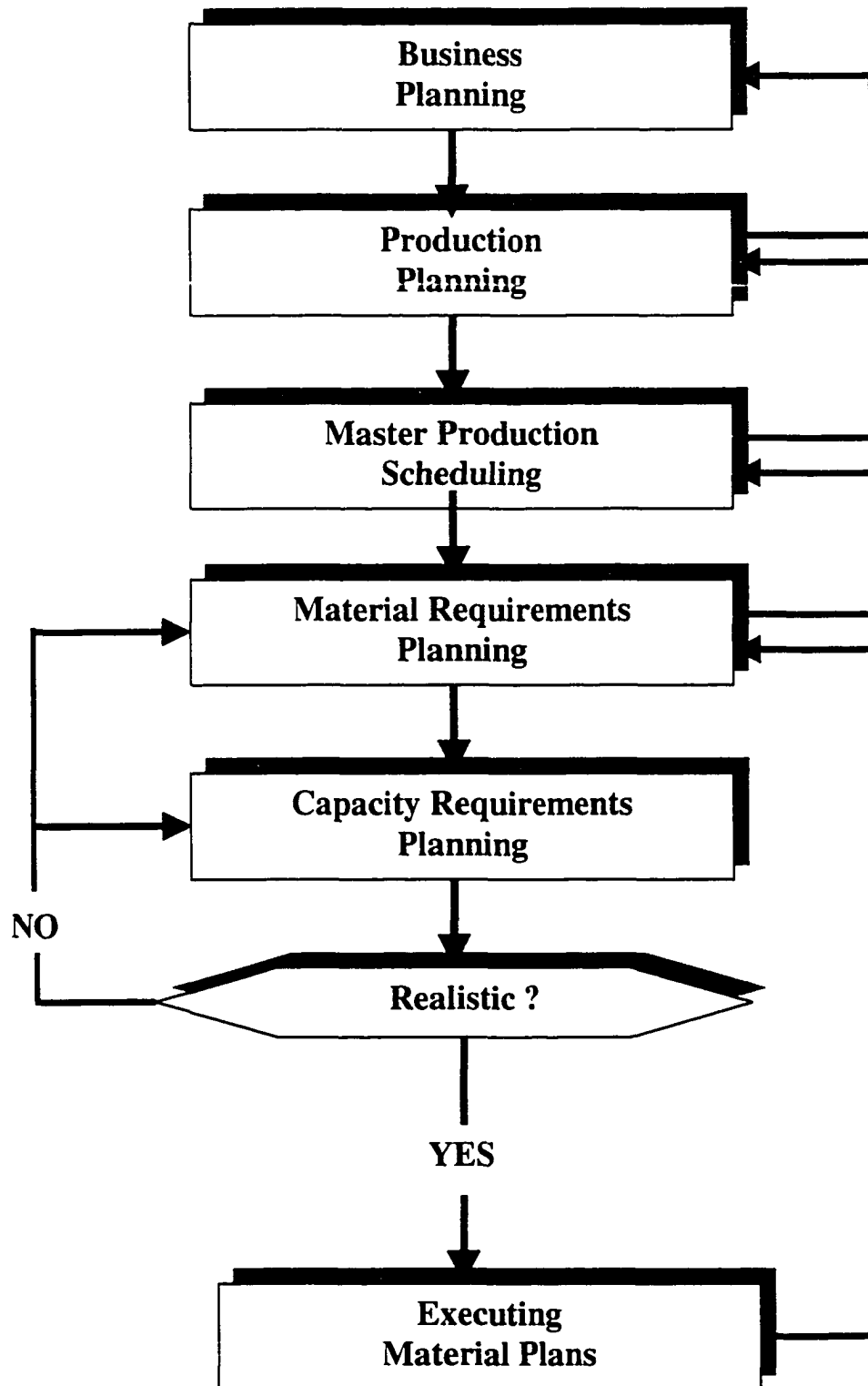


Figure 3. Manufacturing resource planning (MRP II).

Functionality

MRP deals with end-items (finished products) and the component parts (lower level items) that make up the end items. The bill of material (BOM) connects the end items with the lower level items. Figure 4 illustrates a typical bill of material for the end-item X. To facilitate the MRP processing, each component part in the bill of material is assigned a low level code (LLC). The LLC indicates the lowest level for which a part is used in a bill of material. In the following figure, the end item X has an LLC of 0. The component parts 10 and 20 have an LLC of 1, parts 30, 40, and 50 have an LLC of 2; and part 60 and 70 an LLC of 3.

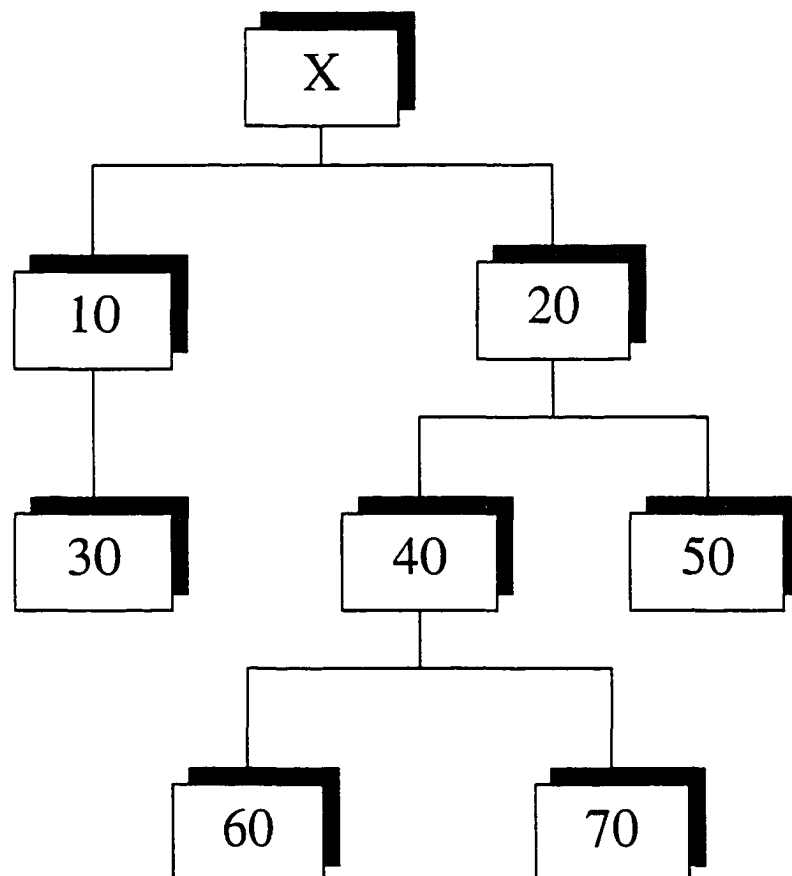


Figure 4. A typical bill of material (BOM).

Table 1 illustrates the material requirements plan for Part A. The gross requirements for Part A come from the production plan. Schedule receipts are the orders that are already in production. To calculate when an order needs to be placed, gross requirements are subtracted from the available balance and schedule receipts are added to it. In Table 1, for example, the on-hand balance is 400 units, the gross requirements for Week 1 are 120 units, so the projected on-hand balance for Week 1 is 280 units. The first uncovered demand in this example is in week 8 for 60 units. The lead time for Part A is 4 weeks; therefore, the order needs to be placed in Week 4 to cover the demand of 60 units in Week 8. The example above illustrates a simple MRP procedure. Because of space constraints, full discussion on the components of MRP procedure--netting, lotsizing, offsetting, and BOM exploding--is not covered in this research. For a full discussion of MRP, see Wight (1984) or Hopp and Spearman (1996).

Table 1

Time-Phased MRP Requirements Processing

Part A	Week								
	1	2	3	4	5	6	7	8	
Gross requirements	120	120	0	0	120	150	0	150	
Schedule receipts			200						
Projected available balance	400	280	160	360	360	240	90	90	-60
Planned order releases									

Advantages and Disadvantages

In the late 1960s and early 1970s, with the rapid advancement in computer technology, MRP took over the manufacturing industry. “Starting in the sixties and on into the seventies, the basic elements of an integrated production planning and control system known as MRP, were established” (Taylor, 1994, p. 8). Initially, computer-based MRP was thought to be so powerful that it made the classical methods of inventory management obsolete. One of the major advantages of the MRP system is its adaptability to dynamic changes and the ability to know what is required several periods in advance (Nagendra, 1995).

Many success stories are reported in the literature about MRP. According to Aggarwal (1985). MRP has indeed helped many organizations in the effort to reduce inventories and streamline scheduling. In discussing the advantages of MRP, Orlicky (1975) notes,

this subject, broadly viewed, marks the coming of age of the field of production and inventory control, and a new way of life in the management of manufacturing business. In the area of manufacturing inventory management the most successful innovations are embodied in what has become known as the material requirements planning (MRP) system. (p. 4)

Umble and Srikanth (1990) state, “MRP became a crusade that helped to shift the emphasis away from the traditional ‘just-in-case’ inventory mentality and toward a manufacturing control system based on actual need dates and quantities” (p. 8).

Manufacturing organizations around the world invested billions of dollars and human resources in the implementation of MRP. In the United States alone, by 1989, sales of MRP software and support exceeded one billion dollars (Hopp & Spearman, 1996), but not all of the outcomes were successful. Taylor (1994), in summarizing the

findings of Anderson, Schroeder, Tupy, and White (1982), reports that a great number of the firms that attempted MRP implementation were not always satisfied. According to Rice and Yoshikawa (1982), the weakest MRP area is in capacity planning. Nagendra (1995) also reports the inability of MRP to perform comprehensive capacity planning. Ashton, Johnson, and Cook (1990) likewise note part-shortage problems that disrupt operations due to MRP. Cox and Clark (1984) report other technical problems such as inventory management and infinite capacity assumption.

MRP has to be constantly modified to cope with the changing manufacturing environment. Over the years, many modules have been added to MRP giving it the more deserved name of manufacturing resource planning (MRP II). With MRP II, manufacturing interacts with other functions of the organization, such as accounting, finance, and human resource planning.

MRP has been an effective tool for several decades for many organizations, even with its built-in limitations. With the changing business environment, production planning and control methods also need to be changed. MRP-based production planning and control solutions are appropriate for organizations with repetitive manufacturing. However, the advantages of MRP for high-mix, low-volume manufacturing organizations are very limited.

Just-in-Time

Evolution

Even though the elements of just-in-time (JIT) has been around since the 1900s, the American manufacturing industry did not start paying serious attention to it until the late 1970s. “The first records of the JIT management philosophy stem from the efforts of Henry Ford and his assembly line operations” (Taylor 1994, p. 13). JIT received much attention in the Western manufacturing world during the early 1980s when a large number of books and articles were written on this subject. Between 1970 and 1991, more than 860 articles about the just-in-time philosophy were published in professional journals (Golhar & Stamm, 1991). The JIT system has become extremely popular in recent years and has been implemented in many kinds of companies around the world.

The just-in-time philosophy is based on the work of Taiichi Ohno of the Toyota Motor Company (Sugimoro, 1977). In the early 1980s, many American manufacturers regarded JIT as a Japanese manufacturing philosophy suited only for Japanese organizations. Initially, most Westerners viewed it as an inventory reduction system, beneficial only for large repetitive manufacturers (White, 1993). As more and more Western organizations successfully applied JIT principles, its benefits became evident for a wide range of manufacturing environments (Hall, 1983). U.S. managers also became more knowledgeable of JIT and described it as a holistic management approach consisting of various practices that contribute to the elimination of waste and a philosophy of continuous improvement of a manufacturing system (Hall, 1987; Schonberger, 1986; White, 1993). Today, many American manufacturing companies regard JIT as vital to their survival (Hobbs, 1997).

Functionality

The JIT philosophy is based on the concept of the elimination of waste in the system. JIT's purpose is to minimize in-process and final inventories (Hall, 1983; Monden, 1983). Early academic research focused on utilizing JIT systems within the internal manufacturing environment (Spencer, Daugherty, & Rogers, 1996), but this approach to JIT is evolving toward a broader concept--a total business philosophy. According to Ramasesh (1992), "JIT represents an integrative philosophy of operations which encompasses several functional systems both within the firm and outside of the firm" (p. 44).

Hall (1983), Sage (1984), and Heard (1984) all agree that the JIT philosophy is based on the pull method of production called "kanban." According to the APICS Dictionary (Cox et al., 1995), kanban is a "method of Just-In-Time production that uses standard containers or lot sizes with a single card attached to each. It is a pull system in which work centers signal with a card that they wish to withdraw parts from a feeding operation supplier" (p. 42). The APICS Dictionary defines pull system as "the production of items only as demanded for use, or to replace those taken for use. In material control, the withdrawal of inventory as demanded by the using operations. Material is not issued until a signal comes from the user" (p. 68).

Advantages and Disadvantages

One of the main advantages of JIT is its emphasis on shop-floor control rather than inventory control (Ohno, 1982). Im and Lee (1989) and Burnham (1987) report many benefits derived from the successful implementation of JIT, including improvements in production planning, improvements in MPS and MRP, and reduction in

inventory. A study conducted by Gilbert (1990), of 250 American manufacturing organizations, found significant reduction in the investment of inventory associated with the implementation of JIT. Other benefits reported by researchers included reduced throughput time, improved labor productivity, improved quality, decreased inventory levels, and reduction in space required for operations (Celley, Clegg, Smith, & Vonderembase, 1986; Golhar, Stamm, & Smith, 1990; Hay, 1988).

Reducing inventory levels toward zero requires eliminating variability within a system. It is very difficult, if not impossible, to eliminate all the variability from a complex manufacturing system. To tackle this problem, managers on the shop floor would have to increase buffer size, which, in turn, would increase the work-in-process inventory. However, this goes against the JIT philosophy. According to Rice and Yoshikawa (1982), the weakest area in JIT is master production planning.

Another drawback is the time required for implementing JIT (Schonberger, 1986). For most Western organizations, the JIT implementation process spans many tedious years. Umble and Srikanth (1990) report four major limitations inherent in JIT and kanban:

First, the number of processes to which JIT logistical systems such as kanban may be successfully applied is limited. Second, the effects of disruptions to the product flow under the kanban system can be disastrous to current throughput. Third, the implementation period required for JIT/kanban systems are often lengthy and difficult. Fourth, the process of continuous improvement inherent in the JIT approach is system wide and therefore does not focus on the critical constraints, where the greatest gain is possible. (p. 125)

Overall, the just-in-time approach to PP&C is based on the philosophy of elimination of all waste in the system. Organizations around the world have been implementing JIT for the last few decades and many of them have reported numerous benefits (Bartezzaghi & Turco, 1989; Burnham, 1987; Crawford, Blackstone, & Cox, 1988; Im & Lee, 1989). Even though there are some drawbacks to implementing JIT, organizations can gain competitive advantage once it is accurately implemented.

Constraints Management

Evolution

Originally known as theory of constraints, constraints management was developed at about the same time as the just-in-time philosophy started to make an impact on Western organizations. Goldratt developed an optimized production timetable (OPT) to assist a friend in the production and assembly of prefabricated chicken coops (Jayson, 1987). The OPT schedule enabled the producer to triple his production without increasing any human resources (Taylor, 1994). The logic behind the OPT software was not revealed because of proprietary reasons. Contrary to MRP philosophy, OPT assumes that production capacity is finite, restricted by the bottleneck operation (Dugdale & Jones, 1995). According to Nahmias (1989), OPT follows these nine principles:

1. Balance the flow, not the capacity.
2. The level of utilization of the non-bottleneck resource is determined not by its own potential, but by some other constraints in the system.
3. Utilization and activation of a resource are not synonymous.
4. One hour lost at the bottleneck operation is an hour lost for the total system.
5. An hour saved at the bottleneck is a mirage.
6. Bottleneck operations govern both throughput and inventory in the system.
7. The transfer batch might not, and many times should not, be equal to the process batch.

8. The process batch should be variable, not fixed.
9. Schedules should be established by looking at all of the constraints simultaneously. Lead times are the result of a schedule and cannot be predetermined. (p. 13)

According to Taylor (1994), constraints management was originally known as OPT, when it was first formulated in 1979. In 1982, the name was changed to optimized production technology, in 1984 to synchronous manufacturing, 1987 it became theory of constraints, and recently it became constraints management.

CM was originally regarded as a management technique suitable for the shop floor, but eventually it was used to manage and solve problems that extended far beyond that (Hobbs, 1997). CM applies the methods of science to the general problem of management (McMullen, 1997). Rack and Rack (1993) define it as follows:

a thinking process used to analyze problems, create or choose appropriate solutions and get buy-in to achieve successful results. Although it is demonstrably very powerful, it is not difficult to understand. Because the process utilizes how man was designed to think, it works for almost everyone interested in tapping into his/her own abilities. The appropriate use of the thinking process significantly impacts the goal and is intrinsically rewarding to the one(s) using it. (p. 3)

Functionality

The main focus of the CM approach is to concentrate effort on the system's constraint(s). Goldratt (1990a) emphasized this point by addressing the need of focusing on a small portion of the system at a time. He went on to say, "spreading attention equally to all portions of the area means no concentration whatsoever, no focusing" (p. 58).

CM methodology is based on five focusing steps:

1. Identify the system constraint(s).

2. Decide how to exploit the system's constraint(s).
3. Subordinate all else to the constraint(s) of the system.
4. Elevate the system's constraint(s).
5. If, in step 4, the constraint has been broken, go back to step 1, do not let inertia become the system's new constraint.

A constraint is anything that limits the organization's achievement of its goal. If the scarce resources of an organization can be used to elevate the system's constraint(s), the organization's goal, which is to make money now and in the future, can be achieved successfully. Goldratt (1994) suggests that the five focusing steps follow a framework based on the following questions:

1. What to change (finding the core problem)?
2. What to change to (devise simple, practical solutions)?
3. How to cause the change (cause others to invent or discover the ideas)?

"The three elements of change are techniques for verbalizing our intuition so we can check its soundness and communicate it clearly to others" (Taylor, 1994, p. 21).

Goldratt has developed approaches to deal with problems using the Socratic method, rather than the more traditional Aristotelian way. According to Taylor (1994), Goldratt developed the following techniques to deal with change:

1. Effect-cause-effect: A technique for finding the core problem. This method allows for verbalization of intuition and its cause.
2. Evaporating clouds: A technique for stating a problem as a conflict. This allows for the conflict assumptions to be challenged. Faulty assumptions allow the problem to disappear.

3. Socratic method: This allows for others to invent or discover answers themselves and conceive ownership in them.

According to Woepffel (1991), all of the above techniques have proven to be very effective for increasing one's ability to verbalize intuitively. These techniques have been used in the manufacturing industry to develop and implement effective procedures.

Constraints management also addresses the issue of inventory in process with drum-buffer-rope (DBR) technique, defined by the APICS Dictionary as "the generalized technique used to manage resources to maximize throughput. The drum is the rate or pace of production set by the system's constraint. The buffers establish the protection against uncertainty so that the system can maximize throughput. The rope is a communication process from the constraint to the gating operation that checks or limits material released into the system to support the constraint" (Cox et al., 1995, p. 25).

CM emphasizes the need of inventory buffer in front of the constraint operation. DBR concentrates on managing the flow of products to meet the bottleneck constraint's needs. The buffer inventory in front of the constraint protects the constraint from stockouts due to upstream process interruptions. Since the bottleneck acts as a valve controlling the system's throughput, managing the bottleneck's throughput manages the system's throughput. To maximize the system's throughput, the bottleneck must utilize all of its available capacity.

The three commonly used PP&C methods discussed MRP, JIT, and CM, all offer some advantages for organizations engaged in various types of manufacturing activities. To choose any one of these three PP&C methods and apply it for all types of manufacturing environments would not be an easy task, especially for managers with

little exposure to academic research. The present research would help managers in repetitive industry to compare and evaluate the three popular PP&C approaches and choose the one that would work best for their manufacturing environment. The next section discusses genetic algorithms, the history and functionality.

Genetic Algorithms

Genetic algorithms are becoming a widely used tool for difficult optimization problems (Bennett, Ferris, & Ioannidis, 1991; Goldberg, 1989; Grefenstette, 1987). In recent years, GA have received remarkable attention all over the world, a fact reflected in the amount of literature published on this topic in the last few years (Back, 1996). Researchers have explored the possibilities of GA applications in various fields, including game theory, process planning, classifier systems, machine learning, and function optimization (Crossley, 1995). The use of GA for scheduling in manufacturing has also been explored by many researchers (Bagchi, Uckun, Miyabe, & Kawamura, 1991; Davis, 1985, 1991; Nissen, 1993; Whitley, Starkweather, & Fuquay, 1989).

History

The history of genetic algorithms goes back more than four decades (Back, Hammel, & Schwefel, 1997). Bremermann (1962, 1967, 1968, 1973), Fraser (1957, 1962, 1968), Reed, Toombs, and Barricelli, (1967), and Holland (1969, 1975) report early research related to genetic algorithms. Genetic algorithms in the present form were developed by Dr. John Holland, computer scientist and psychologist at the University of Michigan. Dr. Holland, along with his students and colleagues during the 1960s and 1970s, developed the research area of artificial intelligence (AI), now known as genetic

algorithms. His book Adaptation in Natural and Artificial Systems (1975) is considered to be the starting point of almost all known applications and implementations of genetic algorithms (Back, 1996).

Research in the field of artificial intelligence is based on the idea that “evolution could be used as an optimization tool for engineering problems” (Mitchell, 1996, p. 5). The common theme in almost all evolutionary systems is the belief that it is possible to evolve a population of candidate solutions to a given problem, using operators inspired by natural genetic variation and natural selection (Chambers, 1991). Many researchers have expanded on Holland's research on genetic algorithms since 1975.

The growing complexity of scheduling and sequencing problems in manufacturing has led many researchers to experiment with genetic algorithms as an optimization tool. Genetic algorithms have been used to solve scheduling problems with increasing frequency since the early 1980s. Various researchers (Bagchi et al., 1991; Cleveland & Smith, 1989; Davis, 1985; Nakano & Yamada, 1991; Syswerda, 1991; Whitley et al., 1989) have reported experimentation with genetic algorithms to solve scheduling problems.

Functionality

The genetic algorithm is a probabilistically guided search method, “developed originally in the 1970’s as a computer science tool to improve programming structures and performance” (Holland, 1992, p. 66). Chambers (1991) defines GA as a “problem solving method that uses genetics as its model of problem solving” (p. 13). GA are search techniques based on the mechanics of natural selection and genetics, and they involve a structured yet randomized information exchange resulting in the survival of the

fittest amongst a population of string structures. GA operates on a population of structures that are fixed-length strings representing all possible solutions to a problem domain (Mars, Chen, & Nambiar, 1996). Genetic algorithms work by mimicking the “survival of the fittest” patterns of natural selection and reproduction similar to those in biological populations (Crossley, 1995).

Davis (1991) identifies four features of the evolution process that are the bases of genetic algorithms. These four features are as follows:

1. Evolution is a process that operates on chromosomes rather than on living beings they encode.
2. Natural selection is the link between chromosomes and the performance of their decoded structures. Process of natural selection causes those chromosomes that encode successful structures to reproduce more often than those that do not.
3. The process of reproduction is the point at which evolution takes place. Mutation may cause the chromosomes of biological children to be different from those of their biological parents, and recombination processes may create quite different chromosomes in the children by combining material from the chromosomes of two parents.
4. Biological evolution has no memory. Whatever it knows about producing individuals that will function well in their environment is contained in the gene pool the set of chromosomes carried by the current individuals--and in the structure of the chromosome decoders. (pp. 2-3)

The features described above allow genetic algorithms to solve complex problems without having any knowledge of the problem or the search space. Michalewicz (1994)

identifies five components that must be contained by genetic algorithms:

1. A genetic representation for potential solutions to the problem
2. A way to create an initial population of potential solutions
3. An evaluation function that plays the role of the environment, rating solutions in terms of their fitness
4. Genetic operators that alter the composition of children
5. Values for various parameters that the genetic algorithm uses. (p. 6)

The three basic operators that are found in every genetic algorithm are (a) reproduction, (b) crossover, and (c) mutation.

Reproduction. The reproduction operator permits individual strings to be copied in the next generation. The string's chance to be copied to the next generation depends on its fitness value calculated from a fitness function. The reproduction operator chooses strings that were placed in the waiting pool for each generation. The next generation is based on this pool.

Table 2 demonstrates that string 01100 is the best fit. This string should be selected for reproduction approximately 66% of the time. String 01101 is the second best fit and should be selected 21% of the time. And string 10101, the weakest, should be selected only 13% of the time.

Table 2

Fitness Test

String	Fitness value	%
01101	8	21
10101	5	13
01100	25	66

Crossover. After the mating pool is created through the selection operator, the next genetic algorithm operation is called crossover. In biological terms, crossover

occurs when two parents exchange parts of their corresponding chromosomes to produce an offspring. Figure 5 illustrates the crossover operation within genetic algorithms.

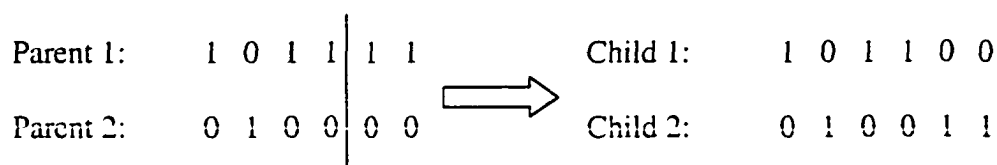


Figure 5. Crossover operation.

Each child in the example receives four of the six parts of each parent's genetic material. In a genetic algorithms search, crossover is performed until a new population is created, and then the cycle starts again with a new selection. According to Davis (1991), crossover is an extremely important component of a genetic algorithm. Use of the crossover operator distinguishes the genetic algorithm from all other optimization algorithms.

Mutation. The mutation operator brings a certain amount of randomness to the genetic search. Mutation can help the genetic search to find solutions that crossover alone might not encounter. Selection and crossover operations in a genetic search can generate a large quantity of different strings. However, depending on the initial population of the search, the resulting strings may not have enough variety. The mutation operator can offset this shortcoming. When a genetic algorithm performs a mutation, it randomly changes the element value to a new one. If, to use the example in Figure 5, Position 5 of the Parent 1 string were mutated, the resulting string would be 101101. In the binary strings, 0s are changed to 1s and 1s are changed to 0s.

There are significant differences between genetic algorithms and other optimization tools. Crossley (1995) identifies four major differences between calculus-based optimization and genetic algorithms as follows:

1. GA works with a coding of the design variables and parameters in the problem, rather than with the actual parameters themselves.
2. GA makes use of a population-type search. Many different points are evaluated during each iteration, instead of moving from one point to the next.
3. GA needs only a fitness or objective function value. No derivatives or gradients are necessary.
4. GA uses probabilistic transition rules to find new points for exploration rather than using deterministic rules based on gradient information to find new design points. (p. 24)

One of the most significant advantages of using genetic algorithms is flexibility and adaptability to the problem at hand (Back et al., 1997).

Foundational Study for Current Research

In an earlier study, which provided the basis for the present research, Choudhry (1998) investigated the current status of production planning and control methods at an engine manufacturing plant (EMP) of a midwestern manufacturer of agricultural equipment, hereafter referred to as MMAE. In that study, the writer focused on 11 questions dealing with current methods and problem areas. The results are reported under the following listing of those 11 research questions.

Current Production Planning and Control Methods

1. What are the production planning and control (MRP, JIT, CM) methods currently being used at EMP?

Production planning is the primary responsibility of the logistics manager, who reports directly to the plant manager. The seven employees in the production planning

department include a supervisor of production planning and an employee who performs the daily final assembly scheduling (line-up). Three employees are involved in the distribution of the daily schedule to the shop floor. One employee is responsible for the inventory accuracy, and the seventh employee is in charge of fulfilling service store requirements. The purchasing department orders components based on the master schedule in the MRP and is also responsible for component sourcing and price negotiations.

The key performance measurements for the logistics department were not clear because at the time of this study, the department had only been in existence for a few months. The key performance measurements for the production planning supervisor and the department are (a) due date performance as a percentage of total order shipped (for the three months prior to this study, this figure was close to 100%); (b) customer acceptance; and (c) a target inventory as a percentage of sales.

In late 1979 EMP developed and implemented an in-house material requirements planning system, which has undergone significant modifications throughout the following years. The system continues to be modified at the present time as the need arises. MMAE is in the process of implementing an enterprise resource planning (ERP) system by SAP throughout its plants around the world. At its midwestern locations, this implementation will start in the middle of 2000 and will be fully implemented in about two years.

Accuracy of the bill of material (BOM) is around 96%, and part routing accuracy is 95%. Changes are made daily to the bills of material. Communication seems to be the main problem between the specification and engineering departments. Routings are not

changed frequently, two per part for new engines and about 5% for the repetitive builds. For the inventory management, an ABC analysis was performed, and EMP uses six categories--A, B, C, D, E, and F. A cycle counting system is in operation, which is a physical count of inventory that is conducted every quarter; once a year, auditors from the company corporate office count the inventory. Inventory turns are about 13 per year. Inventory breakdown at EMP is as follows: raw, about 34.4%; WIP, 57.1%; and finished goods, about 8.5%.

The current MRP system is regenerated on a weekly basis and is using weekly buckets for requirements. Daily net changes for the master production schedule and inventory netting are performed. Even though the logistics manager is pleased with the accuracy of the MRP reports, he considers them very time insensitive. In the new global economy, customer requirements are being changed regularly without regard to weekly buckets.

EMP has been relying on the MRP system for production planning and control activities since its implementation in 1979. Some aspects of just-in-time (kanban) are also being implemented in a few subassembly work centers. Constraints management is not being practiced formally, but management does consider the two bottleneck operations in the plant when production planning activities are undertaken. The management at EMP is trying to minimize reliance on MRP. Many new projects are under way to develop Excel-based tools for PP&C.

2. What methods are currently being employed to develop the master production schedule at EMP?

The process of master scheduling at EMP begins when an order is received from the customer with the required ship date. For interfactory customers, the common worldwide interfactory system (CWIS) is used; for various original equipment manufacturers (OEM), the complete goods order management and reporting system (COMAR) is utilized. The difference between the two types of orders is that options are attached to OEM orders. Engines built for each OEM customer are unique, whereas engines built for interfactory customers are build via repetitive manufacturing methods.

The master scheduler enters these orders into the master schedule system and accounts for the number of days it takes to build an engine (lead-time). After the leveling activity is completed, information is passed on to a planner to perform the line-up. The same information is entered into the system's material requirements planning (MRP), which in turn passes it to CPS (common purchasing system), so the purchasing department is informed when to procure the parts.

MRP generates the shop production schedule (SPS) for the machining department, informing them when to start production for these parts based on the parameters maintained in MRP (lead-time, scrap %, order policy, etc.) by the planners in the machining department. The planners in the machining department report to the machining business unit leader. MRP information is driven by the line-up for 20 days and the master schedule beyond the 20-day time frame.

If a shortage is foreseen for any parts, the critical shortage report comes into play. When purchasing cannot procure a part or machining cannot manufacture one, that information is generated on the critical shortage report and passed on to a scheduler.

Most of the computer systems used at EMP are “legacy” systems. They were called common systems (MRP, COMAR, etc.) because they were supposed to work in a uniform manner for all MMAE units around the world. If any changes were proposed in the system, those changes had to be approved by a committee consisting of members from each plant. If the changes were approved by the committee, each unit incorporated them into the system. However, in the last few years, this situation has changed. Now each unit makes changes independently. As a result, MMAE does not pay headquarters for system support, and the company is moving toward implementation of an enterprise resource planning system by SAP.

When there are changes to be made in the engineering specification of a particular engine, the product engineering center (PEC) provides this information to the head of the specification department. This department works through the approved specifications and loads them in the system along with the effectivity dates. The information is routed to appropriate departments affected by the changes. If the changes have to do with options for OEM customers, that information also needs to be routed through the marketing department, so they can forecast for parts or options.

Of the engines manufactured at EMP, 85% are sold to interfactory customers, and the rest are sold to OEM customers. These engines are used in tractors, combines, and other agriculture and construction equipment for the interfactory customers. Interactions

with dealers are then minimal; the marketing department, specifically the OEM representative, interacts with OEM dealers and customers.

3. What methods are currently being employed to plan production priority at EMP?

The 85% of engines produced for interfactory customers are manufactured via repetitive build, whereas the rest of the engines, for OEM customers are customized with many options for each model. The MRP process of explosion and netting lose this identity. Production orders for the shop floor are created by the MRP based on the lead times of each component.

Even though MRP creates shop orders for a majority of the manufactured components, EMP has been in the process of establishing kanbans, in this case a replenishment cycle of about two to three days for 80% of the components. Priority planning at EMP is accomplished through the use of the MRP trigger system for purchased components. Kanban is used to plan priorities for 50% of in-house manufactured parts. Management at EMP has initiated projects in the last two months to include all in-house parts for kanban delivery.

The primary priority planning document used for the final assembly line is the report generated manually by the production scheduler titled "daily line-up". This report lists all engines to be built in the sequence that day, based on customer ship orders. The report is distributed to 60 work centers on the final assembly and subassembly lines. The new logistics manager has initiated many projects to streamline the master scheduling and daily line-up process at EMP. In the new PP&C process, distribution of daily line-up sheets will be either eliminated or minimized. EMP is in the process of implementing kanbans for the majority of the subassembly stations.

4. What methods are currently being employed to plan production capacity at EMP?

Capacity is defined at EMP by the number of engines built per day. Long-term capacity planning occurs during the next fiscal year's production planning process. Capacity has never been a major issue at EMP. This facility was built to produce 300 engines per day, but demand for engines has never exceeded that number. Production can be easily increased, if the forecast indicates a growth in sales.

EMP operates on two shifts for the final assembly on a five-day-per-week basis; however, it is possible to drop to one shift if the demand declines for a few weeks. Because of the current union contract, MMAE's four local plants cannot lay off any hourly employees. When production is cut, shop floor employees are put in a "resource pool" which is comprised of extra employees and used for rapid continuous improvement (RCI) projects.

Short-term capacity planning for the assembly areas is accomplished through the use of a final assembly schedule for the following 20 days and a computer program (Workforce & Machine Load) that converts units into the workforce required. Adjustments to the final assembly schedule are rarely made at the final assembly line due to the unavailability of operators.

The test and paint departments are the current constraints at EMP; many times, test and paint problems cause delays in customer shipments. The test and paint departments run on a three-shift, five days/week basis. Only eight test cells must handle about 171 engines per day. Capacity for the paint department is 30 engines per shift, 90 engines per day. About 60% of the engines manufactured at EMP require paint. Capacity is adjusted by adding overtime shifts on Saturdays and Sundays.

5. What methods are currently being employed to control production priority at EMP?

In the final assembly and subassembly areas, priority is controlled by the daily line-up schedule. Once the daily line-up is created for the following three days, unique serial numbers are assigned to each engine, and serial plates and serial tags are generated. If there is a change in the build schedule, the master scheduler has to make manual changes on the distributed line-up sheets. There are about 10 changes per week in the final assembly line-up.

Order changes are established through negotiations between the EMP management and its interfactory and OEM customers. Both types of customers can change their orders in the CWIS beyond 90 days without approval from the master scheduler. If changes are made within 90 days, customers must request the changes through CWIS, which generates an "action file." The changes in the action file have to be reviewed and accepted by the master scheduler. If EMP cannot fulfill the requirements, the master scheduler proposes a date when those requirements can be fulfilled. This interaction with the customer continues until both parties agree on a mutually satisfactory date. Changes in customer requirements affect 13% of the total sales at EMP.

6. What methods are currently being employed to control production capacity at EMP?

Department supervisors control capacity at the two bottleneck areas, test and trim and paint, on a daily basis along with the assembly general supervisor. Overtime is scheduled as required if production exceeds capacity. Assembly supervisors request overtime authorization from the plant manager. The test and trim department schedules

overtime on a regular basis to avoid any delays in shipping. The new logistics manager has initiated a project to streamline these departments.

Identification of the current methods of production planning and control practiced at EMP was not an easy task. Interviewees often could not describe the current process in place. The researcher had to illustrate and explain the majority of the production planning and control terminology to extract information. In the next section the problems inherent in the current production planning and control system at EMP are presented.

Problem Areas by Production Function

1. What problems are currently being encountered in master production scheduling at EMP?

The first area of concern for management regarding the master production schedule is the reliance on legacy computer systems, CWIS and COMAR. These systems are very labor intensive, requiring too much duplication of work by the master scheduler and the schedulers. A second area of concern is the limitations of the MRP system, which is unable to support changes during the week. Changes in the master production schedule only become apparent after the weekend report is generated by the system. Another concern is the development of the MPS by the master scheduler. According to the master scheduler, no formal procedure is in place for the development of the MPS for the following fiscal year. The master scheduler uses a rolling 12 months for the development of the MPS instead of using a fiscal year.

2. What problems are currently being encountered in planning production priority at EMP?

The first area of concern is the limitations of the MRP system and the execution of the master production schedule. MRP is limited to weekly buckets, which create

unseen changes made during the week by the master scheduler. Management has implemented controlled delivery for a few subassembly work centers to establish priorities. A final assembly schedule is prepared from the master production schedule and is also used to identify the priorities in machining. The final assembly schedule, which is in weekly buckets, is also used by the scheduler to line-up engines for the next 20 days. The line-up schedule is used to generate the part shortage list, "critical shortage day-one." Another area of concern is the marketing department's ability to alter relative production priorities as required for OEM customers. Reprioritization in the final assembly schedule also creates problems for the machining department. A third problem is the long lead-times for three critical parts: turbo, injection pump, and pistons. Lead-time for these parts averages about 120 days. Long lead-times limit the flexibility of MMAE to respond to customer changes in requirements.

3. What problems are currently being encountered in planning production capacity at EMP?

Capacity planning at EMP occurs concurrently with master production scheduling. Long lead-times for component parts is a concern for management. Due to the union contract, there is a long lead-time to change labor capacity relative to the order horizon. Another concern for management is the shut-down days of sister factories. Various interfactory customers plan their shut-down days/weeks according to their own needs. This creates changes in the requirement dates, and the master scheduler has to pull ahead orders and repeat the leveling activity.

4. What problems are currently being encountered in controlling production priority at EMP?

The key area of concern for priority control occurs at the two bottleneck areas: test and paint. Daily monitoring by the department supervisors and the general supervisor of assembly is the control method used for priority control in these areas. In these two departments reprioritization is common to meet customer ship dates. Another concern is the amount of changes in customer orders, which is about 13% monthly. Changes in customer orders can require the reprioritization and expediting of orders to make sure customer delivery dates are met. Frequency of set-up required on the assembly line is also problematic. The set-up frequency and time are factors not taken into considerations in the MRP calculations. Since the early stages of implementation, problems related to kanban have not been addressed by EMP.

5. What problems are currently being encountered in controlling production capacity at EMP?

Changes in available capacity at EMP occur due to machine down-time or changes in customer requirements. Capacity problems are typically resolved by using overtime or reassigning workers to areas where they are needed. Overtime in any assembly area must be approved by the factory manager. Department supervisors adjust workforce assignment, if allowed by the union contract, to resolve capacity problems.

During the course of this research, the logistics manager initiated several projects to address these problems and streamline the production planning process. A number of these projects will take more than a year to make an impact on the current production planning process.

Summary

This chapter examined the literature pertinent to the three most common production planning and control methods: material requirement planning (MRP), just-in-time (JIT), and constraints management (CM). The history, functionality, and advantages/disadvantages of each were discussed. The origin of genetic algorithms, as well as a discussion of the functionality of this method, was presented. One of its most significant advantages, it was pointed out, is flexibility. The findings of a foundational study for the current research, both current production planning and control methods and problems areas by production function, were reported.

CHAPTER III
RESEARCH DESIGN AND METHODOLOGY

Research Design

This experimental research (proposed method/present method) was designed to identify production planning and control (PP&C) constraints and to develop and validate scheduling and sequencing model based on constraints management and using genetic algorithms. The five research questions stated in Chapter I were used as a basis for this study.

1. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the cycle time for the final assembly line and four downstream processes at an engine manufacturing plant (EMP) of a midwestern manufacturer of agricultural equipment (MMAE)?
2. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the queue size for the final assembly line and four downstream processes at EMP?
3. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the utilization of work centers in the final assembly line and four downstream processes at EMP?
4. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the flow rate of engines through the final assembly line and four downstream processes at EMP?

5. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the total output of engines through the final assembly line and four downstream processes at EMP?

Independent Variable

The independent variable in this research is the method of scheduling and sequencing. The control condition is the current scheduling and sequencing method, and the experimental condition is the proposed scheduling and sequencing model based on constraints management and utilizing genetic algorithms.

Dependent Variables

The dependent variables in this research are as follows:

1. Cycle time of engines for the final assembly line and four down-stream processes
2. Queue size in front of four downstream processes after final assembly line
3. Utilization of work centers in the final assembly line and four downstream processes
4. Flow rate of engines through the final assembly line and four downstream processes
5. Total output of engines through final assembly line and four downstream processes

Present Method / Proposed Method

Control Group

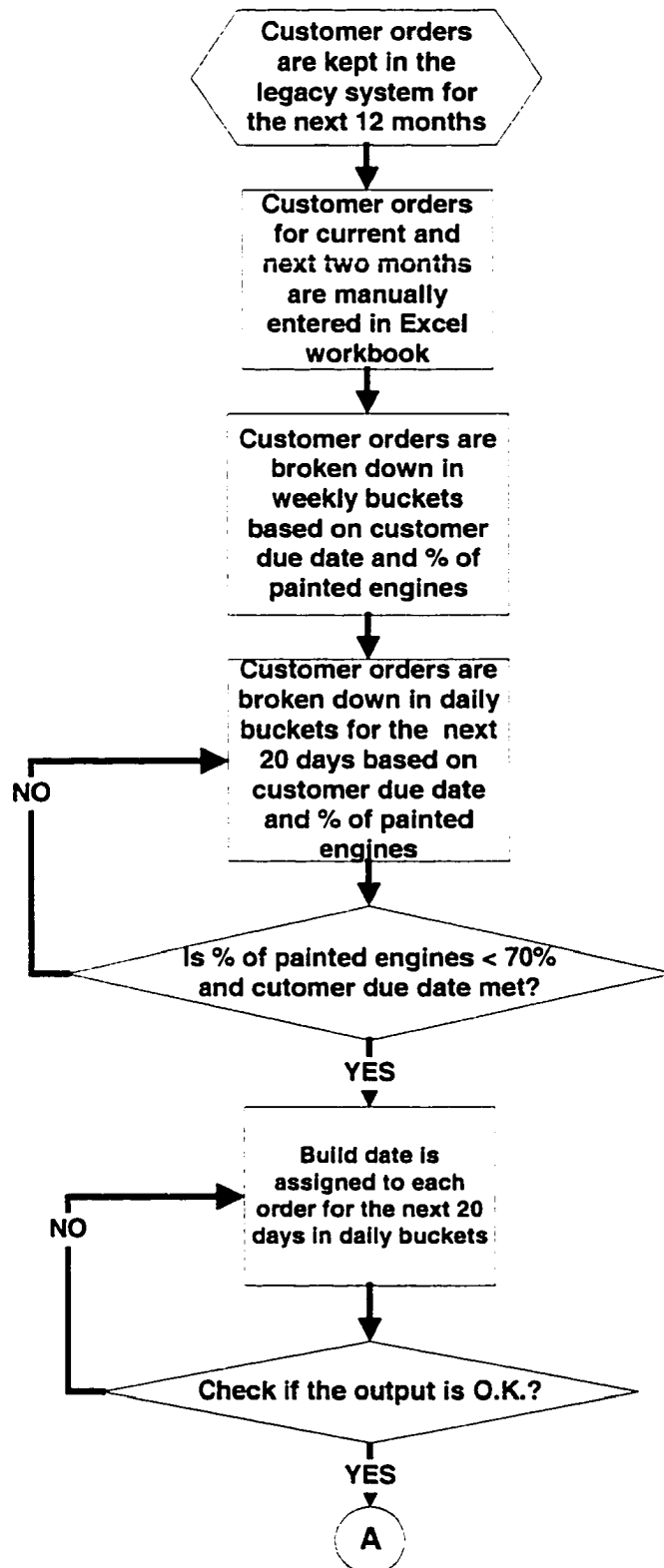
The process of master scheduling at EMP begins when an order is received from the customer with the required ship date. For interfactory customers, the common worldwide interfactory system (CWIS) is used: for various original equipment manufacturers (OEM), the complete goods order management and reporting system (COMAR) is utilized.

The master scheduler enters these orders into the master schedule system and accounts for the number of days it takes to build an engine (lead-time) for the next 12 months (Figure 6). Customer orders for the next two months are manually entered in an Excel workbook. These orders are broken down from monthly buckets into weekly buckets for these two months based on the customer due date and percentage of painted engines. An Excel file containing customer orders for the next four weeks is passed on to the line-up scheduler.

Customer orders for the next four weeks are broken down into daily buckets based on the customer due date and percentage of painted engines. A manual check is performed after the daily breakdown operation to confirm the percentage of painted engines is less than 70%. If the daily percentage of painted engines is less than 70% and customer due dates are met, a production build date is assigned to each customer order for the next 20 production days. If the daily percentage of painted engines is greater than 70%, assigned dates are adjusted manually and the schedule is frozen for the next production day. The next day's frozen schedule is manually sequenced in small batches.

The build schedule is generated and distributed on the shop floor for the next production day.

Flow chart for the control group was reviewed by the key expert in the area of production planning and control at EMP (D. Eck, personal communication, April 24, 2000), who confirmed that the flow chart is an actual representation of the current master scheduling and line-up process at EMP.



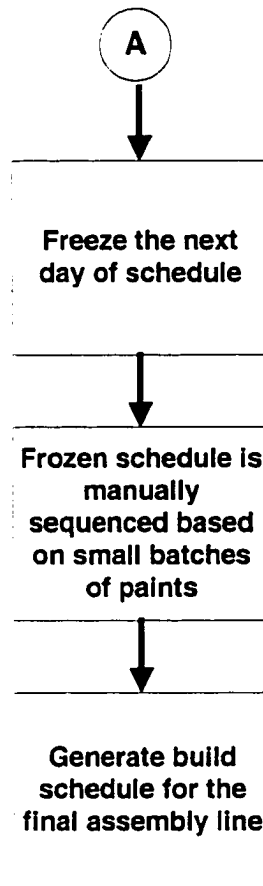
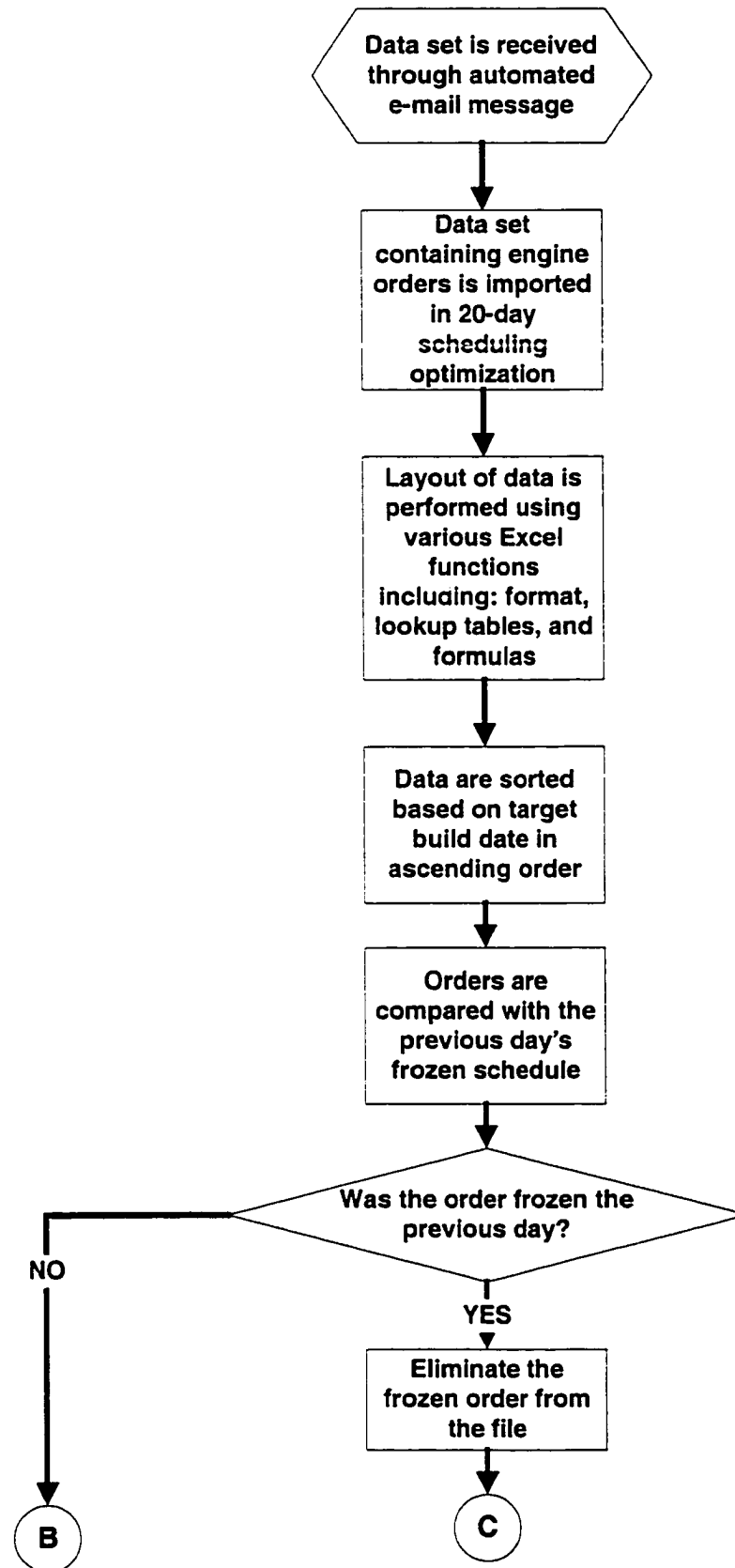


Figure 6. Control group flow chart for the master scheduling and line-up process.

Experimental Group

A flow chart for the experimental group is illustrated in Figure 7. This flow chart was also reviewed by the key expert in the area of production planning and control at EMP (D. Eck, personal communication, April 24, 2000). Detailed discussion about the new master scheduling and line-up process is presented in the next section. Snapshots of each Excel worksheet are described with the various Excel functions that were used for the development of the scheduling and sequencing model in Excel.



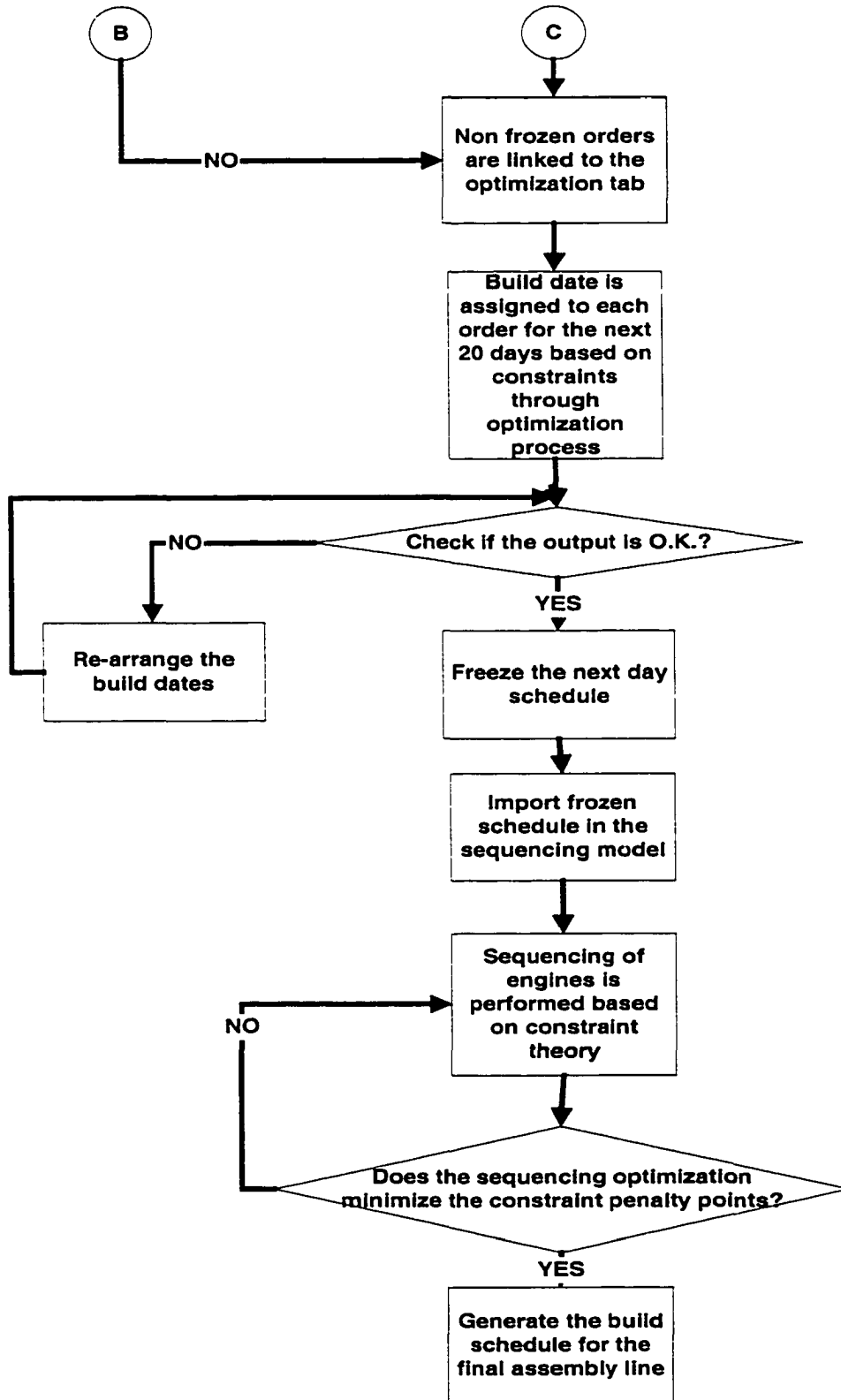


Figure 7. Experimental group flow chart for the master scheduling and line-up process.

Lack of time and capital resources limited the complete implementation of constraints management five focusing steps of: (a) identify the constraint, (b) exploit the constraint, (c) subordinate all other operations to the constraint, (d) elevate the constraint, and (e) avoid inertia. Three of the five focusing steps were used to develop the proposed scheduling and sequencing model at EMP; (a) identify the constraint, (b) exploit the constraint, and (c) subordinate all other operations to the constraint. Scheduling and sequencing methods used for the proposed model were based on drum-buffer-rope (DBR), which “is the core of the scheduling procedure under TOC” (Duclos & Spencer, 1995, p. 176). Figure 8 presents a generic version of the model used.

The paint operation was identified as the constraint at EMP, as indicated in step 1 of the focusing steps of constraints management. The paint operation dictates the launch schedule of engines at the final assembly line, thus fulfilling the definition of “drum” according to the APICS Dictionary: “the drum is the rate or pace of production set by the system’s constraint” (p. 25). According to the Schragenheim and Ronen (1990), “drum is the exploitation of the constraint of the system.” Using the drum to determine the pace of the system and its capacity accomplishes step 2 (exploit the constraint). A constraint buffer, which provides time to protect constraint from disruptions, was established after the custom trim operation. In the DBR method, the rope is a communication process from the constraint (paint operation) to the gating operation (final assembly line) that checks or limits material released into the system to support the constraint.

The flow of engines is depicted in Figure 9. After the engines leaves the final assembly line, a decision is made on space availability in test cells. If space is available, an engine is moved into a test cell; if not, the engine goes to temporary storage location.

After the engines are tested, they need to go through head torque operation. Once they pass this point, a decision is made on the routing of engines. Engines that are to be painted need to proceed first through custom trim, then paint and final trim areas. Non-paint engines go directly to final trim before they are warehoused. If both the custom trim and final trim queues are full, the head torque operation is shut down and the operator helps the test cell operators.

Figure 10 shows the time needed at each operation for the process of engines. A buffer of seven hours was created before the paint operation to protect the constraint from disruptions. The size of the constraint buffer was determined by managerial evaluation including operators in the paint operation and their supervisor opinions.

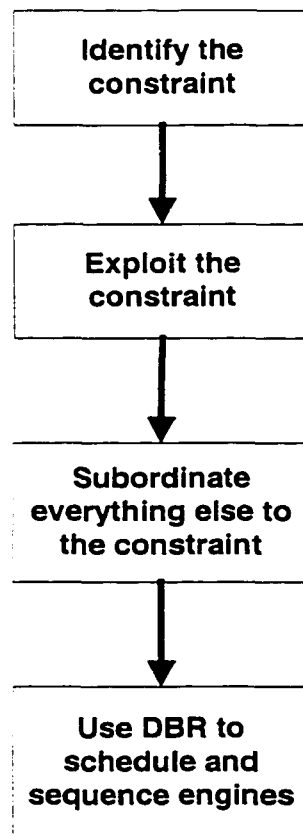


Figure 8. The application of CM at EMP.

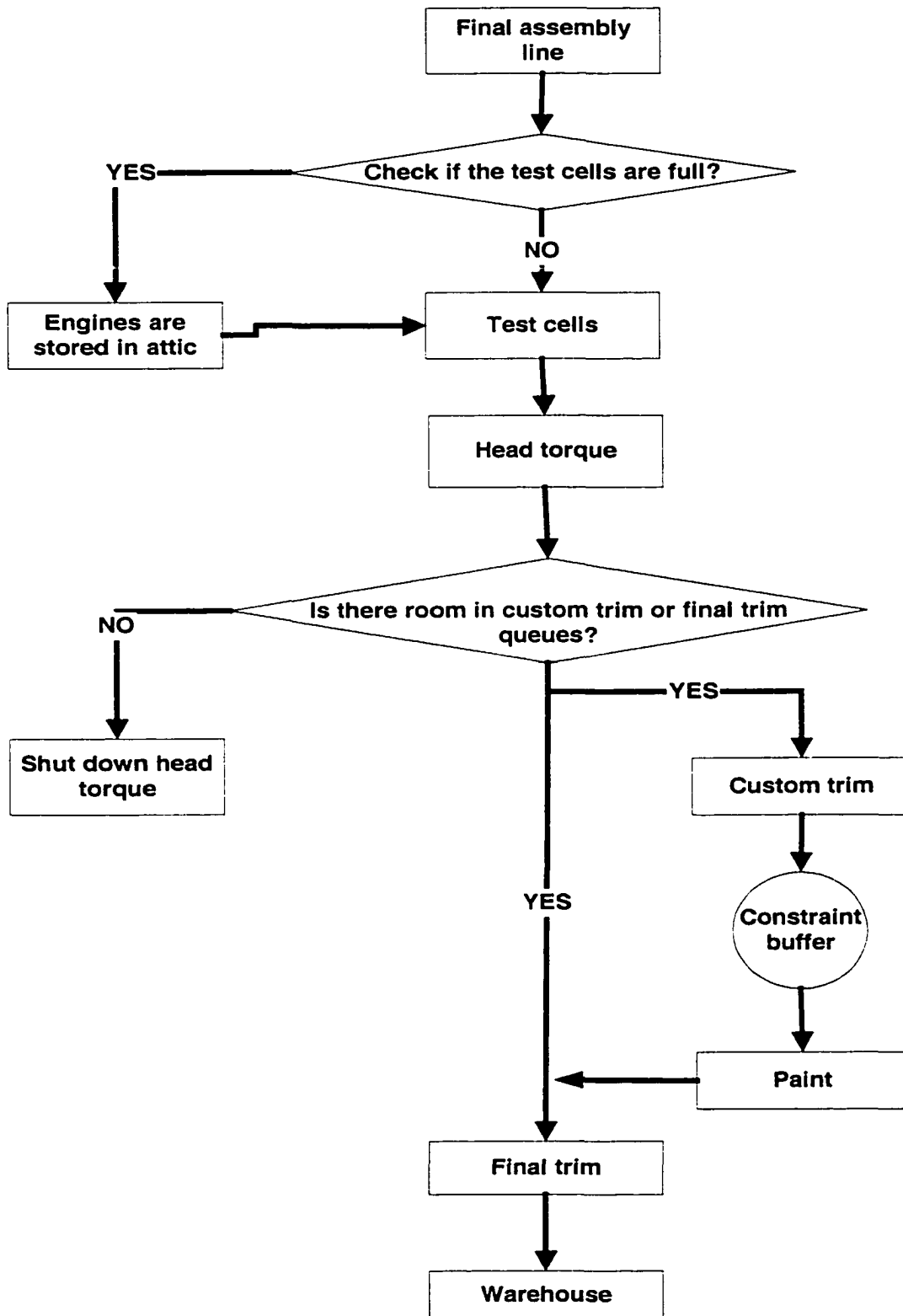


Figure 9. Flow of engines at EMP.

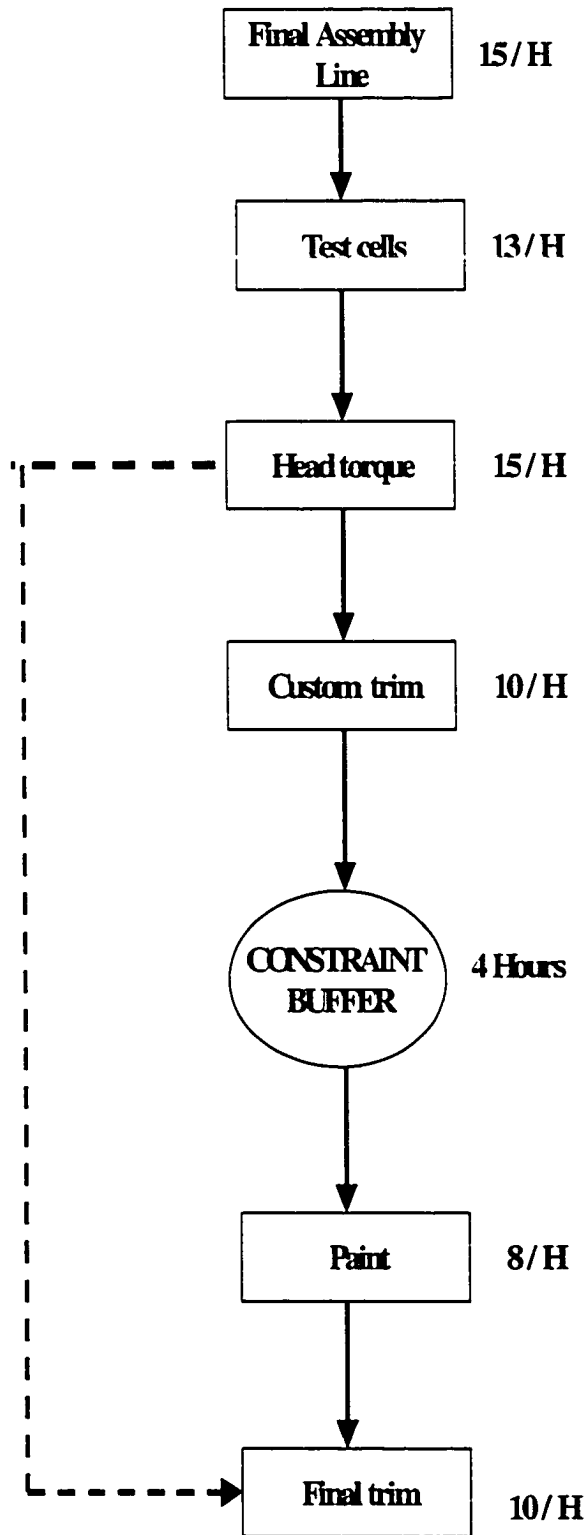


Figure 10. Flow rate of engines at EMP.

Scheduling model. Two-part model was developed in Excel, one part for scheduling and the other part for sequencing engines in order to utilize CM methods. In the scheduling part of the model, engine orders are assigned a date to be built based on the following constraint criteria:

1. Customer due date
2. Available capacity in final assembly line
3. Available capacity in the test department
4. Available capacity in the customer trim area
5. Available capacity in the paint area
6. Available capacity in the final trim area

Each day the scheduling model generated a daily build schedule for engines for the next 20 days. The build schedule was frozen for the first day of production and was adjusted daily for each of the remaining 19 days. Customer due date is the only hard constraint (constraint that cannot be violated) in this model. Soft constraints can be violated, but there is a penalty for each violation. The constraints and penalty points for each constraint are discussed in detail later in this section.

Figure 11 illustrates the first sheet of the scheduling model titled “import new orders.” A new file is downloaded everyday by clicking on the icon titled “IMPORT FILE.” Each file is updated daily in a folder saved on the server by the systems department. A macro was recorded with Microsoft Visual Basic in Excel to perform the import function from the server to the 20-day scheduling file. Each row represents an

Microsoft Excel - 20 DAY SCHEDULING OPTIMIZATION

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07

CUSTOMER	PART #	ORDER #	SHIP DATE	CUSTOMER LINE-UP DATE	QUANTITY	SEQUENCE
	19991105	19991221			1	1
WATERLOO	RG23812	32541		11/09/99	1	2
WATERLOO	RG23812	32541		11/09/99	1	1
WATERLOO	RG23878	32541		11/09/99	1	2
WATERLOO	RG23878	32541		11/09/99	1	3
WATERLOO	RG23878	32541		11/09/99	1	4
WATERLOO	RG23878	32541	11/16/99		1	1
WATERLOO	RG23878	32541	12/10/99		1	1
WATERLOO	RG23878	32541	12/10/99		2	2
WATERLOO	RG23878	32541	12/13/99		1	1
WATERLOO	RG23878	32541	12/14/99		1	1
WATERLOO	RG23878	32541	12/14/99		2	2
WATERLOO	RG23878	32541	12/17/99		1	1
WATERLOO	RG23878	32541	12/17/99		2	2
WATERLOO	RG23878	32541	12/17/99		3	3
WATERLOO	RG23878	32541	12/17/99		4	4
WATERLOO	RG23878	32541	12/20/99		1	1
WATERLOO	RG23878	32541	12/20/99		2	2
WATERLOO	RG23878	32541	12/20/99		3	3
WATERLOO	RG23878	32541	12/20/99		4	4

Import new orders / format orders / sort orders / comparison / optimization / frozen line-up / engine info

IMPORT FILE

CAPS NUM

Figure 11. Import new orders.

order in this file. If a customer orders 10 engines for the same date, these 10 engines are represented in 10 continuous rows.

Data set received from legacy systems needs to be formatted before it can be utilized in a Windows-based application. Additional information is assembled using a function in Excel called Vlookup table. Numerous Excel formulas were used to clean the data and make it useable for the optimization. In the next sheet, “format orders,” data are being filtered and cleaned. These formulas are visible in various figures in forthcoming sections. Figure 12 illustrates a snapshot of the “format orders” sheet, and Figure 13 illustrates the same sheet with the formulas in each cell visible. In the next sheet, “sort orders,” shown in Figure 14, data are filtered again and sorted based on “target build date” criteria in ascending order. Customer orders that need to be built early on were moved to the top of the list. Figure 15 illustrates the same sheet with formulas visible in the cells.

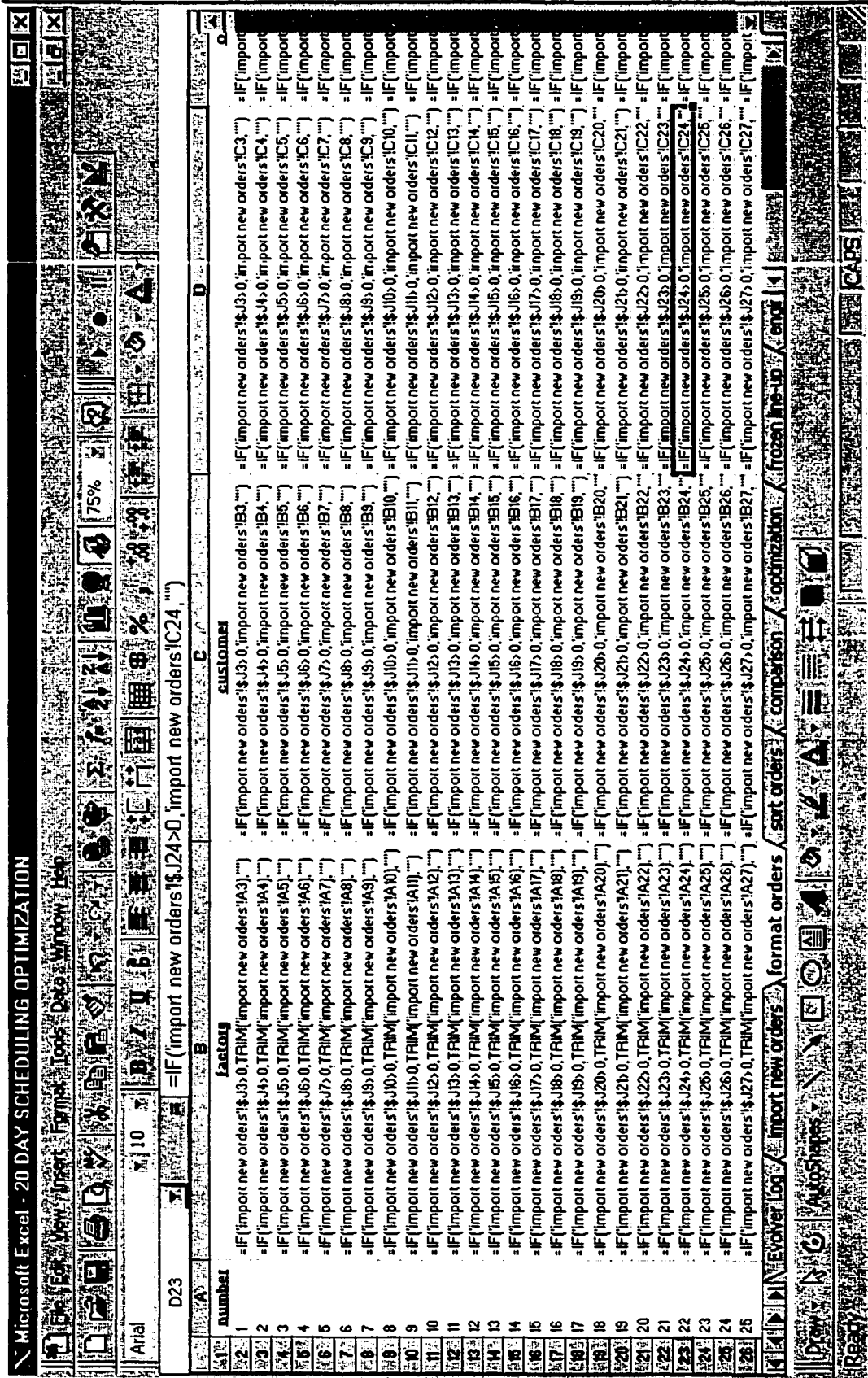


Figure 13. Format orders with formulas visible in the cells.

Microsoft Excel - 20 DAY SCHEDULING OPTIMIZATION

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Ready

COPY & SORT

factory	part #	model	target build	due date	unique number	paint / non	split	factory
1	WATERLOO	RG23812	6081HRW03	11/09/99	RG2381211/09/991	NON	2	165
2	WATERLOO	RG23812	6081HRW03	11/09/99	RG2381211/09/992	NON	2	166
3	WATERLOO	RG23878	6125HRW01	11/09/99	RG2387811/09/991	PAINT	3	167
4	WATERLOO	RG23878	6125HRW01	11/09/99	RG2387811/09/992	PAINT	3	105
5	WATERLOO	RG23878	6125HRW01	11/09/99	RG2387811/09/993	PAINT	3	106
6	WATERLOO	RG23878	6125HRW01	11/09/99	RG2387811/09/994	PAINT	3	107
7	WATERLOO	RG23878	6125HRW01	11/16/99	RG2387811/16/991	PAINT	3	108
8	WATERLOO	RG23878	6125HRW01	12/10/99	RG2387812/10/991	PAINT	3	35
9	WATERLOO	RG23878	6125HRW01	12/10/99	RG2387812/10/992	PAINT	3	36
10	WATERLOO	RG23878	6125HRW01	12/13/99	RG2387812/13/991	PAINT	3	2477
11	WATERLOO	RG23878	6125HRW01	12/14/99	RG2387812/14/991	PAINT	3	2478
12	WATERLOO	RG23878	6125HRW01	12/14/99	RG2387812/14/992	PAINT	3	2479
13	WATERLOO	RG23878	6125HRW01	12/17/99	RG2387812/17/991	PAINT	3	2480
14	WATERLOO	RG23878	6125HRW01	12/17/99	RG2387812/17/992	PAINT	3	2579
15	WATERLOO	RG23878	6125HRW01	12/17/99	RG2387812/17/993	PAINT	3	2580
16	WATERLOO	RG23878	6125HRW01	12/17/99	RG2387812/17/994	PAINT	3	2581
17	WATERLOO	RG23878	6125HRW01	12/20/99	RG2387812/20/991	PAINT	3	2582
18	WATERLOO	RG23878	6125HRW01	12/20/99	RG2387812/20/992	PAINT	3	2679
19	WATERLOO	RG23878	6125HRW01	12/20/99	RG2387812/20/993	PAINT	3	2680
20	WATERLOO	RG23878	6125HRW01	12/20/99	RG2387812/20/994	PAINT	3	2680
21	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/991	PAINT	3	2785
22	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/992	PAINT	3	2786
23	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/993	PAINT	3	2787
24	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/994	PAINT	3	2787
25	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/995	PAINT	3	2787
26	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/996	PAINT	3	2787
27	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/997	PAINT	3	2787
28	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/998	PAINT	3	2787
29	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/999	PAINT	3	2787
30	WATERLOO	RG23878	6125HRW01	12/21/99	RG2387812/21/1000	PAINT	3	2787

COUNTER 3566

sort orders / format orders / import new orders / sort orders / optimization / engine info /

Figure 14. Sort orders.

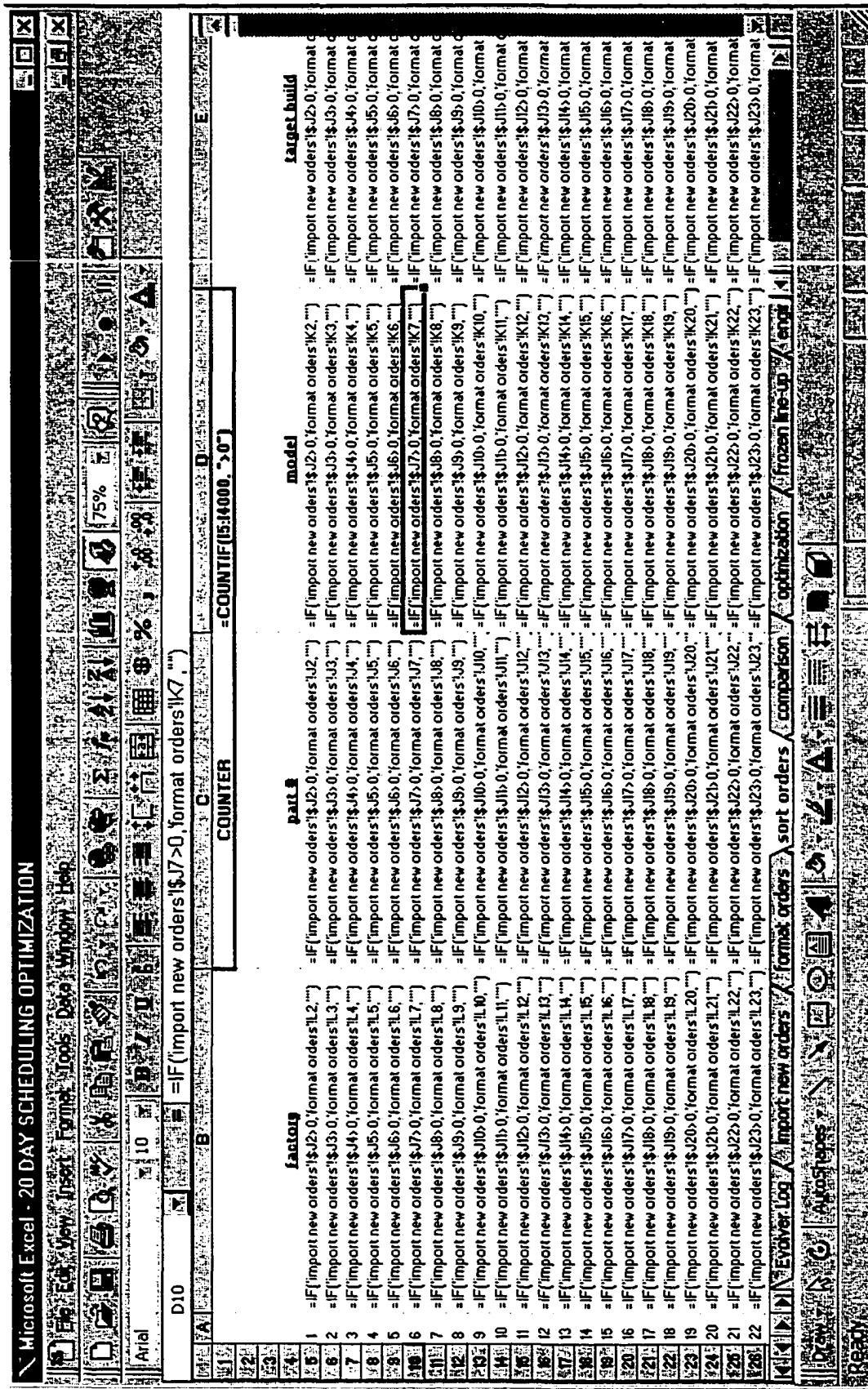


Figure 15. Sort orders with formulas visible in the cells.

Before the orders are linked to the “optimization” sheet, they are compared with the previous day’s frozen line-up. This step was necessary to avoid orders being duplicated. If an order is already frozen the previous day, that order will not be linked to the “optimization” sheet and thus will not be used for optimization. Figure 16 presents a snapshot of a “comparison” sheet, and Figure 17 depicts the same sheet with formulas visible in each cell.

Figures 18–23 illustrate various sections of the optimization sheet, the next step in the scheduling model. Figures 18 and 19 display the section in which available capacity in standard minutes is calculated for the j-hook capacity (final assembly line), test (engine test cells), custom trim (painted engines are trimmed before paint operation), final trim (painted engines are trimmed again after paint), and paint operations. Figures 20 and 21 illustrate the required capacity in standard minutes for the same processes. A calculation for the difference in available and required capacity for each process is also performed here. Figures 22 and 23 present the optimization sheet displaying scheduled orders with regard to customer ship dates. If an order is scheduled late, the date field is highlighted in red, making it readily visible for the master scheduler to adjust the schedule.

Microsoft Excel - 20 DAY SCHEDULING OPTIMIZATION

Arial 10

number	factory	customer	target build	due date	john deere	model	customer	qty	seq num	unique number	paint / no	split	pa
2	WATERLOO	RG23878			11/09/99	608H-RV03	WATERLOO	1	2	RG2387811/09/992	NON	2	
3	WATERLOO	RG23878			11/09/99	6125H-RV01	WATERLOO	1	1	RG2387811/09/991	PAIN	3	
4	WATERLOO	RG23878			11/09/99	6125H-RV01	WATERLOO	1	2	RG2387811/09/992	PAIN	3	
5	WATERLOO	RG23878			11/09/99	6125H-RV01	WATERLOO	1	3	RG2387811/09/993	PAIN	3	
6	WATERLOO	RG23878			11/09/99	6125H-RV01	WATERLOO	1	4	RG2387811/09/994	PAIN	3	
7	WATERLOO	RG23878		11/16/99		6125H-RV01	WATERLOO	1	1	RG2387811/16/991	PAIN	3	
8	WATERLOO	RG23878		12/10/99		6125H-RV01	WATERLOO	1	1	RG2387812/10/991	PAIN	3	
9	WATERLOO	RG23878		12/10/99		6125H-RV01	WATERLOO	1	2	RG2387812/10/992	PAIN	3	
10	WATERLOO	RG23878		12/13/99		6125H-RV01	WATERLOO	1	1	RG2387812/13/991	PAIN	3	
11	WATERLOO	RG23878		12/14/99		6125H-RV01	WATERLOO	1	1	RG2387812/14/991	PAIN	3	
12	WATERLOO	RG23878		12/14/99		6125H-RV01	WATERLOO	1	2	RG2387812/14/992	PAIN	3	
13	WATERLOO	RG23878		12/17/99		6125H-RV01	WATERLOO	1	1	RG2387812/17/991	PAIN	3	
14	WATERLOO	RG23878		12/17/99		6125H-RV01	WATERLOO	1	2	RG2387812/17/992	PAIN	3	
15	WATERLOO	RG23878		12/17/99		6125H-RV01	WATERLOO	1	3	RG2387812/17/993	PAIN	3	
16	WATERLOO	RG23878		12/17/99		6125H-RV01	WATERLOO	1	4	RG2387812/17/994	PAIN	3	
17	WATERLOO	RG23878		12/20/99		6125H-RV01	WATERLOO	1	1	RG2387812/20/991	PAIN	3	
18	WATERLOO	RG23878		12/20/99		6125H-RV01	WATERLOO	1	2	RG2387812/20/992	PAIN	3	
19	WATERLOO	RG23878		12/20/99		6125H-RV01	WATERLOO	1	3	RG2387812/20/993	PAIN	3	
20	WATERLOO	RG23878		12/20/99		6125H-RV01	WATERLOO	1	4	RG2387812/20/994	PAIN	3	
21	WATERLOO	RG23878		12/21/99		6125H-RV01	WATERLOO	1	1	RG2387812/21/991	PAIN	3	
22	WATERLOO	RG23878		12/21/99		6125H-RV01	WATERLOO	1	2	RG2387812/21/992	PAIN	3	
23	WATERLOO	RG23878		12/21/99		6125H-RV01	WATERLOO	1	3	RG2387812/21/993	PAIN	3	
24	WATERLOO	RG23878		12/21/99		6125H-RV01	WATERLOO	1	4	RG2387812/21/994	PAIN	3	

Evolver Log / Import new orders / format orders / sort orders / comparison / optimization / frozen line-up / end

Figure 16. Comparison.

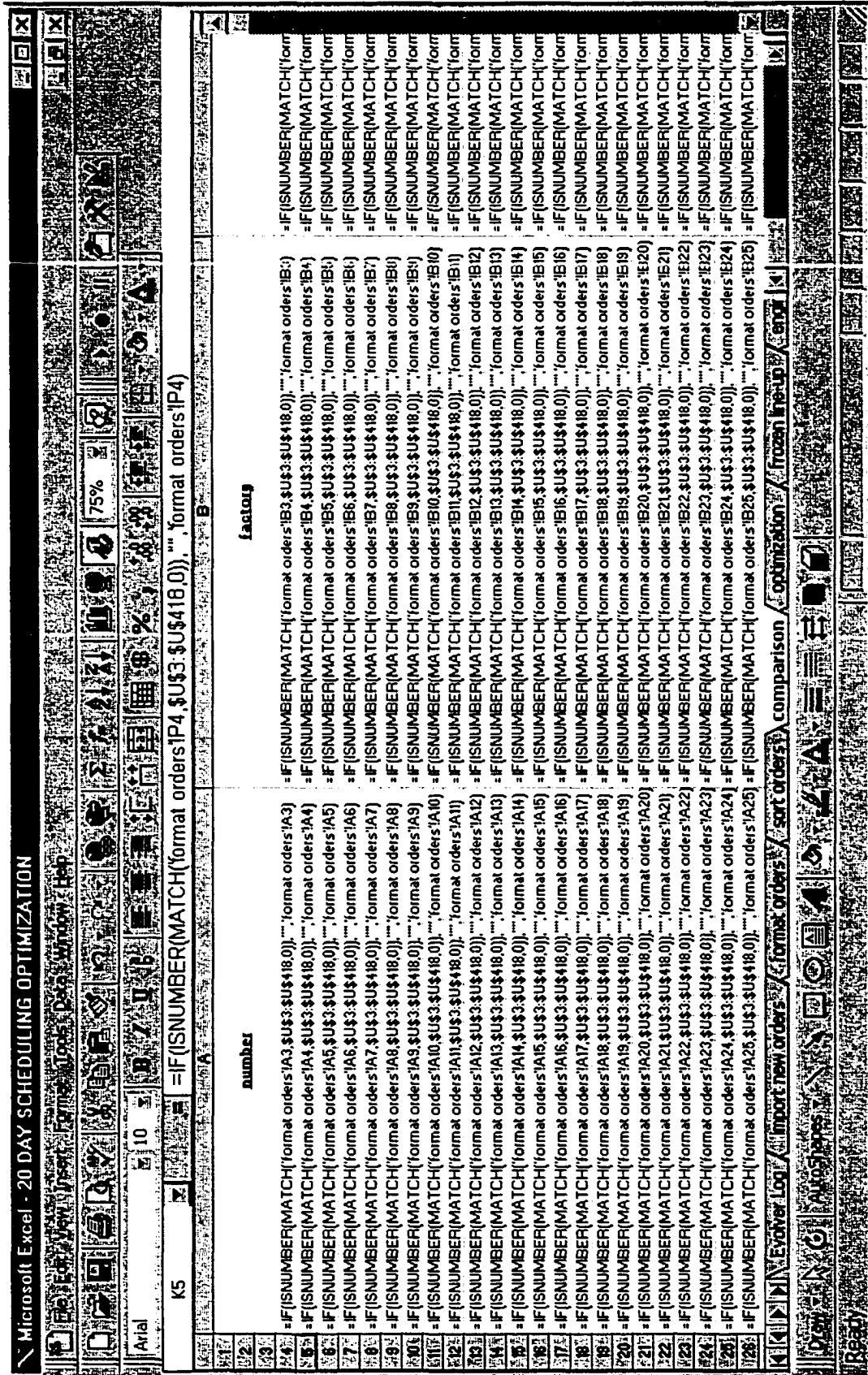


Figure 17. Comparison with formulas visible in the cells.

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	M	N	O	P	Q	R	S	T	U	V	X	Y	Z	AA	AB	AC	AD	AE	AF	AG	
2	J-HOOK	OT	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	
3		J-HOOK	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	17613	
4	TEST	OT	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	
5		TEST	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	5419	
6	CUSTOM	OT	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	
7		CUSTOM TRIM	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	2471	
8	PAINT	OT	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	
9		PAINT	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	1976	
10	FINAL T	OT	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	10%	
11		FINAL TRIM	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	4447	
14			1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
15	FINAL TRIM		11/3	11/4	11/5	11/8	11/9	11/10	11/11	11/12	11/15	11/16	11/17	11/18	11/19	11/22	11/23	11/24	11/29	11/30	12/1
16	82.92		1	0	0	0	0	0	1	0	1	0	1	0	0	0	0	0	0	1	2
17	0.00		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
18	0.00		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
19	0.000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
20	0.000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
21	18.77		1	0	1	0	1	2	1	1	2	1	9	2	1	0	1	0	0	1	1

Figure 18. Optimization tab, available capacity section.

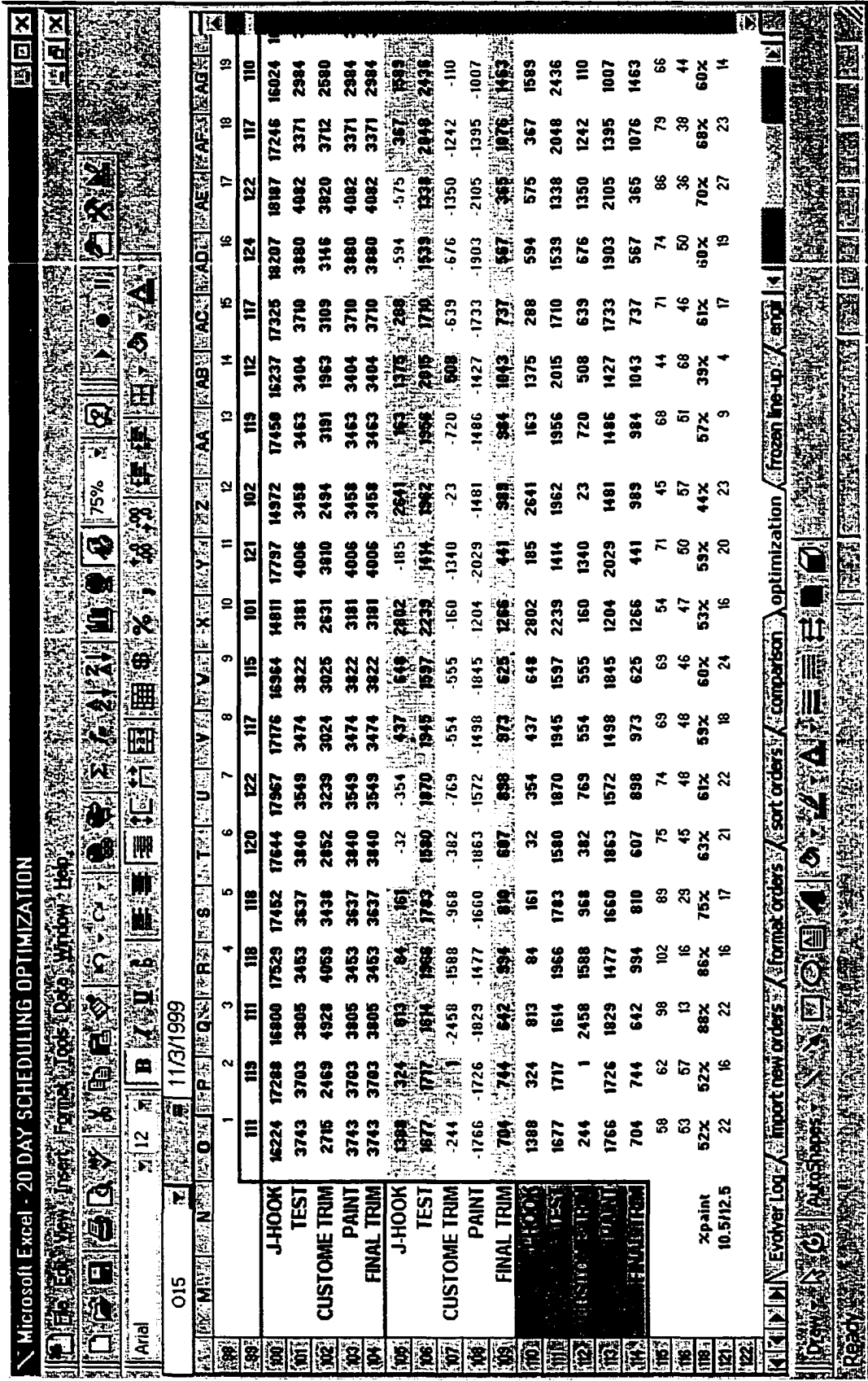


Figure 20. Optimization tab, required capacity section.

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10

	1	2	3	4	5	6
J-HOOK	=SUM(Q16:Q97)	=SUM(P16:P97)	=SUM(R16:R97)	=SUM(S16:S97)		
TEST	=SUM(\$I\$16:\$I\$97*Q16:Q97)	=SUM(\$I\$16:\$I\$97*P16:P97)	=SUM(\$I\$16:\$I\$97*Q16:Q97)	=SUM(\$I\$16:\$I\$97*R16:R97)	=SUM(\$I\$16:\$I\$97*S16:S97)	
CUSTOMER TRIM	=SUM(\$J\$16:\$J\$97*Q16:Q97)	=SUM(\$J\$16:\$J\$97*P16:P97)	=SUM(\$J\$16:\$J\$97*Q16:Q97)	=SUM(\$J\$16:\$J\$97*R16:R97)	=SUM(\$J\$16:\$J\$97*S16:S97)	
PAINT	=SUM(\$K\$16:\$K\$97*Q16:Q97)	=SUM(\$K\$16:\$K\$97*P16:P97)	=SUM(\$K\$16:\$K\$97*Q16:Q97)	=SUM(\$K\$16:\$K\$97*R16:R97)	=SUM(\$K\$16:\$K\$97*S16:S97)	
FINAL TRIM	=SUM(\$L\$16:\$L\$97*Q16:Q97)	=SUM(\$L\$16:\$L\$97*P16:P97)	=SUM(\$L\$16:\$L\$97*Q16:Q97)	=SUM(\$L\$16:\$L\$97*R16:R97)	=SUM(\$L\$16:\$L\$97*S16:S97)	
J-HOOK	=SUM(Q100)	=SUM(P100)	=SUM(R100)	=SUM(S100)		
TEST	=SUM(Q101)	=SUM(P101)	=SUM(R101)	=SUM(S101)		
CUSTOMER TRIM	=SUM(Q102)	=SUM(P102)	=SUM(R102)	=SUM(S102)		
PAINT	=SUM(Q103)	=SUM(P103)	=SUM(R103)	=SUM(S103)		
FINAL TRIM	=SUM(Q104)	=SUM(P104)	=SUM(R104)	=SUM(S104)		
J-HOOK	=ABS(Q105)	=ABS(P105)	=ABS(R105)	=ABS(S105)		
TEST	=ABS(Q106)	=ABS(P106)	=ABS(R106)	=ABS(S106)		
CUSTOMER TRIM	=ABS(Q107)	=ABS(P107)	=ABS(R107)	=ABS(S107)		
PAINT	=ABS(Q108)	=ABS(P108)	=ABS(R108)	=ABS(S108)		
FINAL TRIM	=ABS(Q109)	=ABS(P109)	=ABS(R109)	=ABS(S109)		
J-HOOK	=SUM(IF(\$A:\$16:\$A,\$97,"PAINT"),C)	=SUM(IF(\$A:\$16:\$A,\$97,"PAINT"),C)	=SUM(IF(\$A:\$16:\$A,\$97,"PAINT"),C)	=SUM(IF(\$A:\$16:\$A,\$97,"PAINT"),C)	=SUM(IF(\$A:\$16:\$A,\$97,"PAINT"),C)	
TEST	=SUM(IF(\$A:\$16:\$A,\$97,"NON"),Q)	=SUM(IF(\$A:\$16:\$A,\$97,"NON"),Q)	=SUM(IF(\$A:\$16:\$A,\$97,"NON"),Q)	=SUM(IF(\$A:\$16:\$A,\$97,"NON"),Q)	=SUM(IF(\$A:\$16:\$A,\$97,"NON"),Q)	
CUSTOMER TRIM	=SUM(Q117)	=SUM(P117)	=SUM(R117)	=SUM(S117)		

zpaint

Evolver Log Import new orders / format orders / sort orders / comparison / optimization / frozen lines / center

Figure 21. Optimization tab, required capacity section, with formulas visible in the cells.

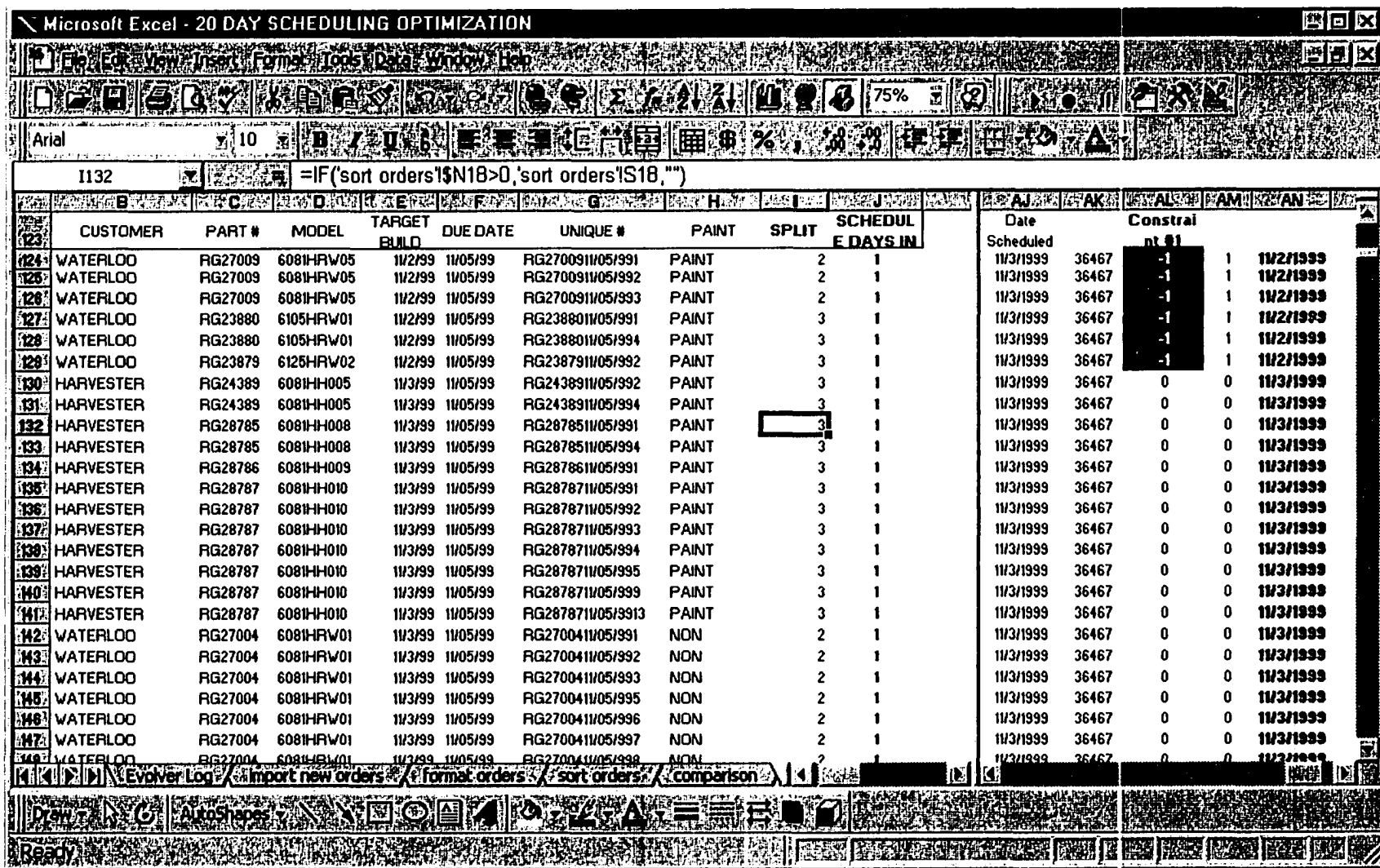


Figure 22. Optimization tab, scheduled orders with ship date relative to each customer.

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AJ124 =INDEX(O6:15,AH\$15,MATCH(I,O124:AH124,FALSE))

	CUSTOMER	PART #	MODEL	Constraint #1
124	=IF('sort orders'!\$N6>0,'sort orders'!L5,"")	=IF('sort orders'!\$N5>0,'sort orders'!M5,"")	=IF('sort orders'!\$N6>0,'sort orders'!M6,"")	=IF(NETWORKDAYS(AK124,E124)>0, NETWORKDAYS(AK124,E12 -A
125	=IF('sort orders'!\$N6>0,'sort orders'!L6,"")	=IF('sort orders'!\$N6>0,'sort orders'!M6,"")	=IF('sort orders'!\$N7>0,'sort orders'!M7,"")	=IF(NETWORKDAYS(AK125,E125)>0, NETWORKDAYS(AK125,E12 -A
126	=IF('sort orders'!\$N7>0,'sort orders'!L7,"")	=IF('sort orders'!\$N7>0,'sort orders'!M7,"")	=IF('sort orders'!\$N8>0,'sort orders'!M8,"")	=IF(NETWORKDAYS(AK126,E126)>0, NETWORKDAYS(AK126,E12 -A
127	=IF('sort orders'!\$N8>0,'sort orders'!L8,"")	=IF('sort orders'!\$N8>0,'sort orders'!M8,"")	=IF('sort orders'!\$N9>0,'sort orders'!M9,"")	=IF(NETWORKDAYS(AK127,E127)>0, NETWORKDAYS(AK127,E12 -A
128	=IF('sort orders'!\$N9>0,'sort orders'!L9,"")	=IF('sort orders'!\$N9>0,'sort orders'!M9,"")	=IF('sort orders'!\$N10>0,'sort orders'!M10,"")	=IF(NETWORKDAYS(AK128,E128)>0, NETWORKDAYS(AK128,E12 -A
129	=IF('sort orders'!\$N10>0,'sort orders'!L10,"")	=IF('sort orders'!\$N10>0,'sort orders'!M10,"")	=IF('sort orders'!\$N11>0,'sort orders'!M11,"")	=IF(NETWORKDAYS(AK129,E129)>0, NETWORKDAYS(AK129,E12 -A
130	=IF('sort orders'!\$N11>0,'sort orders'!L11,"")	=IF('sort orders'!\$N11>0,'sort orders'!M11,"")	=IF('sort orders'!\$N12>0,'sort orders'!M12,"")	=IF(NETWORKDAYS(AK130,E130)>0, NETWORKDAYS(AK130,E130)-INETWOTI =A
131	=IF('sort orders'!\$N12>0,'sort orders'!L12,"")	=IF('sort orders'!\$N12>0,'sort orders'!M12,"")	=IF('sort orders'!\$N13>0,'sort orders'!M13,"")	=IF(NETWORKDAYS(AK131,E131)>0, NETWORKDAYS(AK131,E131)-INETWOTI =A
132	=IF('sort orders'!\$N13>0,'sort orders'!L13,"")	=IF('sort orders'!\$N13>0,'sort orders'!M13,"")	=IF('sort orders'!\$N14>0,'sort orders'!M14,"")	=IF(NETWORKDAYS(AK132,E132)>0, NETWORKDAYS(AK132,E132)-INETWOTI =A
133	=IF('sort orders'!\$N14>0,'sort orders'!L14,"")	=IF('sort orders'!\$N14>0,'sort orders'!M14,"")	=IF('sort orders'!\$N15>0,'sort orders'!M15,"")	=IF(NETWORKDAYS(AK133,E133)>0, NETWORKDAYS(AK133,E133)-INETWOTI =A
134	=IF('sort orders'!\$N15>0,'sort orders'!L15,"")	=IF('sort orders'!\$N15>0,'sort orders'!M15,"")	=IF('sort orders'!\$N16>0,'sort orders'!M16,"")	=IF(NETWORKDAYS(AK134,E134)>0, NETWORKDAYS(AK134,E134)-INETWOTI =A
135	=IF('sort orders'!\$N16>0,'sort orders'!L16,"")	=IF('sort orders'!\$N16>0,'sort orders'!M16,"")	=IF('sort orders'!\$N17>0,'sort orders'!M17,"")	=IF(NETWORKDAYS(AK135,E135)>0, NETWORKDAYS(AK135,E135)-INETWOTI =A
136	=IF('sort orders'!\$N17>0,'sort orders'!L17,"")	=IF('sort orders'!\$N17>0,'sort orders'!M17,"")	=IF('sort orders'!\$N18>0,'sort orders'!M18,"")	=IF(NETWORKDAYS(AK136,E136)>0, NETWORKDAYS(AK136,E136)-INETWOTI =A
137	=IF('sort orders'!\$N18>0,'sort orders'!L18,"")	=IF('sort orders'!\$N18>0,'sort orders'!M18,"")	=IF('sort orders'!\$N19>0,'sort orders'!M19,"")	=IF(NETWORKDAYS(AK137,E137)>0, NETWORKDAYS(AK137,E137)-INETWOTI =A
138	=IF('sort orders'!\$N19>0,'sort orders'!L19,"")	=IF('sort orders'!\$N19>0,'sort orders'!M19,"")	=IF('sort orders'!\$N20>0,'sort orders'!M20,"")	=IF(NETWORKDAYS(AK138,E138)>0, NETWORKDAYS(AK138,E138)-INETWOTI =A
139	=IF('sort orders'!\$N20>0,'sort orders'!L20,"")	=IF('sort orders'!\$N20>0,'sort orders'!M20,"")	=IF('sort orders'!\$N21>0,'sort orders'!M21,"")	=IF(NETWORKDAYS(AK139,E139)>0, NETWORKDAYS(AK139,E139)-INETWOTI =A
140	=IF('sort orders'!\$N21>0,'sort orders'!L21,"")	=IF('sort orders'!\$N21>0,'sort orders'!M21,"")	=IF('sort orders'!\$N22>0,'sort orders'!M22,"")	=IF(NETWORKDAYS(AK140,E140)>0, NETWORKDAYS(AK140,E140)-INETWOTI =A
141	=IF('sort orders'!\$N22>0,'sort orders'!L22,"")	=IF('sort orders'!\$N22>0,'sort orders'!M22,"")	=IF('sort orders'!\$N23>0,'sort orders'!M23,"")	=IF(NETWORKDAYS(AK141,E141)>0, NETWORKDAYS(AK141,E141)-INETWOTI =A
142	=IF('sort orders'!\$N23>0,'sort orders'!L23,"")	=IF('sort orders'!\$N23>0,'sort orders'!M23,"")	=IF('sort orders'!\$N24>0,'sort orders'!M24,"")	=IF(NETWORKDAYS(AK142,E142)>0, NETWORKDAYS(AK142,E142)-INETWOTI =A
143	=IF('sort orders'!\$N24>0,'sort orders'!L24,"")	=IF('sort orders'!\$N24>0,'sort orders'!M24,"")	=IF('sort orders'!\$N25>0,'sort orders'!M25,"")	=IF(NETWORKDAYS(AK143,E143)>0, NETWORKDAYS(AK143,E143)-INETWOTI =A
144	=IF('sort orders'!\$N25>0,'sort orders'!L25,"")	=IF('sort orders'!\$N25>0,'sort orders'!M25,"")	=IF('sort orders'!\$N26>0,'sort orders'!M26,"")	=IF(NETWORKDAYS(AK144,E144)>0, NETWORKDAYS(AK144,E144)-INETWOTI =A
145	=IF('sort orders'!\$N26>0,'sort orders'!L26,"")	=IF('sort orders'!\$N26>0,'sort orders'!M26,"")	=IF('sort orders'!\$N27>0,'sort orders'!M27,"")	=IF(NETWORKDAYS(AK145,E145)>0, NETWORKDAYS(AK145,E145)-INETWOTI =A
146	=IF('sort orders'!\$N27>0,'sort orders'!L27,"")	=IF('sort orders'!\$N27>0,'sort orders'!M27,"")	=IF('sort orders'!\$N28>0,'sort orders'!M28,"")	=IF(NETWORKDAYS(AK146,E146)>0, NETWORKDAYS(AK146,E146)-INETWOTI =A
147	=IF('sort orders'!\$N28>0,'sort orders'!L28,"")	=IF('sort orders'!\$N28>0,'sort orders'!M28,"")	=IF('sort orders'!\$N29>0,'sort orders'!M29,"")	=IF(NETWORKDAYS(AK147,E147)>0, NETWORKDAYS(AK147,E147)-INETWOTI =A
148	=IF('sort orders'!\$N29>0,'sort orders'!L29,"")	=IF('sort orders'!\$N29>0,'sort orders'!M29,"")	=IF('sort orders'!\$N30>0,'sort orders'!M30,"")	=IF(NETWORKDAYS(AK148,E148)>0, NETWORKDAYS(AK148,E148)-INETWOTI =A

Ready

Figure 23. Optimization tab, scheduled orders with ship date relative to each customer, formulas visible in the cells.

After the optimization is performed using genetic algorithms, the schedule for the first day is frozen (Figure 24). These orders are linked to the next spreadsheet titled “frozen line-up” in the 20-day scheduling optimization model. Orders are compared with these frozen orders before they are included in the optimization to eliminate any duplication. These orders are also linked to the sequencing part of the model called sequencing model, which is discussed in detail in the next section. The last sheet in the model (Figure 25) titled “engine info,” includes part number, engine model, lead time in days and split time in minutes. This information is used for the final assembly line (j-hook).

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	A	B	C	D	E	F	G	H	I	J
2	CUSTOMER	PART #	MODEL	DUE DATE	UNIQUE #	PAINT	SPLIT			
3	WATERLOO	RG27009	6081HRW05	11/05/99	RG2700911/05/991	PAINT	2			
4	WATERLOO	RG27009	6081HRW05	11/05/99	RG2700911/05/992	PAINT	2			
5	WATERLOO	RG27009	6081HRW05	11/05/99	RG2700911/05/993	PAINT	2			
6	WATERLOO	RG23880	6105HRW01	11/05/99	RG2388011/05/991	PAINT	3			
7	WATERLOO	RG23880	6105HRW01	11/05/99	RG2388011/05/994	PAINT	3			
8	WATERLOO	RG23879	6125HRW02	11/05/99	RG2387911/05/992	PAINT	3			
9	HARVESTER	RG24389	6081HH005	11/05/99	RG2438911/05/992	PAINT	3			
10	HARVESTER	RG24389	6081HH005	11/05/99	RG2438911/05/994	PAINT	3			
11	HARVESTER	RG28785	6081HH008	11/05/99	RG2878511/05/991	PAINT	3			
12	HARVESTER	RG28785	6081HH008	11/05/99	RG2878511/05/994	PAINT	3			
13	HARVESTER	RG28786	6081HH009	11/05/99	RG2878611/05/991	PAINT	3			
14	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/991	PAINT	3			
15	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/992	PAINT	3			
16	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/993	PAINT	3			
17	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/994	PAINT	3			
18	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/995	PAINT	3			
19	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/999	PAINT	3			
20	HARVESTER	RG28787	6081HH010	11/05/99	RG2878711/05/9913	PAINT	3			
21	WATERLOO	RG27004	6081HRW01	11/05/99	RG2700411/05/991	NON	2			

Import new orders / format orders / sort orders / comparison / optimization / frozen line-up / engine info

Ready

Figure 24. Frozen line-up tab.

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I24														
	A	B	C	D	E	F	G	H	I	J	K	L	M	
1								SPLIT TIME						
2				MODEL	Lead Time	Paint	SPLIT	1	3.133					
3	RG23811	6081 HRW02	6081HRW02	2	NON	1	2	3.167	RG23811	6081 HRW02	6081HR			
4	RG23812	6081 HRW03	6081HRW03	2	NON	1	3	3.3	RG23812	6081 HRW03	6081HR			
5	RG23878	6125 HRW01	6125HRW01	3	PAINT	5	4	3.4	RG23878	6125 HRW01	6125HR			
6	RG23879	6125 HRW02	6125HRW02	3	PAINT	6	5	3.633	RG23879	6125 HRW02	6125HR			
7	RG23880	6105 HRW01	6105HRW01	3	PAINT	6	6	3.7	RG23880	6105 HRW01	6105HR			
8	RG24703	6081 HRW09	6081HRW09	2	NON	1	7	3.7	RG24703	6081 HRW09	6081HR			
9	RG24972	6081 HRW10	6081HRW10	2	NON	1	8	3.85	RG24972	6081 HRW10	6081HR			
10	RG26999	6081 TRW01	6081TRW01	2	NON	2	9	3.85	RG26999	6081 TRW01	6081TR			
11	RG27003	6081 TRW02	6081TRW02	2	NON	1	10	3.267	RG27003	6081 TRW02	6081TR			
12	RG29286	6081 TRW09	6081TRW09	2	NON	2	11	4.033	RG27004	6081 HRW01	6081HR			
13	RG29288	6081 TRW10	6081TRW10	2	NON	2	12	2.65	RG27009	6081 HRW05	6081HR			
14	RG27004	6081 HRW01	6081HRW01	2	NON	1	13	3.5	RG27019	6081 HRW06	6081HR			
15	RG27009	6081 HRW05	6081HRW05	2	PAINT	1	14	2.733	RG27020	6081 HRW07	6081HR			
16	RG27019	6081 HRW06	6081HRW06	2	NON	1			RG27021	6081 HRW08	6081HR			

Figure 25. Engine info tab.

To summarize the 20-day scheduling model: after orders are assigned to the first production day, that day's production schedule is frozen; no additions or deletions can be made to the schedule. Once the first day is frozen, it is linked to the sequencing model, which is discussed in the next section.

Sequencing model. In the sequencing part of the model, sequencing of engines is performed based on the following constraint criteria:

1. Total number of set-ups at the final assembly line (J-Hook)
2. Total number of split changes at the final assembly line (J-Hook)
3. Number of painted engines built per hour
4. Avoiding continuous build of painted engines
5. Grouping of similar types of engine models together

The build schedule for the next production day is frozen every day based on the scheduling constraints mentioned in the previous section. This schedule updates the worksheet titled "frozen line-up" in the scheduling model. The frozen line-up worksheet is linked to the sequencing model (Figures 26-30). Figure 26 shows the section where constraint points and penalty assigned to each constraint are calculated (cells H3:K9). Columns B through E are linked to the frozen line-up worksheet of the 20-day scheduling model. These same columns are also updated automatically every time the frozen line-up worksheet is updated in the scheduling model.

All the constraints in the sequencing model were soft constraints for which individual constraints can be violated. However, each violation had predetermined penalty points which the model applied accordingly. Cells J3:J8 in Figure 26 indicate the

violations for all five constraints. As can be seen, there were 28 violations of the setup constraint, caused by 28 setup changes resulting from the sequencing of the line up.

Correspondingly, for the other four constraints, violations were as follows:

(a) 31 split changes, (b) 42 paint violations, (c) 9 consecutive paint violations, and (d) 57 group models violations. Figures 27 and 28 illustrate the same information that appears in Figure 26 but the formulas are visible in the cells. Figures 29–30 illustrate the computation of each constraint for each row with and without formulas visible in the cells.

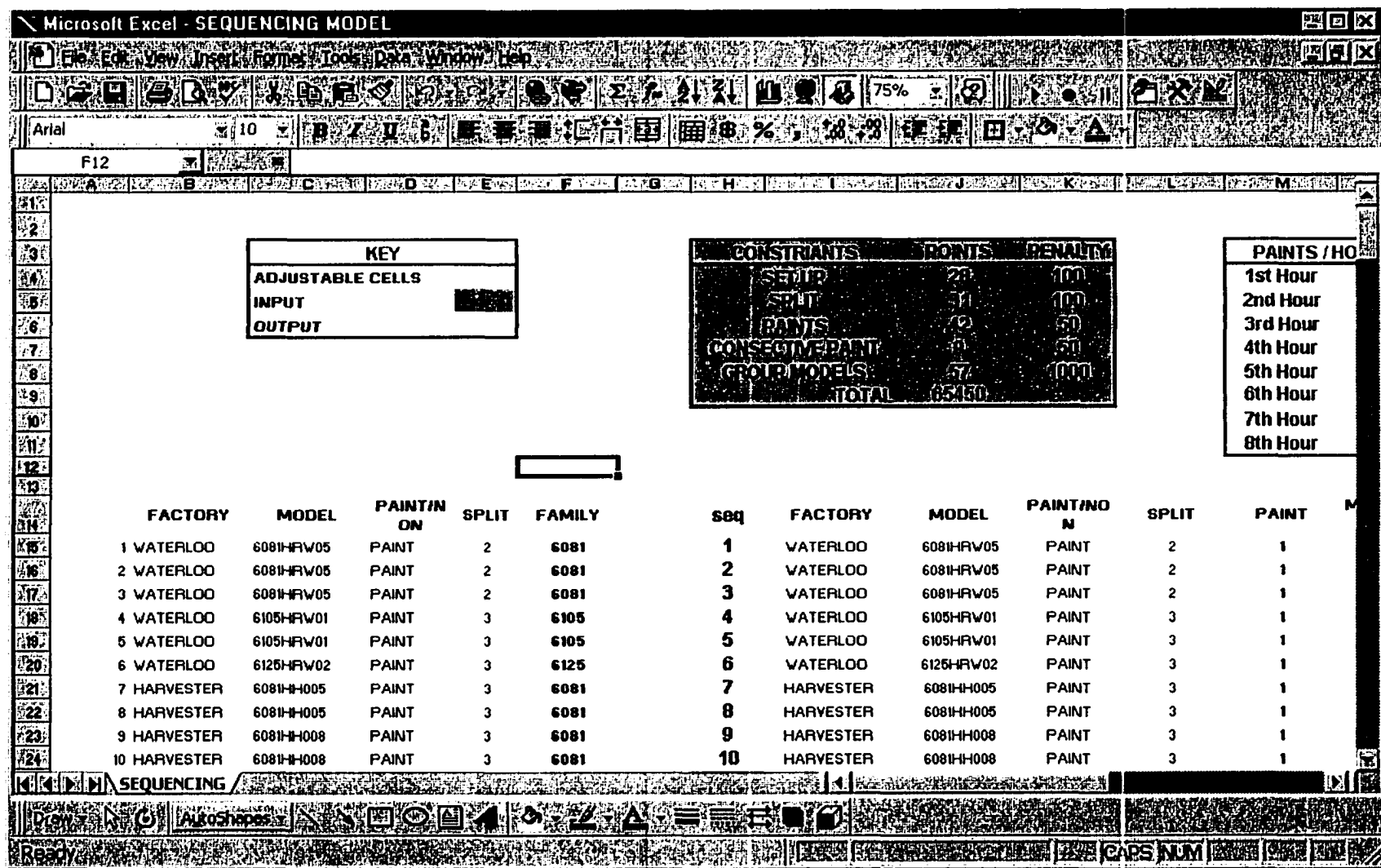


Figure 26. Sequencing tab, calculation of constraint points.

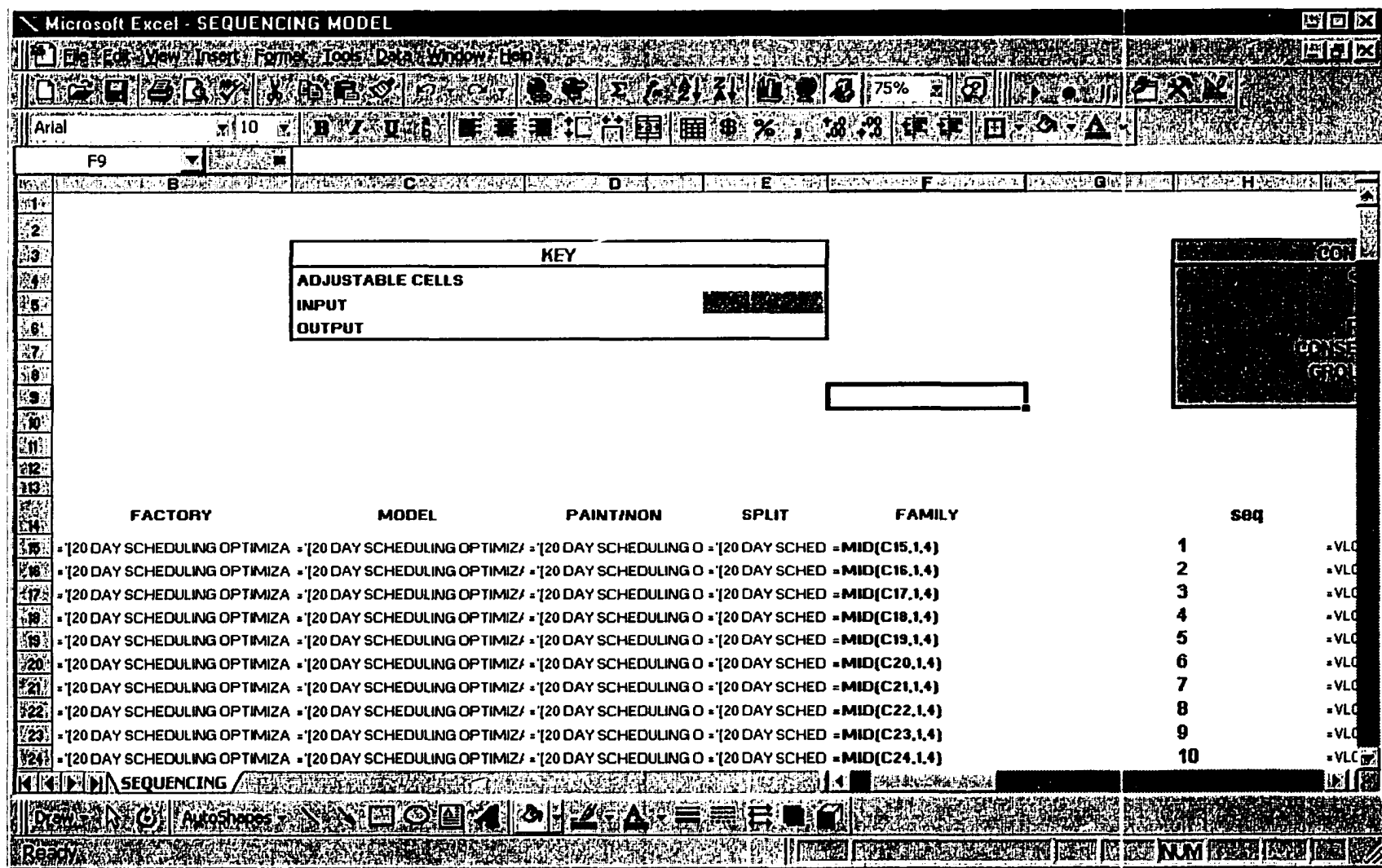


Figure 27. Sequencing tab, calculation of constraint points, with formulas visible in the cells (a).

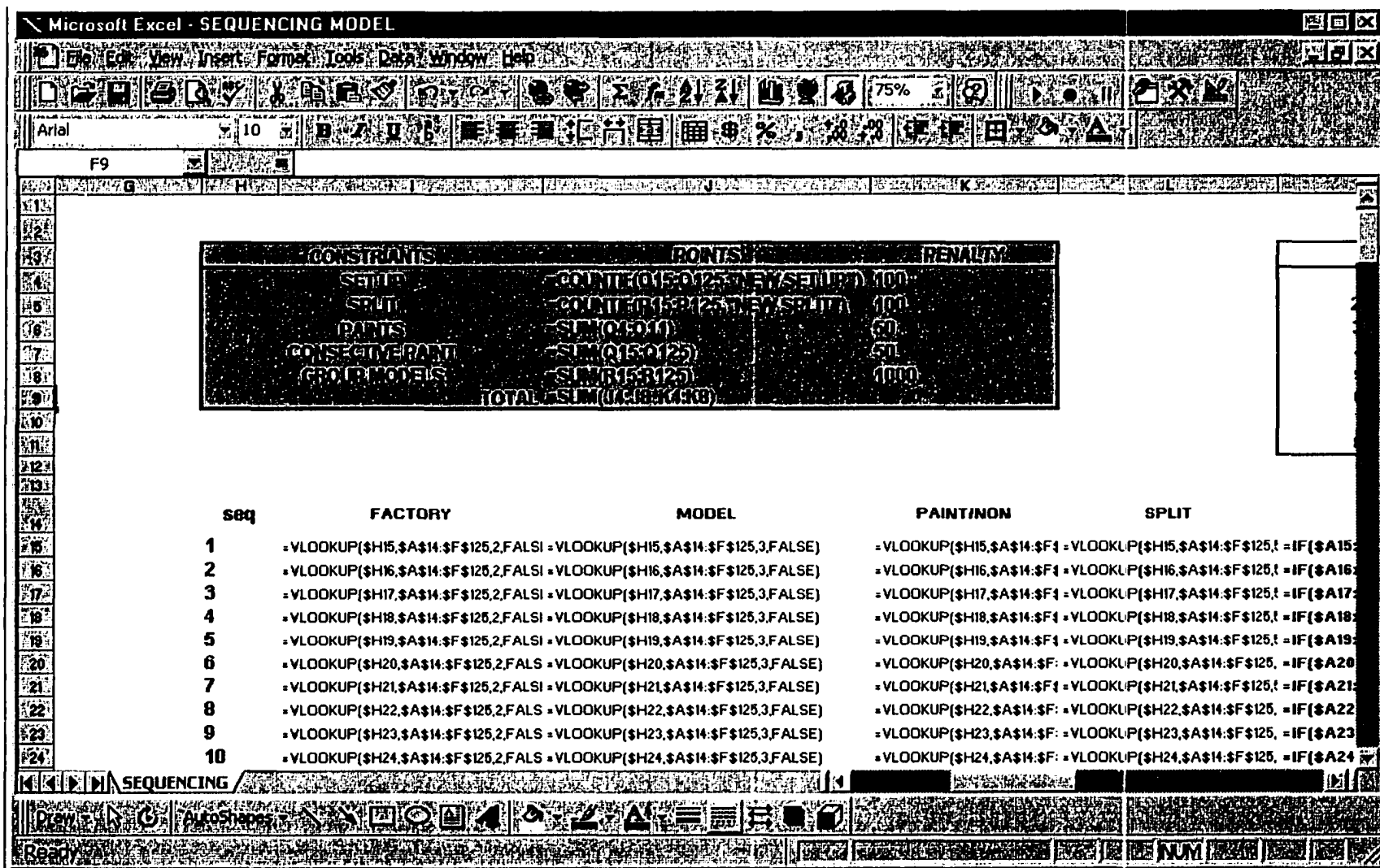


Figure 28. Sequencing tab, calculation of constraint points, with formulas visible in the cells (b).

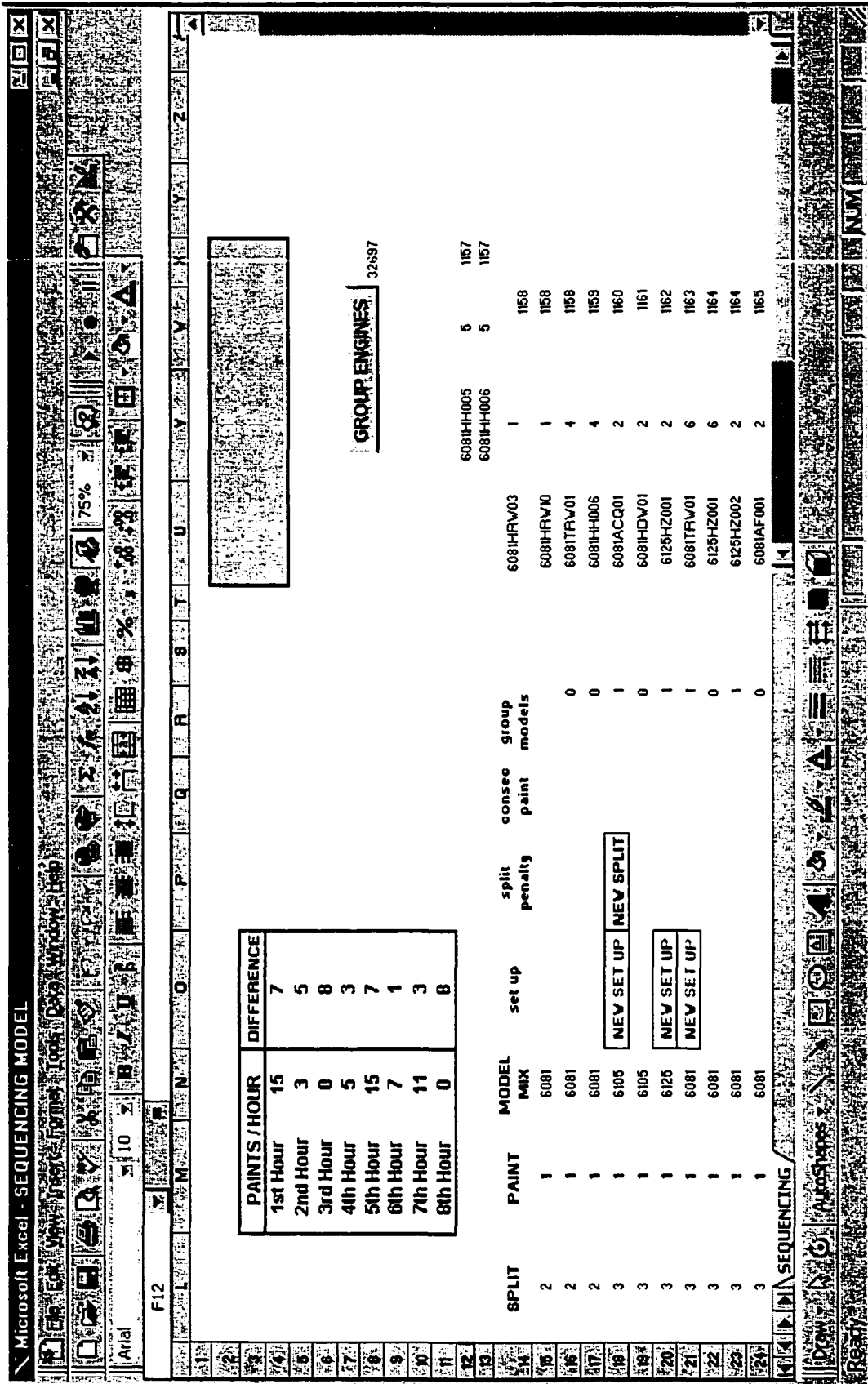


Figure 29. Sequencing tab, computation of constraints.

Site Selection

The site selected for this research was an engine manufacturing facility of a midwestern manufacturer of agriculture equipment, which has been employing the latest technology throughout the years. MMAE allocates more than 2% of its gross sales for research and development, indicating the company's commitment to innovation and its desire to stay ahead of its competition.

MMAE completed its first MRP installation in 1979 and has implemented parts of JIT since 1981 (Williams, 1986). By 1986, the company had implemented MRP in all its plants worldwide. JIT was first implemented within MMAE at a facility that produces hay and forage equipment for agricultural use. Considerable improvements, including a 58% reduction in inventories, were reported after implementing parts of the JIT system.

The engine manufacturing plant of MMAE has long been perceived as the focus factory throughout the organization. It was the second plant within MMAE to achieve the ISO 9000 certification. This facility employs traditional (MRP) and contemporary (JIT) manufacturing systems, a condition that serves the purpose of the present research.

The design and development of EMP was initiated in 1973. This facility has 915,000 square feet, 340,000 of which is allocated to the assembly area. EMP began production of diesel engines in February, 1976. The number of engines produced in 1995 was 29,500 including marine, natural gas, and diesel. This volume is made up of 400 series (7.6 and 8.1 liter) and 500 series (10.1 liter) engines. The engines produced at this facility are shipped to internal customers (MMAE agricultural and industrial divisions) and to numerous original equipment manufacturers (OEM). The share of OEM

production has grown from 3% of volume in 1976 to 15% in 1995 and is expected to reach 50% of volume by the year 2005.

EMP provides purchased and manufactured service parts for the engines built at this facility. The service performance level is measured in the following two ways:

- Fill out of the factory to the Parts Distribution Center (PDC)
- Fill from PDC to dealers

The management goal is to fill 100% of all orders from the factory to PDC and 97% from PDC to dealers each month. EMP currently is filling orders from the factory to PDC at 93% and from PDC to dealers at 98%.

Software Selection

Intense reliance on the legacy computer systems has been one of the concerns of MMAE. EMP also relies heavily on legacy computer systems for production planning and control. Many MMAE facilities have begun using Microsoft Excel as a production-planning tool. This usage was a factor in selecting Excel for the research model.

In the new information-driven economy, selecting software to help achieve organizational goals has become more complex than ever before. The selection of Evolver as an optimization tool was based on its price and availability through MMAE. Evolver, an optimization add-on for Microsoft Excel, uses genetic algorithms to solve complex optimization problems in such areas as finance, distribution, scheduling, resource allocation, manufacturing, budgeting, and engineering. Virtually any type of problem that can be modeled in Excel can be solved by Evolver, including previously unsolvable problems. Evolver, which requires no knowledge of programming or genetic

algorithm theory, is available in three versions: standard, professional, and industrial. The professional and industrial versions have increased problem capacities and advanced features, including the Evolver Developer's Kit. As noted in the literature review, genetic algorithms are becoming prevalent as an optimization tool for scheduling problems. Many software vendors offer genetic algorithm-based optimization software, but Evolver by Palaside Inc. was one of the first in the market.

Data Collection

The master scheduler plans production (via Excel) for the fiscal year in monthly time-buckets. Production for each three-month period (current and following two months) is planned in weekly buckets. The master scheduler gives the production in weekly buckets in Excel workbook to the scheduler, who is responsible for the engine line-up for the next 20 days. The scheduler performs the line-up in daily buckets for the next 20 days in the HOST system.

Customer orders are kept in the legacy computer system called Common Worldwide Interfactory System (CWIS). These orders are auto-downloaded into the MRP master schedule. All customers have offset days within the master scheduling process. An offset is the number of production days between the launch and the ship on the assembly line. MRP generates the master schedule in monthly buckets after considering the customer requirement date and number of offset days. Monthly buckets are broken down in weekly buckets when the master scheduler runs a program in the HOST MRP.

The purpose of this research was to develop and evaluate a model that will generate an improved engine schedule and sequence based on CM when compared with the current method. The actual line-up schedule and sequence that were used to build engines for the 100 production days between summer of 1999 and spring of 2000 at EMP were used for the comparison. These data were used in the simulation for the current scheduling and sequencing method (control condition), as well as for the proposed scheduling and sequencing model for optimization (experimental condition). After the scheduling and sequencing optimizations were performed, the results of these optimizations were used in simulation.

In the proposed model, the master scheduler would perform the engine line-up in Excel using the optimization tool Evolver. This line-up would be auto-downloaded in the HOST system. The model is intended to provide EMP's management with the ability to perform what-if analysis in a timely manner.

Statistical Analysis

After the output from the simulation run for both methods, current and proposed, was obtained, statistical analysis was performed. Various statistical tools were used to perform the analysis. The five variables compared and analyzed were as follows:

1. Cycle time of engines for the final assembly line and four downstream processes
2. Queue size in front of four downstream processes after final assembly line
3. Utilization of work centers in the final assembly line and four downstream processes

4. Flow rate of engines through the final assembly line and four downstream processes

5. Total output of engines through final assembly line and four downstream processes

Expected improvements in the five variables of the proposed scheduling and sequencing model are as follows:

1. Reduction in cycle time of engines for the final assembly line and four downstream processes (smaller number is better)

2. Reduction in queue size in front of four downstream processes after final assembly line (smaller number is better)

3. Increase in the utilization percentage of work centers in the final assembly line and four downstream processes (larger number is better)

4. Even flow rate of engines through the final assembly line and four downstream processes

5. Increase in total output of engines through final assembly line and four downstream processes (larger number is better)

Some analysis was performed as part of the simulation output, such as determining minimum and maximum values and total output of engines, but the majority of the analysis was done after assembling the simulation output from both methods, current and proposed. A sample output from the model was used to determine that the data were normally distributed. The statistical tools used to analyze the data included the following: arithmetic averages, minimum and maximum values for each dependent variable, standard deviation, percentage of utilization of work centers, and t-tests.

Model Validation

According to a key expert in GPSS/H and PROOF simulation modeling at the corporate office of MMAE (G. Rehn, personal communication, [e-mail], December 22, 1999), simulations at MMAE have proved highly valid although the number of validations of simulations has been limited. Two formal validations in the 1980s and one informal in the early 1990s have been made. A validation of a simulation of one of MMAE's plant that manufacture cotton pickers for its 2X conveyor system in the early 1980s found that in areas primarily equipment oriented, the correlation between the method in use and the simulated method was high (98%) but in the manpower-related instances, the confidence level was in the low 90s.

In 1988 a formal model validation was done for a simulation for the AGV assembly system in conjunction with the test acceptance. A statistician concluded that there was no significant difference between the simulation model and the behavior of the actual system. He recommended that the model be used to predict the effectiveness of future systems because it was quicker and easier to identify tendencies with the model.

In the validation performed in the early 1990s, a simulation model was compared with actual output in order to demonstrate the value of Optimax software. A month's actual line-up at a seeding plant was used as an input for the simulated model. The actual output and the simulated output were so close that no statistical analysis was performed.

Thus in a limited number of cases, model have proved to be highly valid at MMAE. It should also be noted that the key expert at the corporate office of MMAE was consulted whenever questions arose regarding the design and testing of the model.

The proposed model is scheduled to be implemented at the EMP's final assembly line in the spring of 2000. Due to the time constraints for this research, model validation was conducted through computer simulation, using the software GPSS/H and PROOF, products of the Wolverine Software Corporation in Annandale, Virginia. GPSS/H is a simulation language, and PROOF is an animation software used within Excel file format. Excel serves as a user interface to the line-up model. It contains the launch sequence, shipping schedule, initial inventory, process cycle times, operating schedule by department (number of shifts in operation, etc.), number of operators/shift, and some equipment parameters such as number of load bars in the system. All these items are data-driven variables or inputs to the model. The parameters, once specified, define a specific simulation scenario to be tested through the model. An Excel macro that captures all the data defined in the Excel and creates various text files in a specific format understood by the simulation code was used.

GPSS/H, a simulation language, was used to write a model of the line-up alternatives. The simulation code accounts for all the resources, capacities, and process logic of the system. The model reads in all the data provided by the Excel interface and uses those conditions to execute all the "process" rules defined in the simulation code that represents the process flow of engines from the final assembly line to ship. At the end of the simulation run, the model generates output reports describing production volumes attained, operator utilization, equipment utilization, inventory levels, and total process cycle time, which is a function of the all the individual process cycle times and the dynamic delays associated with resource availability. The model also "writes" the graphic commands to a file to drive an animation depiction of the simulation test.

PROOF, the animation software, post-processes the graphic commands written by the simulation model. The result depicts the flow of the processes and illustrates the overall flow of the system. The animation first highlights any process issues and promotes understanding of the overall system. The related GPSS/H output then serves to quantify the performance. PROOF can also be used for some of the input data to the simulation, most often to show the configuration of the layout being tested. PROOF can translate DXF file formats from CAD programs and use them in the animation. Many of the layout capacities and conveyor speeds and times come from the layout of the system, once it has been translated into PROOF.

An output file in plain text format is created each time a simulation run is performed and the outcome is illustrated in the output file. A copy of the output is attached in Appendix A.

Summary

This research was designed to identify production planning and control (PP&C) constraints at EMP and to develop and validate scheduling and sequencing model based on these constraints. The site for the research was an engine manufacturing plant of a midwestern manufacturer of agriculture equipment. The plant employs both traditional and contemporary manufacturing systems.

The independent variable in the research design is the method of scheduling and sequencing, the experimental condition being the proposed model and the control condition, the current scheduling and sequencing method. Dependent variables are cycle time, queue time, utilization of work centers, flow of engines, and total output of engines.

The software selected for the research model was Excel, with Evolver as an optimization tool.

A two-part model, based on constraints management philosophy of production planning and control methods, was developed by the researcher in Excel, one part for scheduling and the other for sequencing. Using data from the 100 production days during the fall of 1999 and the spring of 2000, simulations for the current scheduling and sequencing method and for the proposed model were compared. Output from the simulations for the experimental and control conditions was statistically analyzed, using arithmetic averages, minimum and maximum values for each dependent variable, standard deviation, percentage of utilization of work centers, and t-tests.

CHAPTER IV

SIMULATION RESULTS AND DISCUSSION

As stated earlier, the purpose of this research was to develop and evaluate a model that would generate an improved engine schedule and sequence based on constraint management (CM) in comparison to the currently used method. The actual lineup schedule and sequence that were used to build engines for the 100 production days between summer of 1999 and spring of 2000 at EMP were used for the comparison. Dates for the data were selected after review by the key expert in the area of production planning and control at EMP (D. Eck, personal communication, April 24, 2000). The actual dates for the data used in this study are listed in Table 3. These data were used in the simulation for the current scheduling and sequencing method (control condition), as well as for the proposed scheduling and sequencing model for optimization (experimental condition).

The simulation was developed by the key expert in GPSS/H and PROOF simulation modeling at the corporate office of MMAE. GPSS/H is a simulation language, and PROOF is an animation software used within Excel file format. Excel serves as a user interface to the lineup model. It contains the launch sequence, shipping schedule, initial inventory, process cycle times, operating schedule by department (number of shifts in operation, etc.), number of operators/shift, and some equipment parameters such as number of load bars in the system (see Figures 31 and 32). All these items are data-driven variables or inputs to the model. After specifying the parameters, each simulation run was conducted with a specific simulation number. All the parameters maintained the same values for the 200 simulation runs. The only values

Table 3

Line-up Dates and Test Numbers

Line-up date	Test no.	Line-up date	Test no.	Line-up date	Test no.
6/21/1999	1	9/15/1999	35	11/23/1999	68
6/22/1999	2	9/16/1999	36	11/24/1999	69
6/23/1999	3	9/17/1999	37	11/25/1999	70
6/24/1999	4	9/20/1999	38	11/30/1999	71
6/25/1999	5	9/21/1999	39	12/1/1999	72
6/28/1999	6	9/22/1999	40	12/2/1999	73
6/29/1999	7	9/23/1999	41	12/3/1999	74
6/30/1999	8	10/4/1999	42	12/6/1999	75
7/1/1999	9	10/5/1999	43	12/7/1999	76
7/2/1999	10	10/6/1999	44	12/8/1999	77
7/6/1999	11	10/7/1999	45	12/9/1999	78
7/7/1999	12	10/8/1999	46	12/10/1999	79
8/9/1999	13	10/11/1999	47	12/13/1999	80
8/10/1999	14	10/12/1999	48	12/14/1999	81
8/11/1999	15	10/13/1999	49	12/15/1999	82
8/13/1999	16	10/14/1999	50	12/16/1999	83
8/16/1999	17	10/15/1999	51	12/17/1999	84
8/17/1999	18	11/1/1999	52	12/20/1999	85
8/18/1999	19	11/2/1999	53	12/21/1999	86
8/19/1999	20	11/3/1999	54	12/22/1999	87
8/20/1999	21	11/4/1999	55	1/6/2000	88
8/23/1999	22	11/5/1999	56	1/7/2000	89
8/24/1999	23	11/8/1999	57	1/10/2000	90
8/30/1999	24	11/9/1999	58	1/11/2000	91
8/31/1999	25	11/10/1999	59	1/12/2000	92
9/1/1999	26	11/11/1999	60	1/13/2000	93
9/2/1999	27	11/12/1999	61	1/14/2000	94
9/3/1999	28	11/15/1999	62	1/18/2000	95
9/7/1999	29	11/16/1999	63	1/19/2000	96
9/8/1999	30	11/17/1999	64	1/20/2000	97
9/9/1999	31	11/18/1999	65	1/21/2000	98
9/10/1999	32	11/19/1999	66	1/24/2000	99
9/13/1999	33	11/22/1999	67	1/25/2000	100
9/14/1999	34				

Microsoft Excel - Scheduling and Sequencing Simulation

File Edit View Insert Format Tools Data Window Help

Avail 10 100%

J15

Scheduling and Sequencing Simulation

Test # G1
Description: Control Group Test # 1

J-Hook Production Rate:
 1st Shift: 130
 2nd Shift: 0
 3rd Shift: 0

Unit/Shift Line Speed:
 4.00 ipm
 0.00 ipm
 0.00 ipm

Simulation Days: 1
 Simulation Start-Up Time: 7:00 AM

Shift Start-Up Allowance:
 Shift Clean-Up Allowance:
 # Load bars-Delivery Conv.: 160
 # J-Hook Carriers: 42
 Max Test Loop Count-Inbound: 10
 Max Test Loop Count-Outbound: 40
 Custom Trim Transit Count: 17

Buttons: Create Simulation Data, Run Simulation, View Animation, Preview Output

Figure 31. Excel interface for the simulation run, top section.

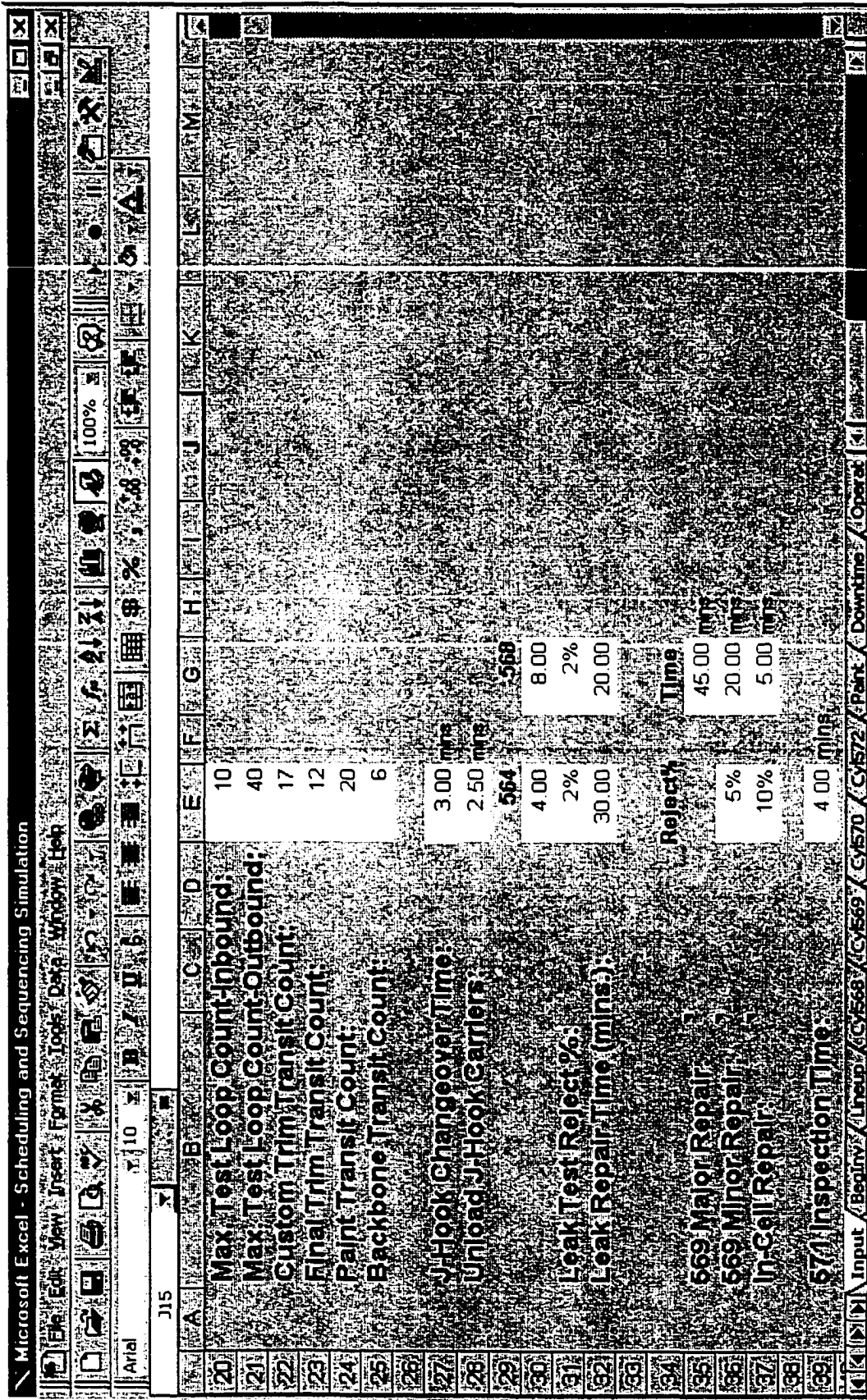


Figure 32. Excel interface for the simulation run, bottom section.

that changed were the lineup sequences. An Excel macro captured all the data defined in the Excel interface and created various text files in a specific format understood by the simulation code.

GPSS/H was used to write a model of the lineup alternatives. The simulation code (see Appendix B) accounts for all the resources, capacities, and process logic of the system. The model reads in all the data provided by the Excel interface and uses those conditions to execute all the “process” rules defined in the simulation code that represents the process flow of engines from the final assembly line to ship. At the end of the simulation run, the model generates output reports describing production volumes attained, operator utilization, equipment utilization, inventory levels, and total process cycle time, which is a function of all the individual process cycle times and the dynamic delays associated with resource availability. The model also “writes” the graphic commands to a file to drive an animation depiction of the simulation test. (See Appendix C for a snapshot of animation depiction of simulation run.)

PROOF post-processes the graphic commands written by the simulation model. The result depicts the flow of the processes and illustrates the overall flow of the system. The animation first highlights any process issues and promotes understanding of the overall system. The related GPSS/H output then serves to quantify the performance. PROOF can also be used for some of the input data to the simulation, most often to show the configuration of the layout being tested. PROOF can translate DXF file formats from CAD programs and use them in the animation. Many of the layout capacities and conveyor speeds and times come from the layout of the system, once it has been translated into PROOF.

An output file in plain text format is created each time a simulation run is performed, and the outcome is illustrated in the output file. A copy of the output appears in Appendix A.

The research questions stated in chapter I were the bases for this experimental study. These questions are reiterated below for quick reference.

1. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the cycle time for the final assembly line and four downstream processes at an engine manufacturing plant (EMP) of a midwestern manufacturer of agricultural equipment (MMAE)?
2. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the queue size for the final assembly line and four downstream processes at EMP?
3. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the utilization of work centers in the final assembly line and four downstream processes at EMP?
4. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the flow rate of engines through the final assembly line and four downstream processes at EMP?
5. What is the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on the total output of engines through the final assembly line and four downstream processes at EMP?

Various statistical tools were used to analyze the output from the simulation run for both methods, current and proposed. The five variables compared and analyzed were as follows:

1. Cycle time of engines for the final assembly line and four downstream processes
2. Queue size in front of four downstream processes after final assembly line
3. Utilization of work centers in the final assembly line and four downstream processes
4. Flow rate of engines through the final assembly line and four downstream processes
5. Total output of engines through the final assembly line and four downstream processes

Expected improvements in the five variables of the proposed scheduling and sequencing model were as follows:

1. Reduction in cycle time of engines for the final assembly line and four downstream processes (smaller number is better)
2. Reduction in queue size in front of four downstream processes after final assembly line (smaller number is better)
3. Increase in the utilization percentage of work centers in the final assembly line and four downstream processes (larger number is better)
4. Even flow rate of engines through the final assembly line and four downstream processes

5. Increase in total output of engines through final assembly line and four downstream processes (larger number is better)

Cycle Time

The results of the simulations indicated very little reduction in average cycle time after 100 runs for the control condition and 100 simulation runs for the experimental condition (see Figure 33 for a comparison of each condition's cycle time for the 100 simulation runs.) The average cycle time for the control condition was 9.04 hours with a standard deviation of 1.14 and average cycle time for the experimental condition was 8.97 hours with a standard deviation of 1.01. Results of t -test indicated the following values: t -value = 1.24, $df = 99$, and two-tailed significance = .219. Thus, the difference between the control condition and the experimental condition results was not statistically significant, with an alpha level of .05.

A smaller standard deviation value for the experimental condition indicates that there is less variation in cycle time. In the manufacturing environment, less variability is better. One reason for a less-than-expected reduction in cycle time could be the increased production of painted engines for the experimental condition, which requires additional processes. (See Figure 33, which shows a spike for Test 51, a day when all engines built were painted.) Cycle time was reduced for 48 out of 100 days for the experimental condition versus 39 days for the control condition; for 13 days, cycle times were identical for both conditions (see Table 4).

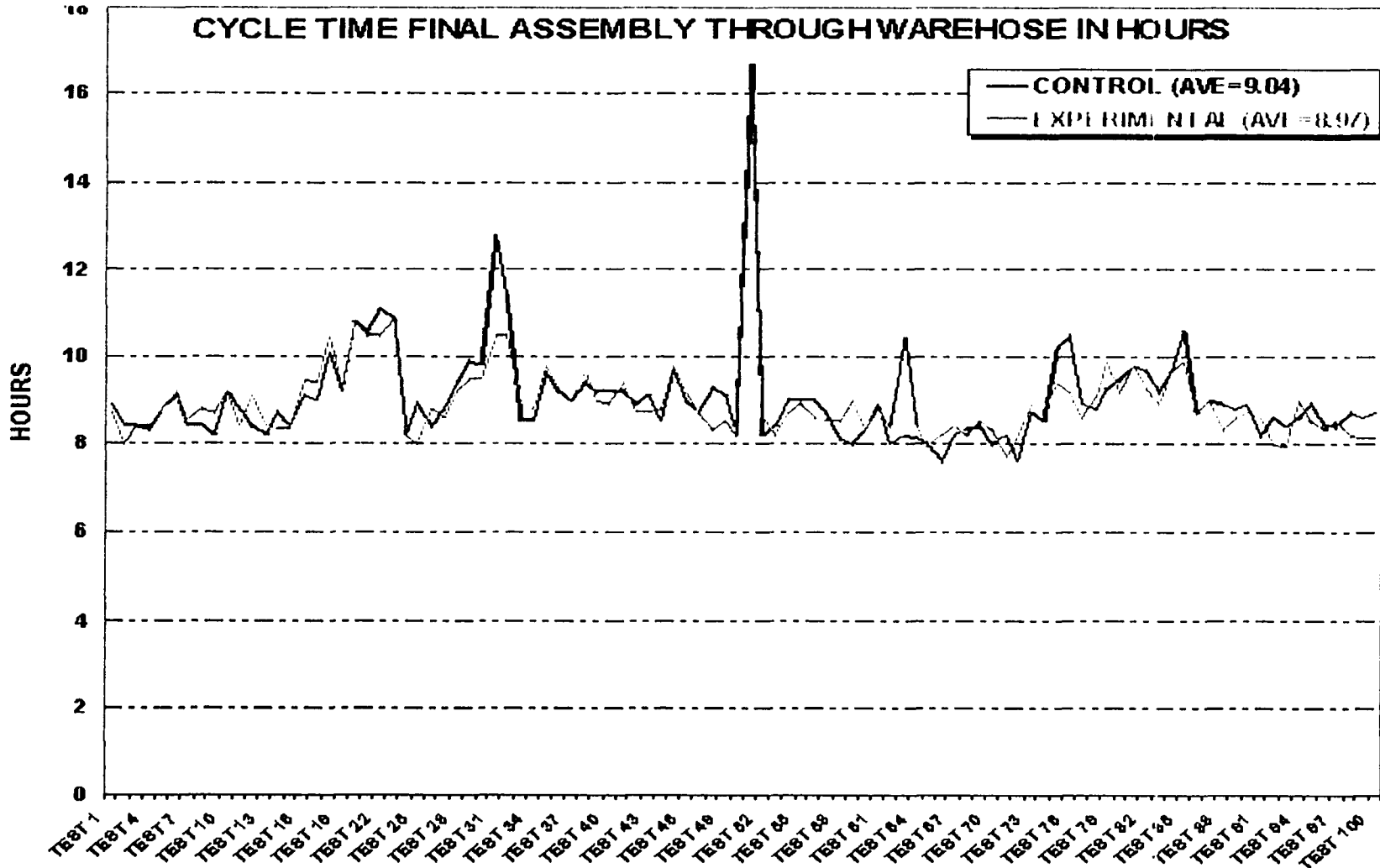


Figure 33. Cycle time final assembly through warehouse in hours. The spike for Test 51 is due to the fact that on that particular day, all of the engines built were painted.

Table 4

Comparison Data for Cycle Time

Measures	Control	Experimental
Average (minutes)	9.04	8.97
SD	1.14	1.01
No. of days of reduced cycle time	39.00	48.00

Queue Size

The results of the simulations indicated very little reduction in queue size after 100 runs for the control condition and 100 simulation runs for the experimental condition. (See Figure 34 for a comparison of the queue size of each condition for the 100 simulation runs.) The average queue size for the control condition was 110.27 engines with a standard deviation of 2.45, and the average queue size for the experimental condition was 110.12 engines with a standard deviation of 2.29. Results of t -test indicated the following values: t -value = 0.54, df = 99, and two-tailed significance = .588. Since the value of two-tailed significance was greater than .05, the difference between results for the control and the experimental conditions was not statistically significant with an alpha level of .05.

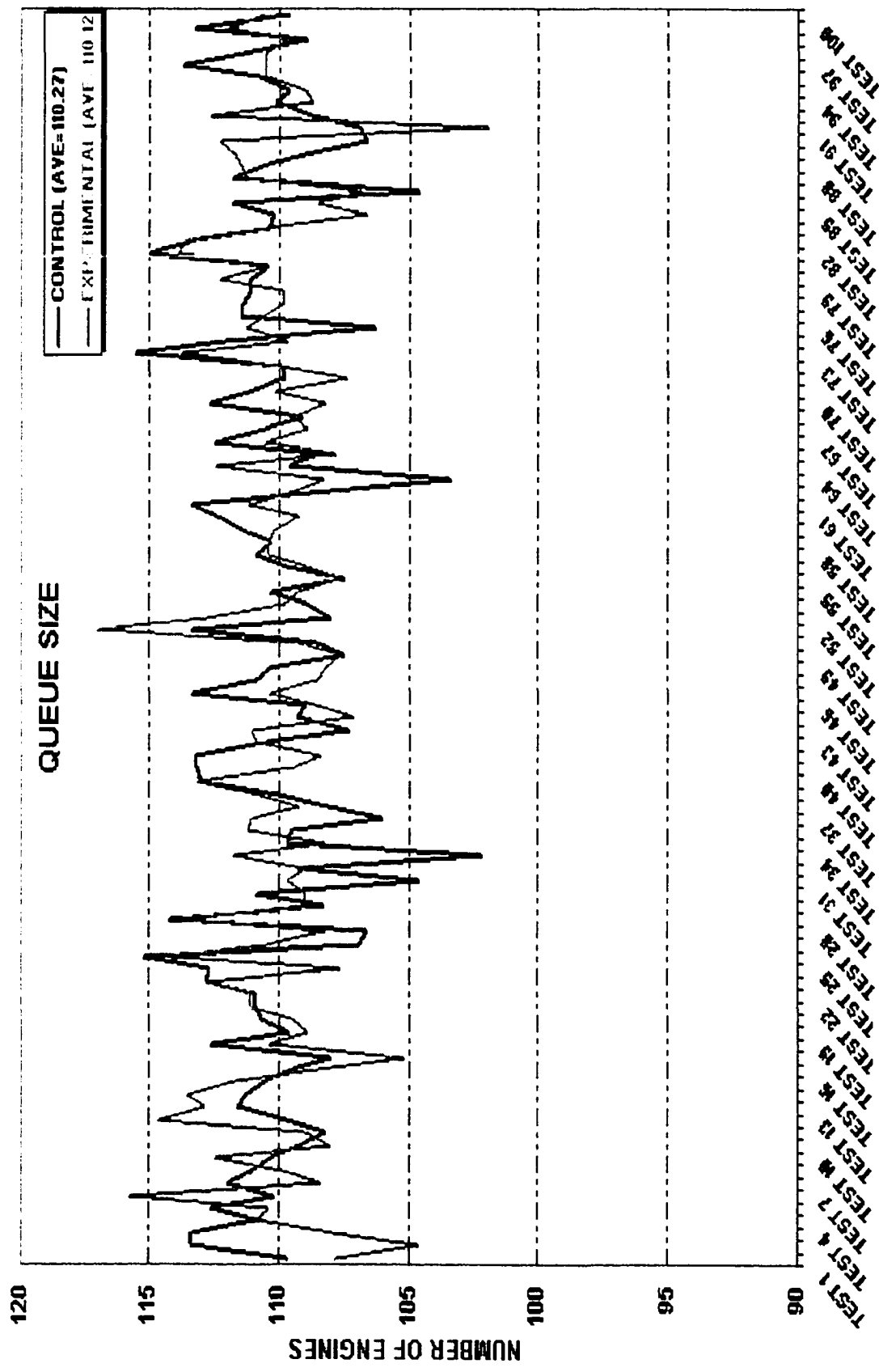


Figure 34. Queue size.

Again a slightly smaller standard deviation value for the experimental condition indicates less variability in the system. Performance in the control condition was better for 44 days and in the experimental condition on 53 days; for the remaining 3 of 100 days, both performed the same (see Table 5). Improvements in queue sizes were observed during the simulation runs for the experimental condition. For the control condition, several times there was “feast or famine” in the queues during daily runs, but data were collected only for average queue sizes. The experimental condition demonstrated uniform queue size throughout the daily simulation runs. A uniform queue size throughout the day is preferred over a queue of wide variability.

Table 5

Comparison Data for Queue Size

Measures	Control	Experimental
Average	110.27	110.12
SD	2.45	2.29
No. of days of reduced queue size	44.00	53.00

Utilization of Work Centers

The results of the simulations indicated improvement in utilization of work centers after 100 runs for the control condition and 100 simulation runs for the experimental condition. (See Figure 35 for a comparison of the control condition and the experimental condition for utilization of work centers for the 100 simulation runs.) The average utilization for the control condition was 41.33% with a standard deviation of 4.22, and the average utilization for the experimental condition was 42.25% with a standard deviation of 3.95. Results of the t -test indicated the following values: t -value = 3.72, df = 99, and two-tailed significance = .000. The difference between results for the control and the experimental conditions was statistically significant, with an alpha level of .05.

The utilization of work centers of test cells, custom trim, paint, and final trim was recorded and measured. Since the final assembly line was a computer controlled line, utilization of work centers was not recorded. Various operators were assigned to more than one work center, but measurements were recorded for the utilization of centers not for the utilization of operators. Total utilization for the four downstream processes of the experimental condition was increased by 2.23%. Utilization of work centers in the four downstream processes for the control condition is presented in Table 6 and for the experimental condition in Table 7.

Performance in the control condition was better than that in the experimental condition on 35 days, and performance for the experimental condition was better on 64 days; for the remaining day, both performed the same (see Table 8).

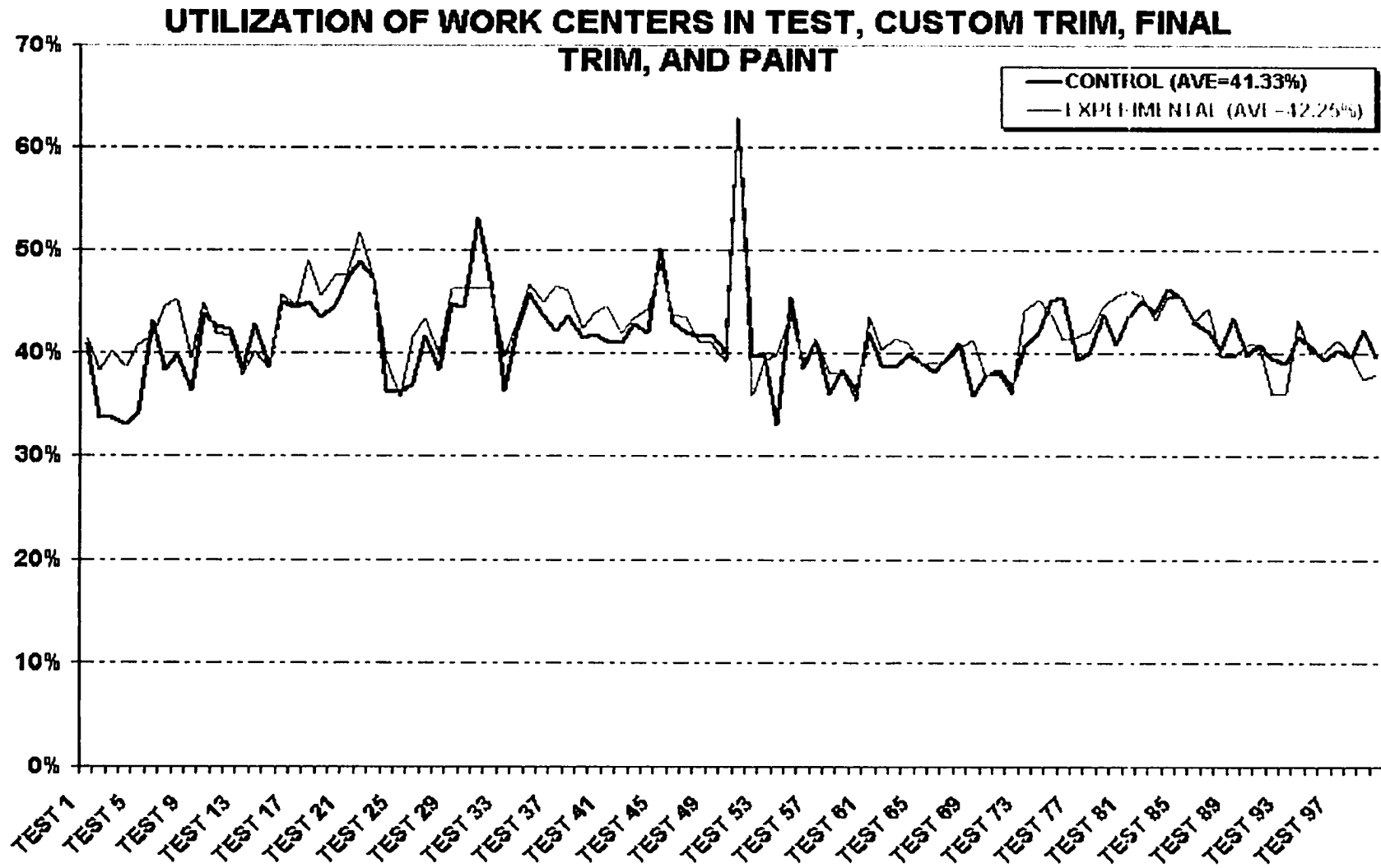


Figure 35. Utilization of work centers in test cells, custom trim, final trim, and paint. As noted the spike for Test 51 is due to the fact that on that particular day, all of the engines built were painted

Table 6

Utilization of Work Centers for the Control Condition

Work centers	Average (%)	SD (%)
Test cells	50.23	3.04
Custom trim	33.43	8.04
Final trim	39.67	2.95
Paint	42.00	8.42
TOTAL	41.33	4.22

Table 7

Utilization of Work Centers for the Experimental Condition

Work centers	Average (%)	SD (%)
Test cells	50.58	2.55
Custom trim	34.44	7.75
Final trim	40.18	3.03
Paint	43.80	7.75
TOTAL	42.25	3.95

Table 8

Comparison Data for Utilization of Work Centers

Measures	Control	Experimental
Average	41.33%	42.25%
SD	4.22	3.95
No. of days of increased total utiliz.	35.00	64.00

Because paint was thought to be the constraint of the system, the results for paint utilization are discussed separately. (See Figure 36 for a comparison of the control condition and the experimental condition for utilization of work centers in paint.) Paint utilization increased for the experimental condition, as expected, but the increase was not statistically significant. The average utilization of work centers in paint for the control and the experimental conditions was 41.99% and 43.80%, respectively. Performance in the control condition was better than that in the experimental condition on 31 days, and performance for the experimental condition was better on 68 days; for the remaining day, both performed the same (see Table 9).

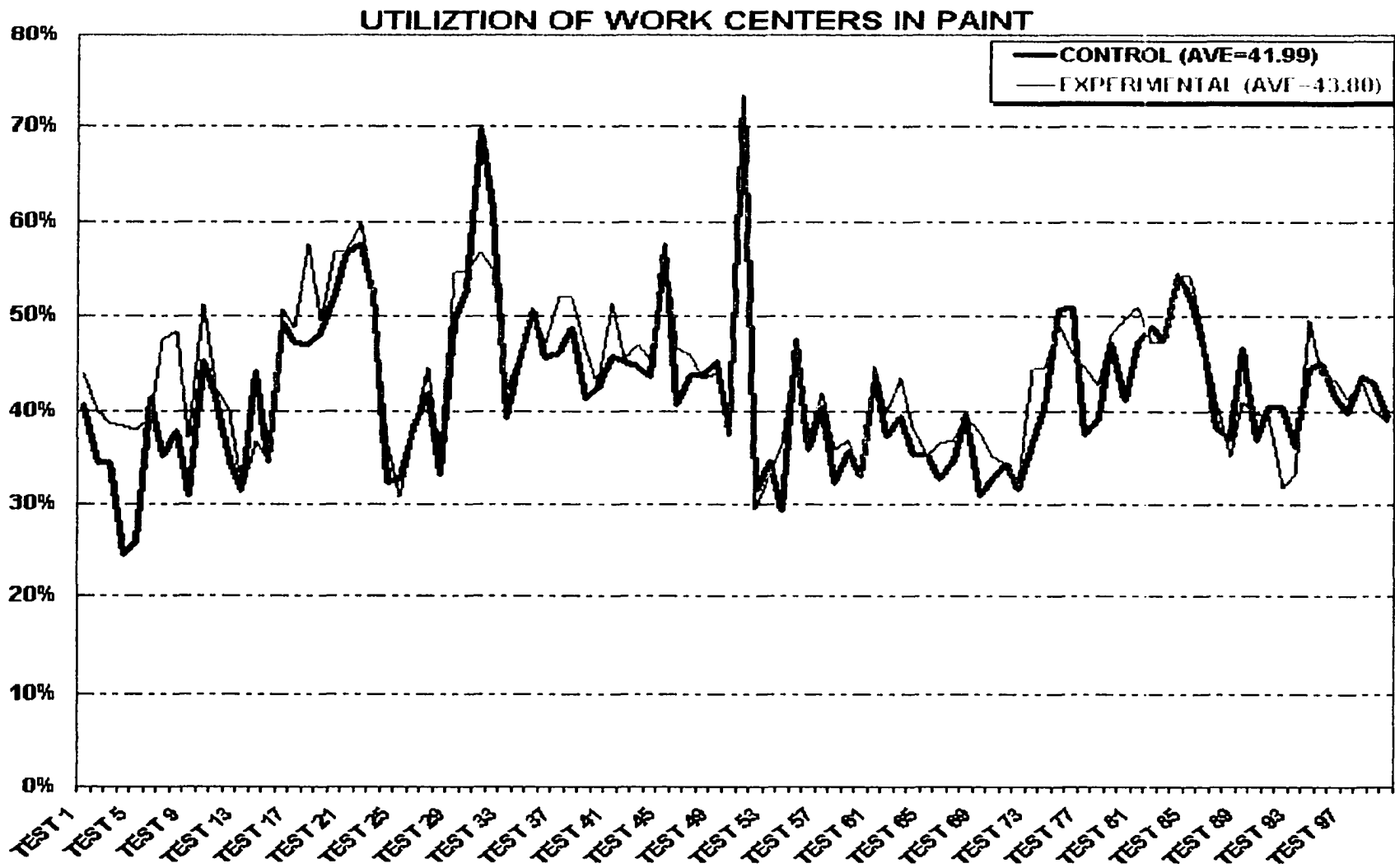


Figure 36. Utilization of work centers in paint. Results from Test 51 were atypical because all the engines built on that day were painted, a process requiring more time.

Table 9

Comparison Data for Paint Utilization

Measures	Control	Experimental
Average	41.99%	43.80%
SD	8.42	7.75
No. of days of increased paint utiliz.	31.00	68.00

Flow Rate of Engines

A better, more even flow of engines through the final assembly line (j-hook) and four downstream processes (test cells, custom trim, final trim, and paint) was the anticipated improvement for the experimental condition, but this was not achieved. Tables 10 and 11 present average and standard deviations of flow rates of engines in minutes for the control and the experimental conditions, respectively. Because paint was considered to be the constraint of the system, special attention was paid to this operation's flow rate. However, data gathered from both groups indicated that the custom trim operation is the constraint. For the control condition simulation run, it took 16.13 minutes to process an engine in custom trim versus 15.90 minutes in paint. For the experimental condition simulation run the data indicated similar results, 15.56 minutes for each engine in the custom trim operation versus 15.31 minutes in paint. Even though the difference in minutes between custom trim and paint was very minimal, it was surprising nonetheless to find out that another operation might become the bottleneck.

Table 10

Flow Rate of Engines for the Control Condition (Minutes/Engine)

Processes	Average	SD
J-hook	4.21	0.23
Test cells	11.26	0.66
Custom trim	16.13	3.45
Final trim	10.85	1.87
Paint	15.90	3.73
TOTAL	58.35	

Table 11

Flow Rate of Engines for the Experimental Condition (Minutes/Engine)

Processes	Average	SD
J-hook	4.18	0.10
Test cells	11.66	4.78
Custom trim	15.56	3.11
Final trim	10.47	0.93
Paint	15.31	3.05
TOTAL	57.18	

The average standard deviation of flow rate of engines in minutes for the five processes for the control and experimental conditions was 2.60 and 2.59, respectively. The number of days performance in the control condition was better than that in the experimental condition were 49, and the number of days performance in the experimental condition was better was 50; for the remaining day, performance was the same for both conditions (see Table 12).

For each condition, custom trim and paint, both of which were more time consuming than other operations, were reduced in cycle times, thereby evening the flow. The experimental condition demonstrated a reduction of 3.50% for custom trim and 3.70% for the paint operation. The experimental condition also demonstrated a reduction of 2.00% in total flow minutes versus the control condition flow minutes, but the goal to have a better flow for the five processes was not achieved.

Table 12

Comparison Data for Even Flow

Measure	Control	Experimental
Average	2.60	2.59
SD	0.23	0.22
No. of days of better even flow	49.00	50.00

Total Output of Engines

Simulation results indicated an increase in the total number of engines processed in the system after 100 runs for the control condition and 100 simulation runs for the experimental condition (see Figure 37). The average number of engines processed each day in the final assembly line and four downstream processes was 467.27 for the control condition with a standard deviation of 49.43. The comparative figure for the experimental condition was 478.07 engines with a standard deviation of 41.92. The smaller standard deviation number for the experimental condition indicates less variability compared with the control condition. The number of days performance in the control condition was better than in the experimental condition was 37, and the number of days performance in the experimental condition was better was 62; for the remaining day, performance was the same for both conditions (see Table 13). Results of the t -test indicated the following values: t -value = 3.18, $df = 99$, and two-tailed significance = .002, with an alpha level of .05. Thus, the difference between the control condition and the experimental condition results was statistically significant. Once again, it should be noted that the data from Test 51, a day when all engines built were painted, a process requiring more time, were atypical.

On average the total number of engines processed in the system increased by 10.8 per day in the experimental condition. The experimental condition produced more engines on 62 out of 100 days, versus 37 days for the control condition. One-day total output was the same for both conditions. Averages with standard deviations for the final assembly line (j-hook) and the four downstream processes are presented in Tables 14 and 15 for the control and experimental conditions, respectively.

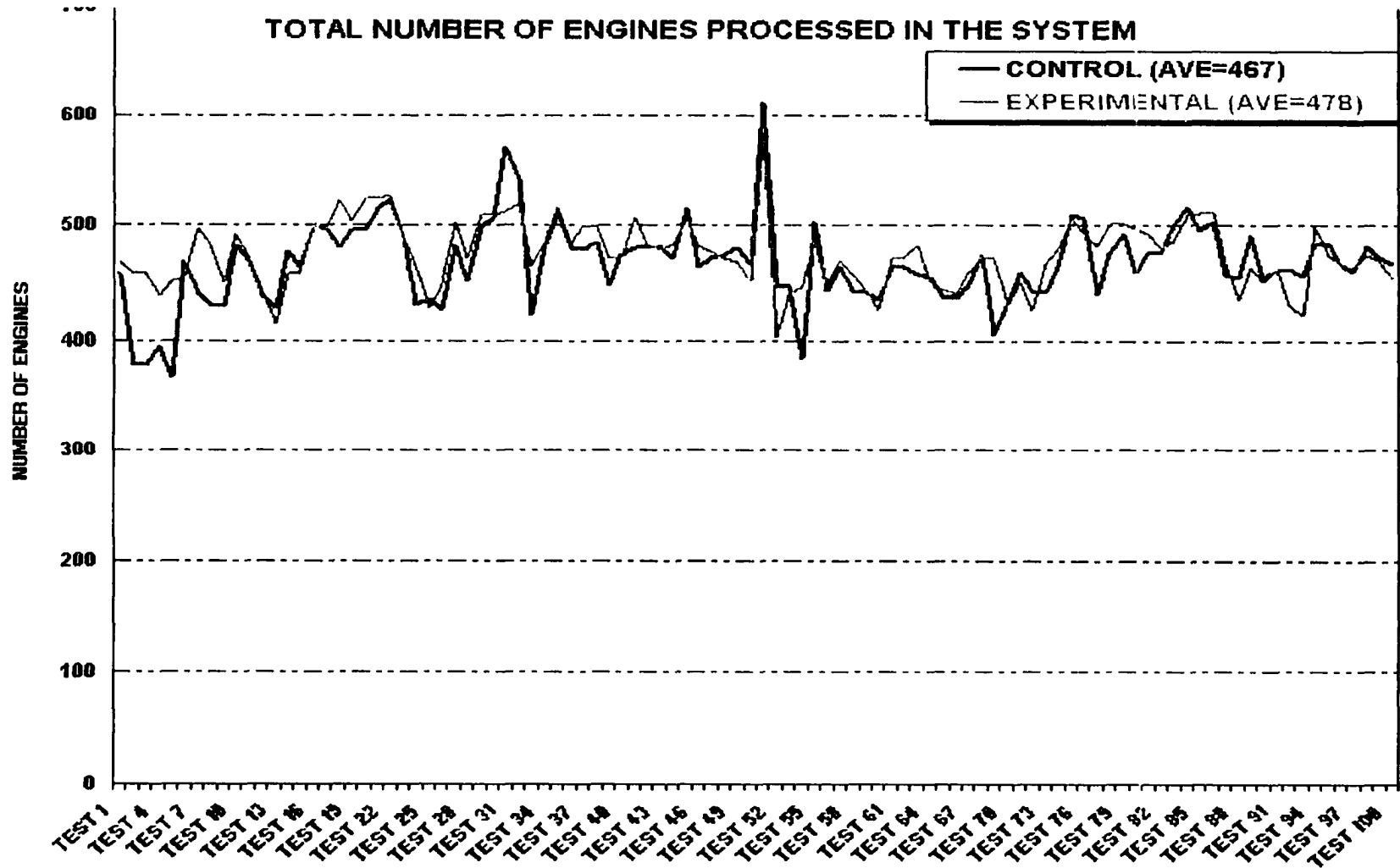


Figure 37. Total engine processed in the system. The spike for Test 51 represents the atypical situation of all engines built that day being painted.

Table 13

Comparison Data for Total Output

Measures	Control	Experimental
Average	467.27	478.07
SD	49.43	41.91
No. of days of increased total output	37.00	62.00

Because paint was thought to be the bottleneck of the system, special attention was paid to this operation. The average number of engines painted for the control condition was 71.88 with a standard deviation of 15.58, and the average number of engines painted for the experimental condition was 74.92 engines with a standard deviation of 13.99. Results of the t -test indicated the following values: t -value = 4.03, df = 99, and two-tailed significance = .000 with an alpha level of .05. Thus the difference between the results for the control and the experimental conditions was statistically significant.

Paint output was increased by 3.04 units or 4.23%. On average, more engines were painted in the experimental condition, on 61 out of 100 days, versus 18 days for the control condition. On 21 days, output was the same for both groups. (See Figure 38 for a comparison of paint production in each condition for the 100 simulation runs.)

Table 14

Number of Engines Processed in the System (Control Condition)

Processes	Average	SD
J-hook	105.04	4.69
Test cells	110.83	6.32
Custom trim	72.58	15.54
Final trim	106.94	7.31
Paint	71.88	15.58
TOTAL	467.27	49.43

Table 15

Number of Engines Processed in the System (Experimental Condition)

Processes	Average	SD
J-hook	105.55	2.39
Test cells	114.41	5.31
Custom trim	74.86	15.02
Final trim	108.33	5.21
Paint	74.92	13.99
TOTAL	478.07	41.92

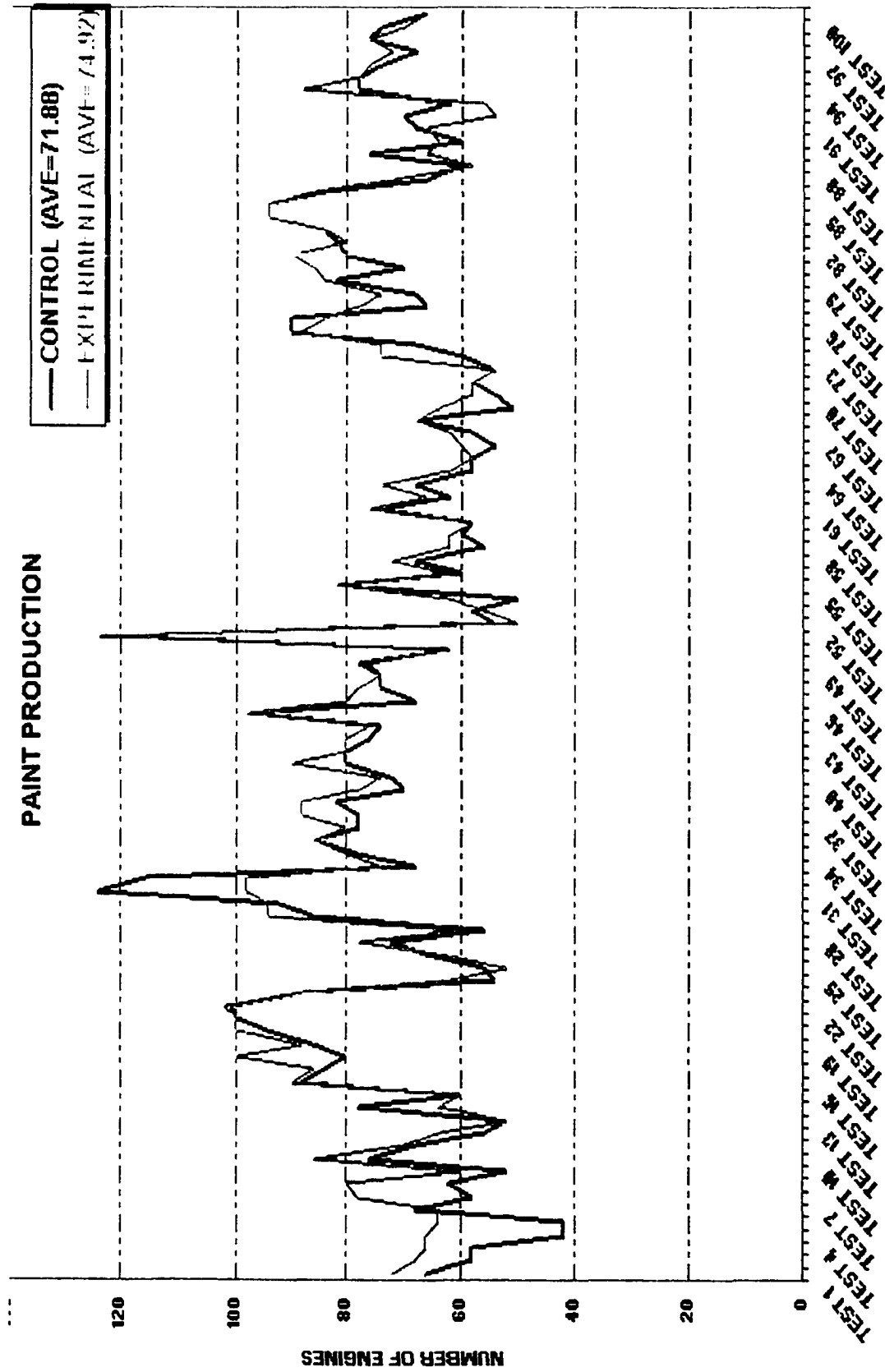


Figure 38. Paint output for the control and the experimental conditions.

A smaller standard deviation for both total output and paint production indicated less variability in the system for the experimental condition. As mentioned earlier, a lesser amount of variability is better in the manufacturing environment. The relatively small standard deviation for total output and paint production indicates more consistent production was achieved for the experimental condition.

CHAPTER V

SUMMARY, CONCLUSIONS, AND RECOMMENDATIONS

Summary

This research was an extension of a previous unpublished study, which investigated the PP&C methods being used at a midwestern manufacturing organization involved in the production of agricultural equipment. The current research study identified the constraints inherent in the production planning and control system and then developed and validated a master production scheduling and sequencing optimization model based on constraints management and utilizing genetic algorithms.

As noted earlier, production planning and control are among the most critical activities in manufacturing. The expected results of this research were to allow manufacturing organizations to maximize the effectiveness of PP&C methods, thereby improving their competitive position in the global economy. To that end, the goal of this research was to develop an optimization model based on constraints management and genetic algorithms to address the constraints in the PP&C methods being used at the factory under study. Published reports of the application of CM in a line assembly environment have been limited. However, according to the research literature, CM has been applied successfully in the job shop environment. In the current research, only three of the five steps of CM were applied. Although the results for the five variables were not statistically significant, results for the experimental condition were the same or better than those for the control condition. It is important to note that improvements are more difficult to achieve in a line assembly environment because there is much less flexibility than in a job shop environment.

The specific objectives of this research were as follows: (a) identify the system's constraints, (b) develop a scheduling and sequencing model to address the identified constraints, (c) develop and validate the proposed model by simulation, and (d) identify and document improvements attributed to the operational change resulting from the implementation of the optimization model.

The research examined the impact of the master production scheduling and sequencing model based on constraints management and utilizing genetic algorithms on five variables for the final assembly line and four downstream processes at an engine manufacturing plant (EMP) of a midwestern manufacturer of agricultural equipment (MMAE). The variables were cycle time, queue size, utilization of work centers, flow rate of engines, and total output of engines.

A two-part model based on constraints management philosophy of production planning and control methods was developed by the researcher in Excel, one part for scheduling and the other for sequencing. Using data from 100 production days during the fall of 1999 and the spring of 2000, simulations for the current scheduling and sequencing method (the control condition) and for the proposed method (the experimental condition) were compared. Output from the simulations for the experimental and control conditions was statistically analyzed.

Conclusions

In the interpretation of output from the simulation runs, it is important to note that daily simulation runs were discrete in nature. Lineup data for each simulation run were used exclusively for that simulation run only; there was no carryover capacity or other

resources from previous days to be used the next day. If the production of the constraint operation was reduced for some reason, makeup the next day would not be possible because new line-up data would initiate the next day's simulation run.

During the 200 simulations run, the cycle time of engines for the final assembly line and four downstream processes was reduced, but the reduction was not statistically significant. Queue size was also reduced, as expected, but once again, the reduction was not statistically significant. Total utilization of work centers was increased, as expected, and the increase was statistically significant. Improvement for the flow rate of engines was minimal. The total output of engines increased, and the increase was statistically significant.

Every effort was made to simulate the actual manufacturing environment of the EMP. But since simulation models are just abstractions of reality, they cannot completely mirror the real-world system under study (Law & Kelton, 1991). Results from the simulation outputs can provide insight as to how and why performance for the experimental condition and the control condition differed (Guide, 1992). However, the effectiveness of this model cannot be known conclusively until it is properly implemented at EMP in the fall of 2000.

The exact results of this research are only applicable for the EMP if the manufacturing environment replicated in the model still exists. Generalizations of the findings of this research should be made with caution.

Recommendations

The following recommendations for future research are provided in view of the findings of this study:

1. In this research, all simulation parameters (shipping schedule, initial inventory, process cycle times, operating schedule by department, number of shifts in operation, number of operators/shift, number of load bars in the system) were held constant for the control and the experimental conditions, except the line-up sequence. It is recommended that the values for the simulation parameters could be manipulated.
2. This research model was designed for the assembly operation, but a similar model could be developed for the manufacturing environment, particularly repetitive-type operations.
3. Data collection for the variables during the simulation runs was limited in scope. Only averages and minimum and maximum values were collected. Averages do not always paint a complete picture of the situation. For example the researcher observed during the simulation runs for queue size that the number of engines at 8:00 a.m. in front of one process for the control condition was zero and an hour later that number was 15. The average for two hours was 7.5. Queue sizes for the experimental condition simulation during the same time period were 8 and 7 for an average of 7.5. Because only averages were recorded, performance for both conditions appeared to be the same. But in reality, this would not be the case. The experimental condition's results would be preferred because of the consistency of queue size. In the future, simulation data should include different measures, ones that more accurately reflect reality.

4. It is recommended that multiple models could be built, based on different production planning and control strategies (JIT, MRP, etc.), and the results could be compared and analyzed.

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APPENDIX A

Simulation Output (Control Condition)

SCHEDULING AND SEQUENCING MODEL SIMULATION CONTROL CONDITION

TEST: NUMBER 1

INPUT CONDITIONS:

AVG. LINE RATE-1ST:	130.0	ENGINES/SHIFT
AVG. LINE RATE-2ND:	0.0	ENGINES/SHIFT
AVG. LINE RATE-3RD:	0.0	ENGINES/SHIFT
# LOAD BARS - MAIN:	160	
HEAVY REPAIR:	45.0	MINS.
LIGHT REPAIR:	20.0	MINS. @ 5% REJECT RATE
CELL DELAY:	5.0	MINS. @ 10% DELAY RATE
# EFFECTIVE DOCKS:	3	

RESULTS AFTER: 1 SIMULATION DAYS

ENGINE PRODUCTION SUMMARY:

	TOTAL	AVG./DAY
J-HOOK PRODUCTION:	105	105.0
TEST PRODUCTION:	112	112.0
CUSTOM TRIM PRODUCTION:	65	65.0
FINAL TRIM PRODUCTION:	109	109.0
PAINT PRODUCTION:	66	66.0
ENGINE SHIPPED:	131	131.0
TRUCKS SHIPPED:	10	10.0

ENGINE PROCESS SUMMARY:

	AVG.	MAX.	MIN.	CURRENT
# ENGINES IN PROCESS/ J-HOOK TO 572:	53.6	100	28	28
# ENGINES IN 572 (TRUCK GRIDS):	67.8	118	11	95
# TRUCK GRIDS:	5.7	10	-----	7
TOTAL ENGINES AFTER J-HOOK:	121.4	173	83	123
TRUCK DOCK USAGE SUMMARY:	0.3	3	-----	0
PROCESS TIME IN DAYS/ J-HOOK TO 572:	0.4	1.1	0.1	
WAREHOUSE TIME IN DAYS:	0.4	1.0	0.0	
TRUCK LOAD TIME IN DAYS:	0.2	0.6	0.0	
ENGINE FINISH SEQUENCE VARIATION:	0.4	52	-70	

FLOW RATE BY DEPARTMENT:

DEPARTMENT (MINS/ENGINE)	TOTAL PRODUCED	# ENGINES /DAY	#SHIFT /DAY	DAYS/ WEEK	EFFECTIVE MINS./DAY	CALCULATED FLOW RATE
564	105	105.0	1	5	440	4.2
568	17	17.0	2	5	880	51.8
569	112	112.0	3	5	1245	11.1
570	65	65.0	2	5	1120	17.2
571	109	109.0	2	5	1120	10.3
572	131	131.0	1	5	440	3.4

570P	66	66.0	2	5	1120	17.0
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J-HOOK CHANGEOVERS

	TOTAL	AVG./DAY
# CHANGEOVERS:	4	4.0
CHANGEOVER TIME(HOURS):	0.2	0.2
% CHANGEOVER:	3.8 %	----

HOURLY FLOW METER SUMMARY (UNITS/HOUR)

AREA	AVG.	MAX.	MIN.
JHOOK	11.7	17.0	6.0
TEST	7.0	15.0	1.0
CUSTOM TRIM	6.5	13.0	3.0
FINAL TRIM	6.8	12.0	1.0
PAINT	5.5	8.0	2.0

CRITICAL QUEUE SUMMARY

AREA	AVG.	MAX.	MIN.
EMPTY	83.0	90.0	56.0
ATTIC	1.3	11.0	0.0
TEST LOOP	6.4	16.0	0.0
CUSTOM TRIM	4.0	15.0	0.0
FINAL TRIM	10.3	12.0	0.0
PAINT	4.7	14.0	0.0

ENGINE PRODUCTION DETAIL:

DAILY ENGINES SHIPPED:

ENGINE	PRODUCTION DAYS:										TOTAL
	1	2	3	4	5	6	7	8	9	10	
6081HRW03	4	0	0	0	0	0	0	0	0	0	4
6125HRW01	2	0	0	0	0	0	0	0	0	0	2
6125HRW02	2	0	0	0	0	0	0	0	0	0	2
6105HRW01	1	0	0	0	0	0	0	0	0	0	1
6081TRW01	20	0	0	0	0	0	0	0	0	0	20
6081TRW02	18	0	0	0	0	0	0	0	0	0	18
6081HRW01	7	0	0	0	0	0	0	0	0	0	7
6081HRW05	2	0	0	0	0	0	0	0	0	0	2
6081HRW06	2	0	0	0	0	0	0	0	0	0	2
6081HRW07	3	0	0	0	0	0	0	0	0	0	3
6081HRW08	1	0	0	0	0	0	0	0	0	0	1
6125HRW04	4	0	0	0	0	0	0	0	0	0	4
6081HDW01	2	0	0	0	0	0	0	0	0	0	2
6081HDW05	2	0	0	0	0	0	0	0	0	0	2
6081HDW06	2	0	0	0	0	0	0	0	0	0	2
6101AT012	3	0	0	0	0	0	0	0	0	0	3
6101AT010	12	0	0	0	0	0	0	0	0	0	12
6081HH006	3	0	0	0	0	0	0	0	0	0	3
6081TF001	22	0	0	0	0	0	0	0	0	0	22
6081HF001	12	0	0	0	0	0	0	0	0	0	12
6081AF001	7	0	0	0	0	0	0	0	0	0	7
TOTAL	131	0	0	0	0	0	0	0	0	0	131

DAILY TRUCK SHIPMENT BY CUSTOMER:

PRODUCTION DAYS:

CUSTOMER	1	2	3	4	5	6	7	8	9	10	TOTAL
WATERLOO	5	0	0	0	0	0	0	0	0	0	5
DAVENPORT	2	0	0	0	0	0	0	0	0	0	2
HITACHI	1	0	0	0	0	0	0	0	0	0	1
HARVESTER	1	0	0	0	0	0	0	0	0	0	1
OEM	1	0	0	0	0	0	0	0	0	0	1
TOTAL	10	0	0	0	0	0	0	0	0	0	10

ENGINE PROCESS DETAIL:

PROCESS TIME BETWEEN J-HOOK & 572 (IN HOURS):

ENGINE	# COMPLETE	AVG.	MAX.	MIN.
6081HRW03	8	12.1	21.7	2.3
6125HRW01	4	8.6	10.5	6.9
6125HRW02	4	8.7	9.6	7.5
6105HRW01	2	3.7	4.4	3.1
6081TRW01	56	4.5	24.0	1.4
6081TRW02	46	7.0	22.9	2.0
6081HRW01	14	12.4	22.0	2.3
6081HRW05	4	7.6	10.8	4.5
6081HRW06	4	12.4	21.7	2.8
6081HRW07	6	12.8	22.2	2.8
6081HRW08	2	12.5	21.9	3.1
6125HRW04	8	9.6	10.5	8.6
6081HDW01	4	7.3	9.8	4.7
6081HDW05	4	7.9	11.4	4.9
6081HDW06	4	7.4	10.1	5.0
6125ADW70	2	10.3	10.9	9.8
6101AT012	6	11.9	12.2	11.6
6101AT010	24	11.3	13.7	9.0
6081HH006	8	7.8	10.8	4.3
6081TF001	44	10.4	15.3	6.2
6081HF001	24	13.2	26.1	5.2
6081AF001	14	9.8	23.4	5.1
TOTAL:	292	8.9	26.1	1.4

WAREHOUSE TIME (IN HOURS):

ENGINE	# COMPLETE	AVG.	MAX.	MIN.
6081HRW03	8	2.9	4.5	1.7
6125HRW01	2	17.6	18.1	17.1
6125HRW02	2	16.7	17.3	16.2
6105HRW01	1	19.9	19.9	19.9
6081TRW01	40	11.1	21.3	1.4
6081TRW02	36	7.2	18.6	1.1
6081HRW01	14	2.9	4.7	1.2
6081HRW05	4	6.1	11.0	1.3
6081HRW06	4	2.6	3.7	1.8
6081HRW07	6	2.1	3.6	1.1
6081HRW08	2	2.2	3.2	1.2
6125HRW04	4	15.2	15.9	14.5
6081HDW01	4	6.3	11.1	1.3
6081HDW05	4	6.0	11.1	1.3
6081HDW06	4	6.3	11.2	1.4
6101AT012	3	11.1	11.2	10.9
6101AT010	12	13.1	15.2	11.3
6081HH006	6	6.2	11.5	1.1

6081TF001	22	16.6	20.9	11.0
6081HF001	12	19.7	22.5	10.9
6081AF001	7	21.7	23.0	20.2

TOTAL:	197	10.3	23.0	1.1
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TRUCK GRID TIME (AWAITING SHIPMENT) IN HOURS:

CUSTOMER	# COMPLETE	AVG.	MAX.	MIN.
WATERLOO	9	8.1	21.3	1.9
DAVENPORT	4	6.4	11.2	1.6
HITACHI	1	15.2	15.2	15.2
HARVESTER	2	6.5	11.5	1.5
OEM	1	23.0	23.0	23.0

TOTAL:	17	8.8	23.0	1.5
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TRUCK LOAD TIME IN HOURS:

CUSTOMER	# COMPLETE	AVG.	MAX.	MIN.
WATERLOO	9	3.6	14.5	1.1
DAVENPORT	4	5.8	11.0	1.3
DUBUQUE	1	10.9	10.9	10.9
HARVESTER	2	5.7	10.3	1.1
OEM	1	10.9	10.9	10.9

TOTAL:	17	5.3	14.5	1.1
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FINISH SEQUENCE VARIANCE:

ENGINE	# COMPLETE	AVG.	MAX.	MIN.
6081HRW03	8	1.6	15	-12
6125HRW01	4	-2.5	10	-17
6125HRW02	4	-2.7	7	-9
6105HRW01	2	37.5	40	35
6081TRW01	56	19.8	52	-50
6081TRW02	46	9.6	48	-30
6081HRW01	14	-3.3	14	-17
6081HRW05	4	6.0	23	-6
6081HRW06	4	1.0	15	-11
6081HRW07	6	0.2	15	-11
6081HRW08	2	3.0	14	-8
6125HRW04	8	-9.8	-5	-17
6081HDW01	4	1.3	16	-14
6081HDW05	4	-4.2	16	-16
6081HDW06	4	1.5	19	-13
6125ADW70	2	-13.5	-11	-16
6101AT012	6	-20.8	-18	-22
6101AT010	24	-17.0	-3	-39
6081HH006	8	3.1	17	-13
6081TF001	44	-19.4	15	-59
6081HF001	24	-4.2	32	-70
6081AF001	14	6.3	26	-10

TOTAL:	292	0.4	52	-70
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TECHNICIAN PERFORMANCE BY DEPARTMENT

DEPT: 568

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
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BBTRIM	1	46	4.5	47.3 %
BBTRIM1	1	46	4.5	47.3 %
LREPAIR	1	3	20.0	13.6 %
LEAKTEST2	1	18	7.6	30.9 %
BBTRIM	2	1	0.0	0.0 %
BBTRIM1	2	1	0.0	0.0 %
LREPAIR	2	1	0.0	0.0 %
LEAKTEST2	2	1	0.0	0.0 %

DEPT: 569

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
TEST5	1	50	7.9	95.0 %
TEST7	1	46	7.8	86.1 %
TEST9	1	43	7.6	79.0 %
TEST11	1	38	7.8	71.4 %
RETORQ1	1	74	3.6	64.1 %
RETORQ2	1	7	3.4	4.0 %
REPAIR1	1	8	37.1	71.5 %
REPAIR2	1	6	27.6	40.0 %
REPAIR3	1	5	26.0	31.3 %
TEST5	2	23	7.3	40.4 %
TEST7	2	19	7.4	33.9 %
TEST9	2	20	7.1	34.2 %
TEST11	2	21	7.3	36.8 %
RETORQ1	2	29	2.9	20.1 %
REPAIR1	2	6	24.7	35.7 %
REPAIR2	2	4	31.0	29.9 %
REPAIR3	2	3	30.0	21.7 %
TEST5	3	1	0.0	0.0 %
TEST7	3	1	0.0	0.0 %
TEST9	3	1	0.0	0.0 %
RETORQ1	3	9	2.7	5.8 %
REPAIR1	3	1	0.0	0.0 %

DEPT: 570

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
CUSTOMT1	1	91	2.4	40.9 %
CUSTOMT2	1	106	2.3	46.6 %
CUSTOMT3	1	77	2.4	35.0 %
CUSTOMT4	1	98	2.3	42.5 %
CUSTOMT5	1	85	2.5	40.3 %
CUSTOMT1	2	45	2.8	21.2 %
CUSTOMT2	2	55	2.5	23.2 %
CUSTOMT3	2	49	2.1	17.4 %
CUSTOMT4	2	71	2.2	26.7 %
CUSTOMT5	2	62	2.2	23.1 %

DEPT: 571

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
FTRIM1	1	43	4.9	39.6 %
FTRIM2	1	95	1.7	30.1 %

FTRIM3	1	108	1.4	28.3 %
FTRIM4	1	114	1.4	30.2 %
FTRIM5	1	102	1.5	29.3 %
FTRIM6	1	100	1.6	29.5 %
FTRIM7	1	100	1.6	30.6 %
FTRIM8	1	96	1.5	27.5 %
FTRIM9	1	70	1.7	22.7 %
FTRIM1	2	75	5.6	71.3 %
FTRIM2	2	180	1.6	50.2 %
FTRIM3	2	224	1.6	59.4 %
FTRIM4	2	188	1.9	61.6 %
FTRIM5	2	199	1.7	56.5 %
FTRIM6	2	199	1.9	63.5 %
FTRIM7	2	197	1.7	55.8 %
FTRIM8	2	174	1.9	55.1 %
FTRIM9	2	121	2.2	45.2 %

DEPT: 572

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# TRUCKS PROCESSED	AVG. TIME/ TRUCK	% ULT.
ANALYST	1	11	4.5	11.4 %
SHIPPER1	1	11	10.9	27.3 %
SHIPPER2	1	11	11.8	29.5 %
TRUCKER1	1	4	18.7	17.0 %
TRUCKER2	1	5	20.0	22.7 %
TRUCKER3	1	4	18.7	17.0 %
CLERK	1	11	9.1	22.7 %

DEPT: 570 PAINT

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
PAINTR1	1	27	5.8	29.5 %
PAINTR2	1	26	6.7	33.1 %
PAINTR1	2	42	6.2	44.1 %
PAINTR2	2	46	7.2	55.8 %

Simulation Output (Experimental Condition)

SCHEDULING AND SEQUENCING MODEL SIMULATION EXPERIMENTAL CONDITION

TEST: NUMBER 1

INPUT CONDITIONS:

AVG. LINE RATE-1ST:	130.0	ENGINES/SHIFT
AVG. LINE RATE-2ND:	0.0	ENGINES/SHIFT
AVG. LINE RATE-3RD:	0.0	ENGINES/SHIFT
# LOAD BARS - MAIN:	160	
HEAVY REPAIR:	45.0	MINS.
LIGHT REPAIR:	20.0	MINS. @ 5% REJECT RATE
CELL DELAY:	5.0	MINS. @ 10% DELAY RATE
# EFFECTIVE DOCKS:	3	

RESULTS AFTER: 1 SIMULATION DAYS

ENGINE PRODUCTION SUMMARY:

	TOTAL	AVG./DAY
	-----	-----
J-HOOK PRODUCTION:	106	106.0
TEST PRODUCTION:	111	111.0
CUSTOM TRIM PRODUCTION:	68	68.0
FINAL TRIM PRODUCTION:	111	111.0
PAINT PRODUCTION:	72	72.0
ENGINE SHIPPED:	139	139.0
TRUCKS SHIPPED:	17	17.0

ENGINE PROCESS SUMMARY:

	AVG.	MAX.	MIN.	CURRENT
	-----	-----	-----	-----
# ENGINES IN PROCESS/ J-HOOK TO 572:	49.6	87	30	30
# ENGINES IN 572 (TRUCK GRIDS):	54.3	99	11	68
# TRUCK GRIDS:	8.7	15	-----	10
TOTAL ENGINES AFTER J-HOOK:	103.9	150	86	98
TRUCK DOCK USAGE SUMMARY:	0.5	3	-----	0
PROCESS TIME IN DAYS/ J-HOOK TO 572:	0.4	1.1	0.1	
WAREHOUSE TIME IN DAYS:	0.4	0.9	0.0	
TRUCK LOAD TIME IN DAYS:	0.3	0.7	0.0	
ENGINE FINISH SEQUENCE VARIATION:	0.5	42	-54	

FLOW RATE BY DEPARTMENT:

DEPARTMENT (MINS/ENGINE)	TOTAL PRODUCED	# ENGINES /DAY	#SHIFT /DAY	DAYS/ WEEK	EFFECTIVE MINS./DAY	CALCULATED FLOW RATE
	-----	-----	-----	-----	-----	-----
564	106	106.0	1	5	440	4.2
568	20	20.0	2	5	880	44.0
569	111	111.0	3	5	1245	11.2
570	68	68.0	2	5	1120	16.5
571	111	111.0	2	5	1120	10.1
572	139	139.0	1	5	440	3.2

570P 72 72.0 2 5 1120 15.6

J-HOOK CHANGEOVERS	TOTAL	AVG./DAY
# CHANGEOVERS:	7	7.0
CHANGEOVER TIME(HOURS):	0.3	0.3
% CHANGEOVER:	6.6 %	----

HOURLY FLOW METER SUMMARY (UNITS/HOUR)

AREA	AVG.	MAX.	MIN.
JHOOK	11.8	18.0	6.0
TEST	9.3	15.0	1.0
CUSTOM TRIM	6.2	11.0	1.0
FINAL TRIM	7.9	13.0	3.0
PAINT	5.5	8.0	2.0

CRITICAL QUEUE SUMMARY

AREA	AVG.	MAX.	MIN.
EMPTY	85.5	90.0	67.0
ATTIC	0.8	9.0	0.0
TEST LOOP	1.2	8.0	0.0
CUSTOM TRIM	4.7	14.0	1.0
FINAL TRIM	9.9	12.0	2.0
PAINT	5.7	15.0	0.0

ENGINE PRODUCTION DETAIL:

DAILY ENGINES SHIPPED:

ENGINE	PRODUCTION DAYS:										TOTAL
	1	2	3	4	5	6	7	8	9	10	
6081HRW03	8	0	0	0	0	0	0	0	0	0	8
6125HRW01	2	0	0	0	0	0	0	0	0	0	2
6125HRW02	2	0	0	0	0	0	0	0	0	0	2
6105HRW01	1	0	0	0	0	0	0	0	0	0	1
6081TRW01	20	0	0	0	0	0	0	0	0	0	20
6081TRW02	9	0	0	0	0	0	0	0	0	0	9
6081HRW01	14	0	0	0	0	0	0	0	0	0	14
6081HRW05	2	0	0	0	0	0	0	0	0	0	2
6081HRW06	4	0	0	0	0	0	0	0	0	0	4
6081HRW07	6	0	0	0	0	0	0	0	0	0	6
6081HRW08	2	0	0	0	0	0	0	0	0	0	2
6125HRW04	4	0	0	0	0	0	0	0	0	0	4
6081HDW01	2	0	0	0	0	0	0	0	0	0	2
6081HDW05	2	0	0	0	0	0	0	0	0	0	2
6081HDW06	2	0	0	0	0	0	0	0	0	0	2
6101AT012	3	0	0	0	0	0	0	0	0	0	3
6101AT010	12	0	0	0	0	0	0	0	0	0	12
6081HH006	3	0	0	0	0	0	0	0	0	0	3
6081TF001	22	0	0	0	0	0	0	0	0	0	22
6081HF001	12	0	0	0	0	0	0	0	0	0	12
6081AF001	7	0	0	0	0	0	0	0	0	0	7
TOTAL	139	0	0	0	0	0	0	0	0	0	139

DAILY TRUCK SHIPMENT BY CUSTOMER:

PRODUCTION DAYS:

CUSTOMER	1	2	3	4	5	6	7	8	9	10	TOTAL
WATERLOO	9	0	0	0	0	0	0	0	0	0	9
DAVENPORT	1	0	0	0	0	0	0	0	0	0	1
HITACHI	2	0	0	0	0	0	0	0	0	0	2
HARVESTER	1	0	0	0	0	0	0	0	0	0	1
OEM	4	0	0	0	0	0	0	0	0	0	4
TOTAL	17	0	0	0	0	0	0	0	0	0	17

ENGINE PROCESS DETAIL:

PROCESS TIME BETWEEN J-HOOK & 572 (IN HOURS):

ENGINE	# COMPLETE	AVG.	MAX.	MIN.
6081HRW03	8	4.5	4.8	4.1
6125HRW01	3	9.1	9.6	8.8
6125HRW02	4	9.9	12.3	8.6
6105HRW01	2	5.4	7.0	3.9
6081TRW01	59	6.5	21.9	1.4
6081TRW02	18	12.2	21.6	2.3
6081HRW01	14	4.7	6.9	3.5
6081HRW05	4	9.6	10.3	8.9
6081HRW06	4	4.3	5.7	3.1
6081HRW07	6	4.4	5.9	3.3
6081HRW08	2	6.1	8.7	3.4
6125HRW04	8	9.3	10.0	8.7
6081HDW01	4	11.6	25.6	5.5
6081HDW05	4	7.9	9.1	5.4
6081HDW06	4	9.1	17.0	5.3
6125ADW70	2	9.5	10.0	9.1
6101AT012	6	9.9	10.7	9.0
6101AT010	24	8.6	12.6	6.9
6081HH006	6	7.1	9.6	4.2
6081TF001	44	11.8	26.1	6.3
6081HF001	24	11.2	21.8	5.2
6081AF001	14	8.5	23.1	4.2
TOTAL:	264	8.7	26.1	1.4

WAREHOUSE TIME (IN HOURS):

ENGINE	# COMPLETE	AVG.	MAX.	MIN.
6081HRW03	8	10.6	19.3	2.2
6125HRW01	2	15.5	15.6	15.4
6125HRW02	2	13.8	15.6	12.0
6105HRW01	1	16.9	16.9	16.9
6081TRW01	40	6.7	17.3	1.2
6081TRW02	18	3.8	7.1	1.1
6081HRW01	14	10.8	20.4	1.4
6081HRW05	2	15.0	15.0	15.0
6081HRW06	4	10.7	20.1	1.5
6081HRW07	6	10.4	20.0	1.4
6081HRW08	2	8.6	16.0	1.3
6125HRW04	4	14.9	15.3	14.0
6081HDW01	4	5.3	17.2	1.2
6081HDW05	4	8.4	14.2	1.3
6081HDW06	4	7.0	14.3	3.9
6101AT012	3	15.0	15.7	13.9
6101AT010	12	17.1	19.0	12.6
6081HH006	6	7.1	12.7	1.1

6081TF001	22	17.5	20.6	14.7
6081HF001	24	5.5	14.6	1.7
6081AF001	14	7.7	15.7	1.2

TOTAL:	196	9.5	20.6	1.1
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TRUCK GRID TIME (AWAITING SHIPMENT) IN HOURS:

CUSTOMER	# COMPLETE	AVG.	MAX.	MIN.
WATERLOO	12	10.7	20.4	1.9
DAVENPORT	2	9.4	17.2	1.6
HITACHI	2	17.9	19.0	15.7
HARVESTER	2	7.5	12.7	2.2
OEM	6	12.7	20.6	3.2

TOTAL:	24	11.4	20.6	1.6
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TRUCK LOAD TIME IN HOURS:

CUSTOMER	# COMPLETE	AVG.	MAX.	MIN.
WATERLOO	12	6.8	16.8	1.1
DAVENPORT	3	1.2	1.3	1.2
HITACHI	2	14.6	16.7	12.6
HARVESTER	2	6.7	12.3	1.1
OEM	5	7.1	16.6	1.2

TOTAL:	24	6.8	16.8	1.1
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FINISH SEQUENCE VARIANCE:

ENGINE	# COMPLETE	AVG.	MAX.	MIN.
6081HRW03	8	23.6	29	19
6125HRW01	3	-8.0	-2	-18
6125HRW02	4	-14.8	2	-29
6105HRW01	2	25.0	30	20
6081TRW01	59	13.8	42	-20
6081TRW02	18	9.9	29	-25
6081HRW01	14	18.1	26	2
6081HRW05	4	-11.8	-4	-20
6081HRW06	4	34.0	41	25
6081HRW07	6	33.7	41	24
6081HRW08	2	20.0	40	0
6125HRW04	8	-10.3	1	-19
6081HDW01	4	-20.5	3	-54
6081HDW05	4	1.5	17	-25
6081HDW06	4	8.3	20	-2
6125ADW70	2	-11.0	-7	-15
6101AT012	6	-15.2	-6	-21
6101AT010	24	-13.5	0	-34
6081HH006	6	-1.8	6	-13
6081TF001	44	-17.6	5	-48
6081HF001	24	-4.1	13	-23
6081AF001	14	-10.6	2	-34

TOTAL:	264	0.5	42	-54
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TECHNICIAN PERFORMANCE BY DEPARTMENT

DEPT: 568

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
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BBTRIM	1	48	4.4	48.4 %
BBTRIM1	1	47	4.5	47.9 %
LREPAIR	1	3	20.0	13.6 %
LEAKTEST2	1	16	7.5	27.3 %
BBTRIM	2	10	3.2	7.2 %
BBTRIM1	2	9	3.5	7.2 %
LREPAIR	2	1	0.0	0.0 %
LEAKTEST2	2	6	6.7	9.1 %

DEPT: 569

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ENGINE	% ULT.
TEST5	1	49	8.0	94.4 %
TEST7	1	45	8.1	87.5 %
TEST9	1	43	8.2	84.8 %
TEST11	1	41	8.3	82.3 %
RETORQ1	1	63	3.7	56.4 %
RETORQ2	1	17	3.2	9.2 %
REPAIR1	1	7	29.7	50.1 %
REPAIR2	1	6	18.4	26.6 %
REPAIR3	1	5	36.0	43.4 %
TEST5	2	24	7.5	43.5 %
TEST7	2	20	7.2	34.6 %
TEST9	2	18	7.3	31.7 %
TEST11	2	18	7.4	32.2 %
RETORQ1	2	35	3.0	25.3 %
REPAIR1	2	5	24.4	29.4 %
REPAIR2	2	4	32.4	31.2 %
REPAIR3	2	3	30.0	21.7 %
TEST5	3	1	0.0	0.0 %
TEST7	3	1	0.0	0.0 %
TEST9	3	1	0.0	0.0 %
RETORQ1	3	1	0.0	0.0 %
REPAIR1	3	1	0.0	0.0 %

DEPT: 570

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ENGINE	% ULT.
CUSTOMT1	1	87	2.9	47.0 %
CUSTOMT2	1	100	2.6	49.9 %
CUSTOMT3	1	86	2.1	34.1 %
CUSTOMT4	1	101	2.4	46.0 %
CUSTOMT5	1	90	2.3	38.4 %
CUSTOMT1	2	59	1.6	16.2 %
CUSTOMT2	2	65	2.3	24.8 %
CUSTOMT3	2	55	2.1	19.8 %
CUSTOMT4	2	60	2.3	23.0 %
CUSTOMT5	2	57	2.2	21.4 %

DEPT: 571

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ENGINE	% ULT.
FTRIM1	1	55	5.1	52.9 %
FTRIM2	1	128	1.6	38.0 %

FTRIM3	1	155	1.3	39.3 %
FTRIM4	1	144	1.6	43.5 %
FTRIM5	1	141	1.6	41.3 %
FTRIM6	1	131	1.7	40.9 %
FTRIM7	1	124	1.5	36.2 %
FTRIM8	1	128	1.7	41.4 %
FTRIM9	1	102	1.8	34.3 %
FTRIM1	2	62	5.5	58.1 %
FTRIM2	2	154	1.6	41.5 %
FTRIM3	2	196	1.5	50.8 %
FTRIM4	2	148	1.9	48.8 %
FTRIM5	2	153	1.7	43.4 %
FTRIM6	2	155	1.9	49.2 %
FTRIM7	2	157	1.6	42.9 %
FTRIM8	2	148	1.8	44.5 %
FTRIM9	2	103	2.1	36.4 %

DEPT: 572

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# TRUCKS PROCESSED	AVG. TIME/ TRUCK	% ULT.
ANALYST	1	17	4.7	18.2 %
SHIPPER1	1	16	12.2	44.3 %
SHIPPER2	1	18	11.4	46.6 %
TRUCKER1	1	6	20.8	28.4 %
TRUCKER2	1	7	19.6	31.2 %
TRUCKER3	1	7	21.4	34.1 %
CLERK	1	18	9.4	38.6 %

DEPT: 570 PAINT

OPERATING DAYS/WEEK: 5

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
PAINTR1	1	31	6.0	35.4 %
PAINTR2	1	30	6.8	38.7 %
PAINTR1	2	43	6.0	43.5 %
PAINTR2	2	48	7.2	58.4 %

APPENDIX B
Simulation Code

SCHEDULING AND SEQUENCING MODEL SIMULATION CODE

DEVELOPED BY G. Rehn

```

*          SIMULATE 3
          REALLOCATE COM,900000
          REALLOCATE STO,500,CHA,500
          REALLOCATE FAC,500,HSV,300,GRP,300
*
OCOLORC STARTMACRO
PUTTIME MACRO
  BPUTPIC          FILE=ATF, (#A, #B)
Set C* Color *
  ENDMACRO
*
          INTEGER   &I, &J, &K, &L, &M, &N, &CDOWN(18), &MAX, &CHOK, &PRVENG
          INTEGER   &KEYCNT, &EFAM(20)
          REAL      &R, &S, &T, &DAY, &CONVS, &JHKCO, &PRORATE(6), &JHKCOTIM
          REAL      &MTBF(20), &DTIM(20), &DELAY1(20)
          CHAR*12   &PRTNO(100), &ENG, &CLR(8), &ECLR(100), &NULL
          VCHAR*12  &PRVCUS, &PCLR(6), &NUM, &ITOCHAR(50)
*
.....
*
* Define job attributes (fullword)
*
ENGINE   EQU          1, PF          //ENGINE ID
DELRT    EQU          2, PF          //DELIVERY DESTINATION
REPAIR   EQU          3, PF          //ENGINE REPAIR INDICATOR
RETEST   EQU          4, PF          //RETEST COUNT
CVSEC    EQU          5, PF          //CURRENT CONTROL ZONE
SEQNM    EQU          6, PF          //ASSEMBLY SEQUENCE #
SUBR     EQU          7, PF          //SUBROUTINE PARAMETER
PTR      EQU          8, PF          //POINTER PARAMETER
CTR      EQU          9, PF          //COUNTER PARM.
PLOC     EQU          10, PF         //PREVIOUS location
CLOC     EQU          11, PF         //CURRENT LOCATION
OPNUM    EQU          12, PF         //OPERATION #
INDX     EQU          13, PF         //ULT. INDEX
JNDX     EQU          14, PF         //ULT. INDEX
SHFT     EQU          15, PF         //TECHNICIAN SHIFT
PCT      EQU          16, PF         //WORKING PCT.
RJCT     EQU          17, PF         //REJECT INDICATOR (0=NO;1=YES)
SSEQN    EQU          18, PF         //GRAND SEQUENCE #
LCTR     EQU          19, PF         //LOOP COUNTER
MOD      EQU          20, PF         //MODULE INDICATOR
LOC1     EQU          21, PF         //LOCATION 1
LOC2     EQU          22, PF         //LOCATION 2
LOC3     EQU          23, PF         //LOCATION 3
LOC4     EQU          24, PF         //LOCATION 4
LOC5     EQU          25, PF         //LOCATION 5
LOC6     EQU          26, PF         //LOCATION 6
OPER1    EQU          27, PF         //1ST OPERATOR IN SERIES
OPERL    EQU          28, PF         //LAST OPERATOR IN SERIES
TECHN    EQU          29, PF         //TECHNICIAN #
PCODE    EQU          30, PF         //LOAD BAR PROCESS CODE
NOOPR    EQU          31, PF
TSEQN    EQU          32, PF         //TRUCK SEQUENCE#
*
* Define job attributes (floating)
*
DELAY    EQU          1, PL          //HOT JOB DELAY
ITIME    EQU          2, PL          //INDEX TIME
WAIT     EQU          3, PL          //WAIT TIME
CYCLE    EQU          4, PL          //CYCLE
LAPTIM   EQU          5, PL          //TOTAL SYSTEM TIME
CMPEST   EQU          6, PL          //COMPLETION ESTIMATE

```

```

ACMBRK  EQU      7,PL          //ACCUMULATED BREAK
*
*.....*
*
* File Variables.
*
      VCHAR*8    &TESTID      Test ID.
      VCHAR*80   &TESTDSCR    Test description.
      REAL      &PRODVOL(3)   Daily production volume.
      INTEGER   &RUNDAYS     # of days to run.
      INTEGER   &LBCTMAIN    Load bar count in main conveyor.
      INTEGER   &LBCTPNT    Load bar count in paint.
      REAL      &TMFOVEN     Time in paint oven (min).
*
      REAL      &TRIM(100)    Time: Trim
      REAL      &TXFR(100)    Time: Transfer
      REAL      &TRM571(100)  Time: Final Trim
*
* Data Declarations
*
      INTEGER   &SHIFTNO,&STAOPMIN,&STAOPMID,&STAOPMAX,&DAYNO
      VCHAR*100 &STRING1
      INTEGER   &OFLDENGs
      INTEGER   &FTRMENGs
      INTEGER   &BBMRG(40)
*
* CUSTOM TRIM STORAGES: 140-159
*
      CTRMQ     EQU      140,S,L //TRIM STATION
      CTLINE   EQU      141(9),S,L //TRIM LINE
      SSTG0    EQU      155,S,L,C //STAGING ZONE
      STRMI    EQU      156,S,L,C //DELIVERY PATH TO TRIMS
      STRM1    EQU      157,S,L,C //TRANSFER SWITCH
      TRMOUT   EQU      158,S,L,C //EXIT TRIM AREA
      TCTLINE  EQU      151,S
      TFTLINE  EQU      152,S
*
      STORAGE  S140,17/S141-S148,1/S149,7/S(SSTG0),2
      STORAGE  S(STRMI),5/S(STRM1),1/S(TRMOUT),5
      STORAGE  S(TCTLINE),5/S(TFTLINE),9
*
* FINAL TRIM Storages: 160-179
*
      FTRMQ    EQU      160,S,L //FINAL TRIM QUEUE
      FTLINE   EQU      161(9),S,L //FINAL TRIM STATION
      BBSWT    EQU      179,L //BACKBONE SWITCH
*
      STORAGE  S(FTRMQ),12
      STORAGE  S161-S169,1
*
* Paint Loop Storages: 180-199
*
      SPNT1    EQU      180,S
      SPNT2    EQU      181,S
      SPNT3    EQU      182,S
      SPNT4    EQU      183,S
      SPNT5    EQU      184,S
      SPNT6    EQU      185,S
      SPNT7    EQU      186,S
      SPNT8    EQU      187,S,C
*
      STORAGE  S(SPNT1),20/S(SPNT2),3/S(SPNT3),3/S(SPNT4),1
      STORAGE  S(SPNT5),1/S(SPNT6),12/S(SPNT7),5/S(SPNT8),11
*
* 569 Repair Storages: 250-259
*
      REPRQ    EQU      250,S,L //REPAIR QUEUE
      EREPR    EQU      259,S //EXIT REPAIR
*

```

```

        STORAGE      S(REPRQ),4/S(EREPR),1
*
* 568 Process Storages: 260-279
*
PRO568  EQU          260(9),F,S,C,L           //568 REPAIR
TRM568  EQU          271(6),F,S,C,L           //568 TRIM LINE
LEAKQ   EQU          269,S,L,C               //LEAK TEST QUEUE
LKTST2  EQU          270,S                   //LEAK TEST
        STORAGE     S260,5/S261-S263,8       //REPAIR SPURS
        STORAGE     S(LEAKQ),14/S270,1       //LEAK TEST QUEUE
        STORAGE     S272-S276,1/S271,3       //568 TRIM LINE
*
* Power & Free Storages: 280-290
*
SPF1    EQU          281,S,L
SPF2    EQU          282,S
SPL     EQU          283,S
SPO     EQU          284,S,F
        STORAGE     S(SPF2),9/S(SPL),1/S(SPO),5
*
* Gather statistics, traffic control Storages: 290+
*
DOCKS   EQU          290,S
EWIPQ   EQU          292,S                   //ENGINES FROM JHOOK TO 572
TOTALQ  EQU          293,S                   //TOTAL ENGINES IN FACTORY
        STORAGE     S200,1
*
* TRANSIT COUNTS STORAGES 301-304
*
CSTRMCNT EQU          301,S                   //CUSTOM TRIM TRANSIT COUNT
FNTRMCNT EQU          302,S                   //FINAL TRIM TRANSIT COUNT
PAINTCNT EQU          303,S                   //PAINT TRANSIT COUNT
TSTLCOUT EQU          304,S                   //TEST LOOP COUNT OUT
BACKBCNT EQU          305,S,L,C               //BACKBONE TRANSIT LIMIT
BLUBFQ   EQU          306,C,Q,L               //BLUEBIRD FLOOR QUEUE
*
* .....
*
* Define Facilities and Storages.
*
BBCNV   EQU          1(26),S,L
MORN    EQU          27,L
COUNT  EQU          28,XF,L                   //OLD RC COUNT
LJHOOK  EQU          29,L                       //Logic flag: JHOOK transfer.
LTXFR   EQU          30,L                       //Logic flag: TXFR transfer.
CELLSW  EQU          31(6),L,S
RTORKQ  EQU          37,S,C,L                   //RETORQUE QUEUE
RTORQ1  EQU          38,S,L                     //RETORQUE STA 1
RTORQ2  EQU          39,S,L                     //RETORQUE STA 2
RTORQE  EQU          40,S,L                     //RETORQUE QUEUE
BACKUP  EQU          400,S
RECR1I  EQU          401,S,L                     //569 RECIRC IN
RECR1   EQU          402,S,L,C                   //569 RECIRC
RECR1O  EQU          403,S,L                     //569 EXIT
SPIN1   EQU          404,L                       //INDICATES RC 1 SEARCHING
RCCAL1  EQU          404,C                       //CALL CHAIN FOR RC1
RECR2I  EQU          405,S,L                     //570 RECIRC IN
RECR2M  EQU          406,S,L,C                   //570 RECIRC MIDDLE
RECR2O  EQU          407,S,L                     //570 EXIT
RECR2   EQU          408,S                       //TOTAL RECIR LOOP
SPIN2   EQU          409,L                       //INDICATES RC 2 SEARCHING
RCCAL2  EQU          410,C                       //RECIRC #2 CALL CHAIN
FAILR   EQU          450,C                       //HOLD FAILURE COUNT
DLAYSW  EQU          451(20),L                   //DELAY CONDITION SWITCHES
*
* STORAGE DEFINITION
*

```

```

STORAGE S1,6/S2,4/S3,14/S4,1/S5,2/S6,6/S7,13/S8,13
STORAGE S9,3/S10,9/S11,7/S12,2/S13,2/S14,7/S15,2
STORAGE S16,12/S17,27/S18,90/S19,8 //BACKBONE
STORAGE S31,2/S32,7/S33,2 //TEST CELL LOOP
STORAGE S34,1/S35,6/S36,4 //TEST CELL QUEUES
STORAGE S37,7/S38-S40,1 //RETORQUE STATIONS
STORAGE S(RECR10),1/S(RECR1),50/S(BACKUP),3

```

* Define Facilities.

```

EXIT1 EQU 77,F,XF EXIT PATH CLEAR
EXIT2 EQU 78,F,XF EXIT PATH CLEAR
ENTR1 EQU 79,F,XF EXIT PATH CLEAR
ENTR2 EQU 80,F,XF EXIT PATH CLEAR
CTEST1 EQU 81,F TEST CELL
CTEST2 EQU 82,F TEST CELL
CTEST3 EQU 83,F TEST CELL
CTEST4 EQU 84,F TEST CELL
CTEST5 EQU 85,F TEST CELL
CTEST6 EQU 86,F TEST CELL
CTEST7 EQU 87,F TEST CELL
CTEST8 EQU 88,F TEST CELL
CTEST9 EQU 89,F TEST CELL
CTEST10 EQU 90,F TEST CELL
CTEST11 EQU 91,F TEST CELL
CTEST12 EQU 92,F TEST CELL
CTEST13 EQU 93,F TEST CELL
CTEST14 EQU 94,F TEST CELL
CTEST15 EQU 95,F TEST CELL
CTEST16 EQU 96,F TEST CELL
CTEST17 EQU 97,F TEST CELL
CTEST18 EQU 98,F TEST CELL
CMCHT EQU 100(18),F ASSOC. CELL RUN TIME

```

```

CSPED EQU 1,XL //CONV. SPEED

```

* PROCESS CODES & GROUPS

```

RCRQ1 SYN 1 //RECIRCULATE
CLTEST SYN 2 //TEST CELL
RTORQ SYN 3 //RETORQUE
AUDIT SYN 4 //AUDIT
OFFLD SYN 5 //OFFLOAD
REPAIRS SYN 6 //REPAIRS
CSTRIM SYN 7 //CUSTOM TRIM
FNTRIM SYN 8 //FINAL TRIM
PNTSYS SYN 9 //PAINT SYSTEM
BBTRIM SYN 10 //BLUE BIRD TRIM

```

```

GRCRQ1 EQU 1,G
GCLTEST EQU 2,G
GRTORQ EQU 3,G
GAUDIT EQU 4,G
GOFFLD EQU 5,G
GREPAIRS EQU 6,G
GCSTRIM EQU 7,G
GFNTRIM EQU 8,G
GPNTSYS EQU 9,G
GGBTRIM EQU 10,G
GFNTRBB EQU 11,G
GFNTRPT EQU 12,G
GPNTSBB EQU 13,G
TRKGRID EQU 51(50),XH,G //TRUCK GRID
TGRIDS EQU 1,Q //NUMBER OF OPEN GRIDS

```

* MATRIX DEFINITIONS

```

CSECT MATRIX ML,50,50 //CONV. SECTION TRAVEL DISTANCE
PROD MATRIX ML,100,20 //PRODUCTION MATRIX

```

```

TECHBD  MATRIX  ML,100,10      //TECHNICIAN BREAKDOWN
TCHASN  MATRIX  MX,200,10      //TECHNICIAN ASSIGNMENTS
CUSTRM  MATRIX  ML,20,20      //CUSTOM TRIM CLASSxSTATION
FNLTRM  MATRIX  ML,20,20      //FINAL TRIM CLASSxSTATION
FLOWRT  MATRIX  ML,6,5        //FLOW RATE COLLECTION
KEYQUE  MATRIX  ML,6,5        //CRITICAL QUEUE COLLECTION

```

```

*****

```

```

* File Definitions for files used in every scenario

```

```

INFILE  FILEDEF  'INPUT.DAT'      //General Input Parmaters
LAYOUT  FILEDEF  'LAYOUT.DAT'     //Layout Definition
INVEN   FILEDEF  'INV.DAT'        //Beginning Inventory
ALINEUP FILEDEF  'LINEUP.DAT'     //Assembly Lineup
DPT568  FILEDEF  'CYL568.DAT'     //568 Cycle Times
DPT569  FILEDEF  'CYL569.DAT'     //569 Cycle Times
DPT570  FILEDEF  'CYL570.DAT'     //570 Cycle Times
DPT572  FILEDEF  'CYL572.DAT'     //572 Cycle Times
DPT571  FILEDEF  'PAINT.DAT'      //571 Paint Parameters
TECHS   FILEDEF  'TECHS.DAT'      //Technician Assignments
OPDAT   FILEDEF  'OPERAT.DAT'     //Operation Schedules
CSTRM   FILEDEF  'CTRIM.DAT'      //Custom Trim Line
FNTRM   FILEDEF  'FTRIM.DAT'      //Final Trim Line
DWNTIM  FILEDEF  'DWNTIM.DAT'     //Downtime Scenarios
ATF     FILEDEF  'TTPS1.ATF'      //ttps Trace File
OUT     FILEDEF  'OUTPUT.DAT'     //Output Report
TSUM    FILEDEF  'TESTSUM.DAT',APPEND //ACCUMULATION TEST SUMMARY

```

```

* INITIALIZATION

```

```

INITIAL XLSCSPED,60.0      CONV. SPEED
INITIAL MLSCSECT(1,1),.84/MLSCSECT(2,1),.54
INITIAL MLSCSECT(3,1),1.75/MLSCSECT(4,1),.14
INITIAL MLSCSECT(5,1),.32/MLSCSECT(6,1),.75
INITIAL MLSCSECT(7,1),1.36/MLSCSECT(8,1),1.59
INITIAL MLSCSECT(9,1),.39/MLSCSECT(10,1),1.14
INITIAL MLSCSECT(11,1),.90/MLSCSECT(12,1),.30
INITIAL MLSCSECT(13,1),.26/MLSCSECT(14,1),.91
INITIAL MLSCSECT(15,1),.27/MLSCSECT(16,1),3.02
INITIAL MLSCSECT(17,1),3.35/MLSCSECT(18,1),11.22
INITIAL MLSCSECT(19,1),1.04
INITIAL MLSCSECT(31,1),.26/MLSCSECT(32,1),.84
INITIAL MLSCSECT(33,1),.18/MLSCSECT(38,1),.28
INITIAL MLSCSECT(39,1),.50

INITIAL MLSCSECT(1,11),.12/MLSCSECT(2,11),.33
INITIAL MLSCSECT(3,11),.35/MLSCSECT(4,11),.12
INITIAL MLSCSECT(9,11),.07
INITIAL MLSCSECT(11,11),.08/MLSCSECT(12,11),.07
INITIAL MLSCSECT(13,11),.12
INITIAL MLSCSECT(15,11),.15
INITIAL MLSCSECT(17,11),.14
INITIAL MLSCSECT(32,11),.13/MLSCSECT(33,11),.13
INITIAL MLSCSECT(38,11),.42/MLSCSECT(39,11),.21

INITIAL MLSCSECT(1,12),.33/MLSCSECT(2,12),.14
INITIAL MLSCSECT(3,12),.22/MLSCSECT(4,12),.12
INITIAL MLSCSECT(9,12),.08
INITIAL MLSCSECT(11,12),.08/MLSCSECT(12,12),.15
INITIAL MLSCSECT(13,12),.13
INITIAL MLSCSECT(15,12),.22
INITIAL MLSCSECT(17,12),.14
INITIAL MLSCSECT(32,12),.15/MLSCSECT(33,12),.14

INITIAL MLSCSECT(1,22),16.92/MLSCSECT(1,23),29.92
INITIAL MLSCSECT(1,24),43.03/MLSCSECT(1,25),54.66
INITIAL MLSCSECT(1,26),41.55/MLSCSECT(1,27),28.55
INITIAL MLSCSECT(1,28),39.45/MLSCSECT(1,32),38

```

```

INITIAL      MLSCSECT(1,33),58.82/MLSCSECT(1,34),37.24
INITIAL      MLSCSECT(1,35),165.21/MLSCSECT(1,36),82.92
*
      LET      &BBMRG(1)=1           //BB MERGE
      LET      &BBMRG(2)=1           //BB MERGE
      LET      &BBMRG(3)=1           //BB MERGE
      LET      &BBMRG(4)=1           //BB MERGE
      LET      &BBMRG(9)=1           //BB MERGE
      LET      &BBMRG(11)=1          //BB MERGE
      LET      &BBMRG(12)=1          //BB MERGE
      LET      &BBMRG(13)=1          //BB MERGE
      LET      &BBMRG(15)=1          //BB MERGE
      LET      &BBMRG(17)=1          //BB MERGE
      LET      &BBMRG(32)=1          //BB MERGE
      LET      &BBMRG(33)=1          //BB MERGE
      LET      &BBMRG(35)=1          //BB MERGE
      LET      &BBMRG(37)=1          //BB MERGE
.....
*
* BEGINNING OF BLOCK STATEMENTS
*
.....
*
* CODE ADDITIONS FOR BLOCK AND JHOOK LINE
*
.....
      REAL      &APATH(100)           //ASSEMBLY PATH DISTANCES
      LET      &APATH(1)=11.71
      LET      &APATH(2)=22.06
      LET      &APATH(3)=8
      LET      &APATH(4)=8
      LET      &APATH(5)=8
      LET      &APATH(6)=8
      LET      &APATH(7)=333.98
      LET      &APATH(8)=18.28
      LET      &APATH(9)=423.15
      STORAGE   S201,1/S202,2/S203-S206,1/S207,41/S208,2/S209,52
      REAL      &FSP                   //FAST CONV. SPEED
      LET      &FSP=60.0
      REAL      &SSP                   //SLOW CONV. SPEED
      REAL      &OSP                   //OLD SPEED
      INTEGER   &INV572(100)           //FINISHED ENGINE INV
      INTEGER   &INPROC                //IN PROCESS ENGINES FROM JHOOK ON
      INTEGER   &ESHDP(100)           //ENGINES SHIPPED
      INTEGER   &TRKLD(1000)          //TRUCK LOAD
      VCHAR*12  &PARTNO(100)          //ENGINE PART #
      VCHAR*30  &DUM,&DUM1,&DUM2,&DUM3,&DUM4 //INPUT CHARACTERS
      INTEGER   &FINORD                //FINISH ORDER OF ENGINES
      INTEGER   &SDAY
JHOOK       SYN      200               //J-HOOK OFFSET
ASMLINE     EQU      201(9),L,S        //ASSEMBLY LINE ZONES
ASMPOS      EQU      200(9),F         //ASSEMBLY POSITION
ASMUL       EQU      210,F,C,L        //ASSEMBLY UNLOAD
JHLEAK      EQU      211,F,C,L        //564 LEAK TEST
JHPRO       EQU      212(48),F        //ASSEMBLY CHAIN PROCESS
PRO569      EQU      51(20),F         //569 PROCESSES
PRO571      EQU      125(15),F        //571 PROCESSES
* FACILITIES 300-400 RESERVED FOR TECHNICIANS
ASMLD       EQU      200,C,L          //ASSEMBLY LOAD
SSHRT       EQU      201,C           //SHIPMENT SHORTAGES
INPRO       EQU      202,C           //PROCESS CHAIN
NOTCH       EQU      203,C           //NO TECHNICIANS
HOLD        EQU      204,C           //HOLD CHAIN
BBITQ       EQU      205,C           //BLUEBIRD INPUT TRUCKER
FLRPNTQ     EQU      206,C           //FLOOR PAINT QUEUE
BBOTQ       EQU      207,C           //BLUEBIRD OUTPUT TRUCKER
BBTRMQ      EQU      208,C           //BLUEBIRD TRIM QUEUE

```



```

ACELLS EQU 209,C //ACTIVE CELLS
FINV EQU 215,C //FINISHED INVENTORY
TRKHLD EQU 216,C //TRUCK HOLD
STPSHP EQU 217,C //STOP SHIPMENT
PDLAY EQU 218,C //DELAYED JOB
MATCH EQU 218,L //MATCH ONE DELY @ TIME
DINIT EQU 219,L //INDICATES INITILIZATION DONE
SWING EQU 219,C //HOLD POSITION FOR SWING TECHS
ONTRK EQU 220,C //ENGINES ON TRUCK
FLRSTGQ EQU 221,C //FLOOR STAGE QUEUE
TCHNS SYN 300 //TECHNICIAN OFFSET
.
SHIPS MATRIX MX,900,5 //SHIPMENT SCHEDULE
ESYSRPF MATRIX ML,10,5 //MISC. SYSTEM PERFORMANCE
DSHIPS MATRIX MH,100,21 //DAILY ENGINE SHIPMENTS
TSHIPS MATRIX MH,100,21 //DAILY TRUCK BY CUSTOMERS
SDLAY MATRIX ML,100,5 //SHIPMENT DELAYS
SEQVAR MATRIX ML,100,5 //SEQUENCE VARIATION
PROTIME MATRIX ML,100,5 //PROCESS TIME TO WH
WHSETIM MATRIX ML,100,5 //WAREHOUSE TIME
GRIDTIM MATRIX ML,100,5 //GRID TIME BY CUSTOMER
TRKLDTIM MATRIX ML,100,5 //TRUCK LOAD TIME BY CUSTOMER
FINSEQ FVARIABLE PF(SSEQN)-&FINORD //ENGINE SEQ VS. FINISH ORDER
.
* TTPS Project Inputs
.
REAL &ASMMAX //ASSEMBLY MAXIMUM
REAL &JHSPD(3) //JHOOK SPEED/SHIFT
REAL &PERF(10) //TECH. PERFORMANCE/MODULE
REAL &JHKUL //J-HOOK UNLOAD
REAL &LEAKRJ(2) //LEAK TEST REJECT% (1 & 2)
REAL &LEAKTST(2) //LEAK TEST TIMES (1 & 2)
REAL &LEAKRPR(2) //LEAK REPAIR TIMES (1 & 2)
REAL &HRPRTIM //HEAVY REPAIR TIME
REAL &LRPRTIM //LIGHT REPAIR TIME
REAL &CRPRTIM //CELL REPAIR TIME
REAL &LRPRRJ //LIGHT REPAIR REJECT%
REAL &CRPRRJ //CELL REPAIR REJECT%
REAL &SIN568(100) //STARTING INVENTORY IN 568
REAL &SIN569(100) //STARTING INVENTORY IN 569
REAL &SIN570(100) //STARTING INVENTORY IN 570
REAL &SIN572(100) //STARTING INVENTORY IN 572
REAL &CTRIM(100) //568 COMPRESSOR TRIM
REAL &BTRIM(100) //568 BLUEBIRD TRIM
REAL &RPASS(10) //REAL DATA INPUT VARIABLE
REAL &COPTN(100) //COMPRESSOR OPTIONS
REAL &CTEST(100) //TEST CELL CYCLE TIME
REAL &HOOK(100) //TEST CELL HOOK TIME
REAL &UNHK(100) //TEST CELL UNHOOK
REAL &RHOOK(100) //RTIME FOR TEST CELL HOOK
REAL &RTORK(100) //RETORQUE TIME/ENGINE
REAL &TRJT1(100) //1ST TEST REJECT%
REAL &TRJT2(100) //2ND TEST REJECT%
REAL &BLOWO(100) //PAINT MASK & BLOW-OFF
REAL &MASK(100) //MASK TIME
REAL &PCOAT(100) //PRIME COAT CYCLE TIME
REAL &TCOAT(100) //TOP COAT CYCLE TIME
REAL &RECTRKS //# REC'D TRUCKS/DAY
REAL &SHPTIM(10) //572 CYCLE TIMES
REAL &FLASH //PAINT FLASH TIME/STOP
REAL &COOL //PAINT COOL TIME/STOP
REAL &PNTFSP //PAINT DELIVERY SPEED
REAL &PNTSSP //PAINT PROCESS CHAIN SPEED
REAL &INSPCT //INSPECT TIME
REAL &CYADJ //CYCLE TIME ADJUST
REAL &EPROD(10) //ENGINE PRODUCTION BY MODULE
INTEGER &LBCTJHK //# J-HOOK CARRIERS
INTEGER &NOMDLS //# ENGINE MODELS
INTEGER &TCRTE(100) //TEST CELL ROUTING(0=ANY)

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INTEGER    &DOCK                //# SHIPPING/REC DOCKS
INTEGER    &PCMAX                //MAX. #LOADS ON PROCESS CHAIN
INTEGER    &SVAR                //SAME STATION VARIABLE
INTEGER    &TLAST               //LAST TECHNICIAN
INTEGER    &TCC                 //TECHNICIAN COUNT
INTEGER    &TECHC(300)          //TECHNICIAN COUNT
INTEGER    &GBCNT(10)           //GLOBAL COUNT
INTEGER    &OPCNT(100)          //ENGINE OPTION COUNT
INTEGER    &ENGC1(100)          //ENGINE COUNT (1ST TEST)
INTEGER    &ENGC2(100)          //ENGINE COUNT(2ND TEST)
INTEGER    &MD                  //MODULE POINTER
INTEGER    &SF                  //SHIFT POINTER
INTEGER    &LOC(6)              //LOCATION PARAMETER
INTEGER    &WDAYS(10)           //#WORKS DAYS/WEEK/MODULE
INTEGER    &WEEK                //# PRODUCTION DAYS/WEEK
INTEGER    &CSTLS               //CUSTOM TRIM LAST STATION
INTEGER    &FNTLS               //FINAL TRIM LAST STATION
INTEGER    &ECLASI(100)         //ENGINE CLASS INTEGER BY ENGINE
INTEGER    &BBLIM               //BACKBONE LIMIT
INTEGER    &ATHEAD              //# AT HEAD OF ATTIC
VCHAR*20   &CUSTMR(100)         //CUSTOMER BY ENGINE
VCHAR*20   &CUSTID(100)        //CUSTOMER ID (UNIQUE)
VCHAR*20   &PDATE               //PREVIOUS SHIP DATE
VCHAR*20   &PTRUCK              //PREVIOUS TRUCK #
VCHAR*20   &STECH(10)           //SHIPPING TECHNICIANS
VCHAR*10   &MODID(10)          //MODULE ID NAME
VCHAR*20   &TCHNM(100)         //TECHNICIAN NAME
VCHAR*10   &CPASS(10)          //CHARACTER VALUE PASS
VCHAR*10   &SNAME(300)         //STATION NAME
VCHAR*10   &ECLASC(20)         //ENGINE CLASS CHAR-DEFINITION
*
* VARIABLE DEFINITION
*
CTRVL FVARIABLE MLSCSECT(1,PFSCVSEC)/XLSCSPED CONV. TRAVEL
 1 BVARIABLE FS(81)*LS(41)
 2 BVARIABLE FS(82)*LS(42)
 3 BVARIABLE FS(83)*LS(43)
 4 BVARIABLE FS(84)*LS(44)
 5 BVARIABLE FS(85)*LS(45)
 6 BVARIABLE FS(86)*LS(46)
 7 BVARIABLE FS(87)*LS(47)
 8 BVARIABLE FS(88)*LS(48)
 9 BVARIABLE FS(89)*LS(49)
10 BVARIABLE FS(90)*LS(50)
11 BVARIABLE FS(91)*LS(51)
12 BVARIABLE FS(92)*LS(52)
13 BVARIABLE FS(93)*LS(53)
14 BVARIABLE FS(94)*LS(54)
15 BVARIABLE FS(95)*LS(55)
16 BVARIABLE FS(96)*LS(56)
17 BVARIABLE FS(97)*LS(57)
18 BVARIABLE FS(98)*LS(58)
CELB1 BVARIABLE (BV1=1)OR(BV2=1)OR(BV3=1)OR(BV4=1)OR(BV5=1)OR(BV6=1)
TOSTO BVARIABLE PF(RJCT)=1
TORPR BVARIABLE (PFSRJCT=1)AND(SNF32) //TO REPAIR
RQRWK BVARIABLE (FNU13)AND(SNF14)AND(Q13=0) //RETORQUE REWORK
OPNRT BVARIABLE PF(PTR)'GE'11*PF(PTR)'LE'13
PTWAY BVARIABLE XF79'E'PF1+XF80'E'PF1
BATLD BVARIABLE SE(SPO15)+S(SPNT0)'L'2
SFTCO BVARIABLE (PFSSHFT=&SF)AND(PFSMOD=&MD) //SHIFT CHANGEOVER
DLAY1 BVARIABLE (PFSCLOC=&LOC(1))OR(PFSCLOC=&LOC(2))OR(PFSCLOC=&LOC(3))OR_
(PFSCLOC=&LOC(4))OR(PFSCLOC=&LOC(5))OR(PFSCLOC=&LOC(6))
PBATCH BVARIABLE (CH(SPNT3)>=2)AND(SE(SPNT4))AND(SE(SPNT5))
RTQUL BVARIABLE (LS38)AND(LS39)
ENG105 BVARIABLE (&ECLASI(PFSENGINE)=10)OR_
(&ECLASI(PFSENGINE)=11)OR_
(&ECLASI(PFSENGINE)=12)OR_
(&ECLASI(PFSENGINE)=13)
RTQBYP BVARIABLE (PF(PCODE)=PNTSYS)OR(PF(ENGINE)=0)

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BBMTR   BVARIABLE (LC260)AND(SNF(SPO))AND(SE271) //BLUEBIRD METER
NOBKUP  BVARIABLE (SF$BACKUP)AND(CH$BACKUP>0)AND(SNF$RECR1) //BACKUP CONDITIONBBD0100
*
* FUNCTION DEFINITIONS
*
      2 FUNCTION   PF(CVSEC),D2           //CHAIN DIRECT
34,21/36,22
*
      3 FUNCTION   PFSDELRT,D2           TEST CELL ENTRANCE PATH
6,33/18,32
*
      4 FUNCTION   PFSDELRT,D18          "IN" PATH TRAVEL TIME
1,.49/2,.42/3,.36/4,.28/5,.22/6,.14/7,.05/8,.42/9,.36/10,.29
11,.23/12,.15/13,.50/14,.42/15,.36/16,.29/17,.23/18,.15
*
      5 FUNCTION   PFSDELRT,D18          "OUT" PATH TRAVEL TIME
1,.06/2,.14/3,.2/4,.27/5,.32/6,.40/7,.07/8,.15/9,.2/10,.28
11,.33/12,.41/13,.07/14,.14/15,.20/16,.28/17,.33/18,.41
*
      7 FUNCTION   PFSDELRT,D2           TEST CELL ENTRANCE PATH
6,80/18,79
*
      11 FUNCTION  PFSDELRT,D2           TEST CELL EXIT PATH
6,78/18,77
*
      12 FUNCTION  PF(PCT),D18           //INITIAL %
1,100/2,50/3,33/4,25/5,20/6,16/7,14/8,12/9,11/10,10/11,9/12,8/14,7/17,6
20,5/25,4/33,3/50,2
*
      13 FUNCTION  PF(PCT),D39           //SECONDARY %
12,0/13,200/14,0/15,200/16,400/17,0/18,199/19,399/20,0/21,133/22,199/23,333
24,499/25,0/26,125/27,143/28,200/29,250/30,332/31,500/32,1000/33,0/34,105
35,111/36,125/37,143/38,167/39,181/40,199/41,221/42,249/43,333/44,399/45,499
46,667/47,999/48,1249/49,2499/50,0
*
TLOC1   FUNCTION  PF(LCTR),L6
,PRO110/,PRO120/,PRO130/,PRO140/,PRO150/,PRO160
*
TLOC2   FUNCTION  PF(LCTR),M6           //TECHNICIAN LOCATION #2
,PFSLOC1/,PFSLOC2/,PFSLOC3/,PFSLOC4/,PFSLOC5/,PFSLOC6
*
PROCQ   FUNCTION  PF(LOC1),E6           //STORAGE DIRECT
1,S(18)/2,S(RECR1)/3,S(TSTLCOUT)/4,S(CSTRMCNT)/5,S(FNTRMCNT)/6,S(PAINTCNT)
*
      LET         &PCLR(1)='F3'
      LET         &PCLR(2)='F7'
      LET         &PCLR(3)='F4'
      LET         &PCLR(4)='F11'
      LET         &PCLR(5)='F2'
      LET         &PCLR(6)='F9'
*
      LET         &ITOCHAR(1)='1'
      LET         &ITOCHAR(2)='2'
      LET         &ITOCHAR(3)='3'
      LET         &ITOCHAR(4)='4'
      LET         &ITOCHAR(5)='5'
      LET         &ITOCHAR(6)='6'
      LET         &ITOCHAR(7)='7'
      LET         &ITOCHAR(8)='8'
      LET         &ITOCHAR(9)='9'
      LET         &ITOCHAR(10)='10'
      LET         &ITOCHAR(11)='11'
      LET         &ITOCHAR(12)='12'
      LET         &ITOCHAR(13)='13'
      LET         &ITOCHAR(14)='14'
      LET         &ITOCHAR(15)='15'
      LET         &ITOCHAR(16)='16'
      LET         &ITOCHAR(17)='17'
      LET         &ITOCHAR(18)='18'

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LET      &ITOCCHAR(19)='19'
LET      &ITOCCHAR(20)='20'
LET      &ITOCCHAR(21)='21'
LET      &ITOCCHAR(22)='22'
LET      &ITOCCHAR(23)='23'
LET      &ITOCCHAR(24)='24'
*
* CONTROL STATEMENT PLUGS-INS
*
INSERT   <CNTLDEF1.GPS>
INSERT   <PROOF.MAC>           //ANIMATION MACROS
*
* TECHNICIAN TO ELEMENT MATCH-UP MACRO
*
FNDTCH  STARTMACRO #A
ALTERUCH E APOOL,1,CLOCSPF,PFSCLOC,#A,PFSCLOC,PRO100 //PASS LOC
ALTERUCH E APOOL,1,CYCLESPL,PLSCYCLE,CLOCSPF,PFSCLOC //PASS CYCLE
BLET    PL(CMPEST)=PLSCYCLE+AC1 //ESTIMATE COMPLETION
UNLINK  APOOL,TCH100,1,CLOCSPF,PFSCLOC //GET TECH
ENDMACRO
*
*.....
* Simulation Timer Module
* Written by G. Rehn
* 6/29/98
* Version 01
*-----
* VARIABLES:
PF(CTR)=      Segment Pointer
*
PF(MOD)=      Module #
*
PF(OPER1)=    1st Operator in Range
PF(OPERL)=    Last Operator in Range
*
PF(INDX)=     INDEX POINTER
PF(JNDX)=     INDEX POINTER
*
&SD=         # Simulation Days
&MSHIFT(10)= Initial Shift/Module
&MODID(10)=   Module Identifier
*
&OPXID(200)= Operator ID Index
&COPR(200)=   Operator Color (Current)/Index
*
&SALOW =     Start-up Allowance
&CALOW =     Clean-up Allowance
*
&EFMIN(10) = # Effective Mins/ Day
&OPHRS(10) = # Total Hours
*
&OPSFT(10) = # Operating Shifts/Module
&OPAS(100)=  Input Translation from Excel
*
&DFTOP(100)= Default Operation Description
&ACNOOP(10) = Accumulated Out of Operation Time
*
&CLKS =      Simulation Start Time
&AMPM(2)=    AM/PM START INDICATOR
*
LS(MORN)=    MORNING SWITCH LC-MORNING/LS-AFTERNOON
*
&PE= PAINT PURGE START
&PS= PAINT START-UP TIME
*
Matrix HPS=  Hours/Shift (Halfword)
*
Row=         Module
*
Cols 1-96=   Action in 15 Min. Increments
*
Matrix TCH1,TCHL = First & Last Technicians (Operators)
*
Row=         Module
*
Col=         Shift (1,2,3)
*.....
* TIMER CONTROL STATEMENTS
*.....
INTEGER     &OPXID(200)           //Operator ID Index
VCHAR*9     &COPR(200)           //Operator Color (Current)/Index
INTEGER     &OPSFT(10)           //# Operating Shifts/Module
INTEGER     &MSHIFT(10)          //Initial Shift / Module
REAL        &EFMIN(10)           //# Effective Mins/ Day
REAL        &OPHRS(10)           //# Total Hours
VCHAR*2     &OPAS(100)           //Input Translation from Excel
INTEGER     &DFTOP(100)          //Default Operation
REAL        &ACNOOP(10)          //Accumulated Out of Operation Time

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BSTORAGE S(PAINTCNT),&CHOK //SET STORAGE
BGETLIST FILE=INFILE,&BBLIM //MAX. BB LIMIT
BGETLIST FILE=INFILE,&JHKCO //JHOOK CHANGEOVER
BGETLIST FILE=INFILE,&JHKUL //UNLOAD JHOOK LINE
BGETLIST FILE=INFILE,&DUM //SKIP LINE
BGETLIST FILE=INFILE,&LEAKTST(1),&LEAKTST(2) //1ST&2ND LEAK TEST TIME
BGETLIST FILE=INFILE,&LEAKRJ(1),&LEAKRJ(2) //1ST&2ND LEAK REJECT%
BGETLIST FILE=INFILE,&LEAKRPR(1),&LEAKRPR(2) //1ST&2ND LEAK REPAIR TIME
BGETLIST FILE=INFILE,&DUM //SKIP LINE
BGETLIST FILE=INFILE,&HRPRTIM //HEAVY 569 REPAIR
BGETLIST FILE=INFILE,&LRPRRJ,&LRPRTIM //569 LIGHT REJECT & REPAIR TIME
BGETLIST FILE=INFILE,&CRPRRJ,&CRPRTIM //569 CELL REJECT & REPAIR TIME
BGETLIST FILE=INFILE,&INSPCT //571 INSPECTION
BCLOSE INFILE
*-----
* CUSTOM TRIM
*-----
CUS000 BGETLIST FILE=CSTRM, (&ECLASC(&J),&J=1,14)
      BLET &I=0
      BLET &I=&I+1 //NEXT STATION
      BGETLIST FILE=CSTRM,END=CUS999, (ML(CUSTRM,&J,&I),&J=1,14)
      BLET &CSTLS=&I //SAVE FOR LAST STATIO
      TRANSFER ,CUS000
CUS999 BCLOSE CSTRM
*-----
* FINAL TRIM
*-----
FNL000 BGETLIST FILE=FNTRM, (&EFAM(&J),&J=1,14)
      BGETLIST FILE=FNTRM,&DUM
      BLET &I=0
      BLET &I=&I+1 //NEXT STATION
      BGETLIST FILE=FNTRM,END=FNL999,&DUM, (ML(FNLTRM,&J,&I),&J=1,14)
      TEST NE &DUM,'Klt',FNL000
      BLET &FNTLS=&I //SAVE FOR LAST STATIO
      TRANSFER ,FNL000
FNL999 BCLOSE FNTRM
*-----
* STARTING INVENTORY
*-----
INV000 BGETLIST FILE=INVEN,&DUM //SKIP LINE
      BLET &I=0 //ZERO OUT
      BLET &I=&I+1 //BUMP
      BGETLIST FILE=INVEN,END=INV100,&DUM,&DUM2,&J,&SIN568(&I),_
      &SIN569(&I),&SIN570(&I),&SIN572(&I),&J,_
      &CUSTMR(&I),&DUM1,&ECLR(&I)
      TEST NE &CUSTMR(&I),&PRVCUS,INV005
      BLET PF(LOC1)=&I
      SPLIT 1,KEY000
      BLET &PRVCUS=&CUSTMR(&I)
      BLET PF(LOC1)=0
      BLET PF(LCTR)=LEN(&DUM) //LAST CHAR IN &DUM
INV010 TEST NE SSG(&DUM,PFSLCTR,1),'-',INV020 //FIND '-'
      LOOP LCTRSPF,INV010
INV020 BLET PF(LCTR)=PF(LCTR)+1
      BLET &PARTNO(&I)=SSG(&DUM,PFSLCTR) //TRUNCATE
      BLET PF(LCTR)=20
INV030 TEST E &DUM2,&ECLASC(PFSLCTR),INV040 //MATCH?
      BLET &ECLASI(&I)=PFSLCTR //SAVE PTR VALUE
      TRANSFER ,INV000
INV040 LOOP LCTRSPF,INV030
      TRANSFER ,INV000
INV100 BLET &I=&I-1
      BLET &NOMDLS=&I //SAVE # MODELS
      BCLOSE INVEN
*
      BLET PF(LCTR)=100 //LOOPER
      BLET PF(INDX)=0 //INDEX
      BLET PF(JNDX)=0 //COUNTER
      BLET &DUM='' //SET TO NULL

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INV110  BLET      PF(INDX)=PF(INDX)+1 //BUMP
        TEST NE   &CUSTMR(PF$INDX),'',INV120 //NULL CUSTOMER
        TEST NE   &CUSTMR(PF$INDX),&DUM,INV120
        BLET      PF(JNDX)=PF(JNDX)+1
        BLET      &CUSTID(PF$JNDX)=&CUSTMR(PF$INDX)
        BLET      &DUM=&CUSTMR(PF$INDX)
INV120  LOOP      LCTR$PF,INV110
*-----
* GET LINEUP
*-----
        BGETLIST  FILE=ALINEUP,&DUM
        BLET      &I=0
SIP000  BLET      &I=&I+1 //BUMP
        BGETLIST  FILE=ALINEUP,END=SIP100,&DUM1,MX(SHIPS,&I,2),MX(SHIPS,&I,4)
        BLET      &K=MX(SHIPS,&I,4)-1000 //SAVE TRUCK
        BLET      MX(SHIPS,&I,4)=&K
        BLET      &TRKLD(&K)=&TRKLD(&K)+MX(SHIPS,&I,2)
        BLET      PF(LCTR)=&NOMDLS //SEARCH FOR MODEL ID
SIP030  TEST NE   &PARTNO(PF$LCCTR),&DUM1,SIP040
        LOOP      LCTR$PF,SIP030 //KEEP LOOKING
        BPUTPIC   &DUM1,&I
ENGINE: * AT LINE *** NOT FOUND CORRECT IN LINEUP OR BEGINV
        TRANSFER ,SIP000
SIP040  BLET      MX(SHIPS,&I,1)=PF(LCTR) //MODEL
        BLET      &DUM1=&CUSTMR(PF$LCCTR)
        BLET      PF(LCTR)=50
SIP050  TEST NE   &DUM1,&CUSTID(PF$LCCTR),SIP060
        LOOP      LCTR$PF,SIP050
SIP060  BLET      MX(SHIPS,&I,5)=PF(LCTR) //CUSTOMER ID
        TRANSFER ,SIP000 //GO AGAIN
SIP100  BCLOSE   ALINEUP
*-----
* GET 568 CYCLE TIMES
*-----
        BGETLIST  FILE=DPT568,&DUM //SKIP LINE
        BGETLIST  FILE=DPT568,&DUM //SKIP LINE
        BGETLIST  FILE=DPT568,&DUM //SKIP LINE
CYL000  BGETLIST  FILE=DPT568,END=CYL090,&DUM,(&RPASS(&I),&I=1,3)
        BLET      PF(LCTR)=&NOMDLS
CYL010  TEST NE   &DUM,&PARTNO(PF$LCCTR),CYL020 //PART# SEARCH
        LOOP      LCTR$PF,CYL010 //CHECK MATCH
        BPUTPIC   FILE=OUT,&DUM
* * IN CYL568 NOT FOUND
        TRANSFER ,CYL000
CYL020  BLET      &I=PF(LCTR) //SAVE PART#
        BLET      &BTRIM(&I)=&RPASS(1) //BLUEBIRD TRIM TIME
        BLET      &CTRIM(&I)=&RPASS(2) //COMPRESSOR TRIM TIME
        BLET      &COPTN(&I)=&RPASS(3) //COMPRESSOR OPTION %
        TRANSFER ,CYL000
CYL090  BCLOSE   DPT568
*-----
* GET 569 CYCLE TIMES
*-----
        BGETLIST  FILE=DPT569,&DUM //SKIP LINE
        BGETLIST  FILE=DPT569,&DUM //SKIP LINE
CYL100  BGETLIST  FILE=DPT569,END=CYL190,&DUM,(&RPASS(&I),&I=1,8)
        BLET      PF(LCTR)=&NOMDLS
CYL110  TEST NE   &DUM,&PARTNO(PF$LCCTR),CYL120 //PART# SEARCH
        LOOP      LCTR$PF,CYL110 //CHECK MATCH
        BPUTPIC   FILE=OUT,&DUM
* * IN CYL569 NOT FOUND
        TRANSFER ,CYL100
CYL120  BLET      &I=PF(LCTR) //SAVE PART#
        BLET      &CTEST(&I)=&RPASS(1) //CELL TEST TIME
        BLET      &HOOK(&I)=&RPASS(2) //HOOK-UP TIME
        BLET      &UNHK(&I)=&RPASS(3) //UNHOOK TIME
        BLET      &RHOOK(&I)=&RPASS(4) //HOOK R-TIME
        BLET      &RTORK(&I)=&RPASS(5) //RETORQUE TIME
        BLET      &TCRTE(&I)=&RPASS(6) //CELL ROUTING

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      BLET      &TRJT1(&I) = &RPASS(7) //1ST TIME REJECT %
      BLET      &TRJT2(&I) = &RPASS(8) //2ND TIME REJECT %
      TRANSFER  ,CYL100
CYL190 BCLOSE  DPT569
-----
* GET 570/571 CYCLE TIMES
-----
      BGETLIST  FILE=DPT570,&DUM //SKIP LINE
      BGETLIST  FILE=DPT570,&DUM //SKIP LINE
      BGETLIST  FILE=DPT570,&DUM //SKIP LINE
CYL200 BGETLIST  FILE=DPT570,END=CYL290,&DUM, (&RPASS(&I),&I=1,2),_
      &J, (&RPASS(&I),&I=3,7)
      BLET      PF(LCTR) = &NOMDLS
CYL210 TEST NE  &DUM, &PARTNO(PF$LCCTR), CYL220 //PART# SEARCH
      LOOP     LCTRSPF, CYL210 //CHECK MATCH
*      BPUTPIC  FILE=OUT, &DUM
* * IN CYL570 NOT FOUND
      TRANSFER  ,CYL200
CYL220 BLET      &I=PF(LCTR) //SAVE PART#
      BLET      &TRIM(&I) = &RPASS(1) //TRIM TIME
      BLET      &TXFR(&I) = &RPASS(2) //PAINT TRANSFER TIME
      BLET      &BLOWO(&I) = &RPASS(3) //BLOW-OFF TIME
      BLET      &MASK(&I) = &RPASS(4) //MASK TIME
      BLET      &PCOAT(&I) = &RPASS(5) //PRIME COAT TIME
      BLET      &TCOAT(&I) = &RPASS(6) //TOP COAT TIME
      BLET      &TRM571(&I) = &RPASS(7) //FINAL TRIM TIME
      TRANSFER  ,CYL200
CYL290 BCLOSE  DPT570
-----
* GET 572 CYCLE TIMES
-----
      BLET      &I=0
      BGETLIST  FILE=DPT572, &DOCK // #DOCKS
      BSTORAGE  $$DOCKS, &DOCK
      BGETLIST  FILE=DPT572, &RECTRKS // #RECEIVING SHIPMENTS
      BGETLIST  FILE=DPT572, &DUM //SKIP LINE
CYL300 BGETLIST  FILE=DPT572, END=CYL390, &DUM, &RPASS(1), &DUM1
      TEST E    &DUM1, 'min/load', CYL300 //PART# SEARCH
      BLET      &I = &I + 1
      BLET      &STECH(&I) = &DUM //SHIPPING TECH
      BLET      &SHPTIM(&I) = &RPASS(1) //MASK/BLOW-OFF TIME
      TRANSFER  ,CYL300
CYL390 BCLOSE  DPT572
-----
* GET PAINT PARAMETERS
-----
      BGETLIST  FILE=DPT571, &LBCTPNT //PAINT LOAD BARS
      BGETLIST  FILE=DPT571, &TIMEOVEN //OVEN TIMER/LOAD BAR
      BGETLIST  FILE=DPT571, &FLASH //PAINT FLASH TIME/STOP
      BGETLIST  FILE=DPT571, &COOL //PAINT COOLDOWN/STOP
      BGETLIST  FILE=DPT571, &PNTFSP //PAINT FAST SPEED
      BGETLIST  FILE=DPT571, &PNTSSP //PAINT PROCESS SPEED
SPSPD  MACRO    PNT2, &PNTSSP
      BGETLIST  FILE=DPT571, &PCMAX //PAINT PROCESS CHAIN MAX
      BSTORAGE  $$$PNT2, &PCMAX //WASHER LIMIT
      BCLOSE   DPT571
-----
* READ IN DOWN TIME SCENARIOS
-----
      BGETLIST  FILE=DWNTIM, &DUM
      BLET      PF(INDX) = 0
DTS000 BLET      PF(INDX) = PF(INDX) + 1 //BUMP INDEX VALUE
      BGETLIST  FILE=DWNTIM, END=DTS100, &DUM, PF(JNDX), &DELAY1(PF$INDX), _
      &MTBF(PF$INDX), &DTIM(PF$INDX), PF(LCTR)
      SPLIT    1, DWT000
      TRANSFER  ,DTS000
DTS100 BCLOSE  DWNTIM
-----
* Simulation Timer Module

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* Written by G. Rehn
* 6/29/98
* Version 01
*****
* Input Operation Data
*
CTM000  BLET      &M=&CLKS/15+1           //STARTING SEGMENT
        TEST E    &M,97,*+2             //BEYOND DAY'S END
        BLET      &M=1
        BGETLIST  FILE=OPDAT,&DUM,(&OPAS(&J),&J=1,96)
        BLET      &I=0
CTM010  BLET      &I=&I+1
        TEST E    &OPAS(&I),'R',*+3
        BLET      &DFTOP(&I)=15
        TRANSFER  ,CTM020
        TEST E    &OPAS(&I),'F',*+3
        BLET      &DFTOP(&I)=5
        TRANSFER  ,CTM020
        TEST E    &OPAS(&I),'C',*+3
        BLET      &DFTOP(&I)=10
        TRANSFER  ,CTM020
        TEST E    &OPAS(&I),'A',*+3
        BLET      &DFTOP(&I)=-2
        TRANSFER  ,CTM020
        TEST E    &OPAS(&I),'E',*+3
        BLET      &DFTOP(&I)=-1
        TRANSFER  ,CTM020
        BLET      &DFTOP(&I)=CHARSTOI(&OPAS(&I))
CTM020  TEST E    &I,96,CTM010
        BLET      PF(CTR)=&M
CTM030  TEST E    &DFTOP(&M),-2,CTM040  //@SHIFT START?
        BLET      PF(CTR)=PF(CTR)+1     //SEARCH FORWARD
        BLET      PF(CTR)=FN(PCNVRT)     //POINTER CONVERT
        TEST NE   BV(DISFT),1,CTM060    //FOUND INITIAL?
        TEST NE   &DFTOP(PF(CTR)),-1,CTM050  //@END?;LOOK BACKWARDS
        TRANSFER  ,CTM030              //SEARCH FORWARD EVERYTHING ELSE
        BLET      PF(CTR)=FN(PCNVRT)     //POINTER CONVERT
CTM040  TEST NE   BV(DISFT),1,CTM060    //FOUND INITIAL SHIFT?
        TEST NE   &DFTOP(PF(CTR)),-2,CTM030  //@START?;LOOK FORWARD
CTM050  BLET      PF(CTR)=PF(CTR)-1     //REDUCE
        TRANSFER  ,CTM040
CTM060  BLET      &N=&DFTOP(PF(CTR))    //STARTING SHIFT
        BLET      &I=0                  //RESET
CTM070  BLET      &I=&I-1
CTM080  BGETLIST  FILE=OPDAT,END=CTM190,&MODID(&I),(&OPAS(&J),&J=1,96),&EFMIN(&I),_
        &OPHRS(&I),&OPSFT(&I),&WDAYS(&I),&PERF(&I)
        TEST G    &EFMIN(&I),0,CTM180    //MODULE IN PLAY?
        TEST G    &WDAYS(&I),&WEEK,*+2   //WORK DAYS>WEEK?
        BLET      &WEEK=&WDAYS(&I)      //YES;NEW WEEK DEFINITION
        TEST E    &OPAS(1),'D',CTM100   //DEFAULT?
        BLET      &J=0
CTM090  BLET      &J=&J+1                //BUMP POINTER
        BLET      MH(HPS,&I,&J)=&DFTOP(&J)
        TEST E    &J,96,CTM090
        BLET      &MSHIFT(&I)=&N        //TAG INITIAL SHIFT
        TRANSFER  ,CTM180
        BLET      &J=0
CTM100  BLET      &J=&J+1
CTM110  TEST E    &OPAS(&J),'B',*+3
        BLET      MH(HPS,&I,&J)=15
        TRANSFER  ,CTM120
        TEST E    &OPAS(&J),'F',*+3
        BLET      MH(HPS,&I,&J)=5
        TRANSFER  ,CTM120
        TEST E    &OPAS(&J),'C',*+3

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      BLET      MH(HPS,&I,&J)=10
      TRANSFER ,CTM120
      TEST E    &OPAS(&J),'A',*+3
      BLET      MH(HPS,&I,&J)=-2
      TRANSFER ,CTM120
      TEST E    &OPAS(&J),'E',*+3
      BLET      MH(HPS,&I,&J)=-1
      TRANSFER ,CTM120
      TEST E    &OPAS(&J),'S',*+3          //INDICATES SWING OPERATION
      BLET      MH(HPS,&I,&J)=99
      TRANSFER ,CTM120
      BLET      MH(HPS,&I,&J)=CHARSTOI(&OPAS(&J))
      CTM120    TEST E    &I,96,CTM110
      .
      BLET      PF(CTR)=&M
      TEST E    MH(HPS,&I,PF(CTR)),-2,CTM140 //@SHIFT START?
      CTM130    BLET      PF(CTR)=PF(CTR)+1    //SEARCH FORWARD
      BLET      PF(CTR)=FN(PCNVRT)          //POINTER CONVERT
      TEST NE   BV(TISFT),1,CTM160          //FOUND INITIAL?
      TEST NE   MH(HPS,&I,PF(CTR)),-1,CTM150 //@END?'LOOK BACKWARDS
      TRANSFER ,CTM130                      //SEARCH FORWARD EVERYTHING ELSE
      .
      CTM140    BLET      PF(CTR)=FN(PCNVRT)          //POINTER CONVERT
      TEST NE   BV(TISFT),1,CTM160          //FOUND INITIAL SHIFT?
      TEST NE   MH(HPS,&I,PF(CTR)),-2,CTM130 //@STAR?;LOOK FORWARD
      CTM150    BLET      PF(CTR)=PF(CTR)-1          //REDUCE
      TRANSFER ,CTM140
      CTM160    BLET      &MSHIFT(&I)=MH(HPS,&I,PF(CTR)) //TAG INITIAL SHIFT
      .
      CTM180    TEST E    &I,10,CTM080          //FINISH READ
      CTM190    BCLOSE   OPDAT
      .....
      * READ IN TECHNICIAN DATA
      .
      BLET      PF(PLOC)=0                    //ZERO OUT FOR SWING ID
      BGETLIST  FILE=TECHS,&DUM
      TIN000    BGETLIST  FILE=TECHS,END=DIN000,ERR=DIN000,PF(TECHN),&TCHNM(PFSTECHN),_
      &DUM,&DUM1,PF(SHFT),(&CPASS(&J).&J=1,6)
      TEST NE   &TCHNM(PFSTECHN),'0',DIN000
      TEST E    &DUM1,'Y',TIN000            //TECH IN PLAY?
      BLET      PF(MOD)=10                    //MOD SEARCH
      TIN010    TEST NE   &DUM,&MODID(PFSMOD),TIN020 //MODULE MATCH
      LOOP      MODSPF,TIN010                //KEEP LOOKING
      TRANSFER ,DIN000
      TIN020    BLET      PF(LCTR)=6
      TIN025    TEST NE   &CPASS(PFSLCTR),'0',TIN060
      BLET      PF(INDX)=0
      TIN030    BLET      PF(INDX)=PF(INDX)+1
      TEST NE   &CPASS(PFSLCTR),&SNAME(PFSINDX),TIN040
      TRANSFER ,TIN030
      TIN040    BLET      PF(PFSLCTR+20)=PF(INDX)
      TIN060    LOOP      LCTRS PF,TIN025
      TIN070    BLET      &K=V(ANYOP)          //SUM OF ALL OPERATIONS
      TEST G    &K,0,TIN000                  //IF ZERO; NO TECH
      BLET      &TLAST=PFSTECHN
      BLET      &TCC=&TCC+1                    // #TECHNICIAN
      BLET      MX(TCHASN,PFSTECHN,1)=PF(MOD) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,2)=PF(SHFT) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,3)=PF(LOC1) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,4)=PF(LOC2) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,5)=PF(LOC3) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,6)=PF(LOC4) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,7)=PF(LOC5) //SAVE ASSIGNMENTS
      BLET      MX(TCHASN,PFSTECHN,8)=PF(LOC6) //SAVE ASSIGNMENTS
      TIN080    TEST E    MH(TCH1,PFSMOD,PFSSHFT),0,*+2 //ANY VALUE HERE?
      BLET      MH(TCH1,PFSMOD,PFSSHFT)=PF(TECHN)+TCHNS //NO;MUST BE FIRST
      BLET      MH(TCHL,PFSMOD,PFSSHFT)=PF(TECHN)+TCHNS //CURRENT=LAST
      TEST E    &MODID(PFSMOD),'569S',TIN090 //SWING SHIFT?
      BLET      PF(PLOC)=PF(PLOC)+1          //BUMP COUNTER

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TIN090  SPLIT      1,TCH000                //CREATE XACT
        TEST E    PF(PLOC) ,2, *+2        //SECOND?
        BLET      PF(PLOC)=0              //YES;RESET
        PRIORITY  -1,YIELD                 //XACT GET THERE
        PRIORITY  0
        BLET      PF(LOC1)=0              //ZERO OUT FOR NEXT READ
        BLET      PF(LOC2)=0              //ZERO OUT FOR NEXT READ
        BLET      PF(LOC3)=0              //ZERO OUT FOR NEXT READ
        BLET      PF(LOC4)=0              //ZERO OUT FOR NEXT READ
        BLET      PF(LOC5)=0              //ZERO OUT FOR NEXT READ
        BLET      PF(LOC6)=0              //ZERO OUT FOR NEXT READ
        TRANSFER  ,TIN000                 //LOOP AGAIN
*-----*
* DONE INPUTING - INITILIZE SYSTEM/CREATE REMAINING ACTIVE ENTITIES
*-----*
DIN000  BCLOSE    TECHS
WRITE   MACRO     TESTID,&TESTID
WRITE   MACRO     TESTDSCR,&TESTDSCR
        BLET      PF(LCTR)=&LBCTMAIN      //TOTAL # LOAD BARS IN SYSTEM
        TRANSFER  ,DIN130
*
* 572 INVENTORY
*
DIN010  BLET      PF(ENGINE)=99           //START 572 INITILIZATION
        TEST G    &SIN572(PFSENGINE),0,DIN020 //ANY OF THIS ENGINE?
        BLET      &INV572(PFSENGINE)=&SIN572(PFSENGINE) //YES;INIT
        BLET      &INV572(100)=&INV572(100)+&SIN572(PFSENGINE)
        SPLIT     &SIN572(PFSENGINE),FIN060 //ENGINE TO FINISHED
        ENTER     TOTALQ,&SIN572(PFSENGINE)
        PRIORITY  -1,YIELD
        PRIORITY  0
DIN020  LOOP      ENGINESPF,DIN010        //KEEP LOOPING
WRITE   MACRO     IV572,&INV572(100)      //INITILIZE #
BARG    MACRO     IVB,RIGHT,&INV572(100)
        TRANSFER  ,DIN130
*
*
* 570 INVENTORY
*
        BLET      &DUM='570'
        TRANSFER  SBR,FNDMOD,SUBRSPF
        BLET      PF(ENGINE)=0            //ENGINES
        BLET      PF(PTR)=50              //570 ENGINES ON FLOOR
DIN030  BLET      PF(ENGINE)=PF(ENGINE)+1
        BLET      PF(CTR)=&SIN570(PFSENGINE) // #AVAILABLE
        TEST G    PF(CTR),0,DIN060        // > 0?
        TEST G    PF(PTR),0,DIN045        //FINISHED W/ FLOOR?
        BLET      PF(PTR)=PF(PTR)-PF(CTR) //REDUCE FLOOR COUNT
DIN040  SPLIT     1,ISP000                //TO INSPECT
        BLET      &INPROC=&INPROC+1      //COUNT IN PROCESS
        ENTER     EWIPQ
        ENTER     TOTALQ
        ADVANCE   .1
        LOOP      CTRSFF,DIN040
        TRANSFER  ,DIN060
ISP000  TERMINATE
*
DIN045  BLET      PF(LCTR)=PF(LCTR)-PF(CTR) //CONSUME LOAD BARS
DIN050  BLET      &INPROC=&INPROC+1      //COUNT IN PROCESS
        ENTER     EWIPQ
        ENTER     TOTALQ
        GATE SNF  SOUT
        SPLIT     1,ITT000                //CREATE ENGINE
        ADVANCE   .1                      //CLEARANCE
        LOOP      CTRSFF,DIN050
DIN060  TEST GE   PFSENGINE,99,DIN030    //MORE ENGINES
*
* 569 INVENTORY
*

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      BLET      &DUM='569'
TRANSFER     SBR,FNDMOD,SUBRSPF
      BLET      PF(ENGINE)=0          //ENGINES
DIN070      BLET      PF(ENGINE)=PF(ENGINE)+1
      BLET      PF(CTR)=&SIN569(PFSENGINE) // #AVAILABLE
      TEST G     PF(CTR),0,DIN090      //> 0?
      BLET      PF(LCTR)=PF(LCTR)-PF(CTR)
DIN080      BLET      &INPROC=&INPROC+1    //COUNT IN PROCESS
      ENTER     EWIPQ
      ENTER     TOTALQ
      GATE SNF   SPI
      SPLIT     1,ITC000                //CREATE ENGINE
      ADVANCE   .1                      //CLEARANCE
      LOOP     CTRSPF,DIN080
DIN090      TEST GE   PFSENGINE,99,DIN070    //MORE ENGINES
*
* 568 INVENTORY
*
      BLET      &DUM='568'
TRANSFER     SBR,FNDMOD,SUBRSPF
      BLET      PF(ENGINE)=0          //ENGINES
DIN100      BLET      PF(ENGINE)=PF(ENGINE)+1
      BLET      PF(CTR)=&SIN568(PFSENGINE) // #AVAILABLE
      TEST G     PF(CTR),0,DIN120      //> 0?
      BLET      PF(LCTR)=PF(LCTR)-PF(CTR)
      BLET      PF(RJCT)=0            //ZERO OUT REJECT INDICATOR
      TEST E     &CTRIM(PFSENGINE),0,DIN110 //COMPRESSOR ENGINE?
      TEST E     &BTRIM(PFSENGINE),0,DIN110 //NO;BLUEBIRD?
      BLET      PF(RJCT)=1            //MUST BE REJECT
DIN110      BLET      &INPROC=&INPROC+1    //COUNT IN PROCESS
      ENTER     EWIPQ
      ENTER     TOTALQ
      GATE LC    260
      SPLIT     1,ITR000                //CREATE ENGINE
      ADVANCE   .1                      //CLEARANCE
      LOOP     CTRSPF,DIN110
DIN120      TEST GE   PFSENGINE,99,DIN100    //MORE ENGINES
*
DIN130      SPLIT     1,CNV000          //START MAIN DELIVERY CONV.
      PRIORITY   -1,YIELD
      PRIORITY   0
      SPLIT     1,LIN000                //START ASSEMBLY LINE
      PRIORITY   -1,YIELD
      PRIORITY   0
      GATE LS    DINIT
      BLET      PF(MOD)=-1
      SPLIT     10,TMR000,MODSPF        //CREATE MODULE CONTROLS
      PRIORITY   -1,YIELD
      PRIORITY   0
*-----
* MAIN XACT EXECUTES CLOCK
* CLOCK MOVEMENT
* DAY STARTS AT      &CLKS
*-----
CLK000      BLET      &AMP(1)='AM'      //INITIALIZE AM/PM VAR
      BLET      &AMP(2)='PM'          //INITIALIZE AM/PM VAR
      BLET      PF1=&CLKS/60           // #HOURS INITIAL OFFSET
      BLET      PF2=&CLKS@60           // #MINS. INITIAL OFFSET
      BLET      PF3=&CLKS/15           // #CLOCK LOOPS
      BLET      PL1=PF1@12             //MODULUS OF 12
      BLET      PL2=PF2                //MAKE REAL #
      TEST L     PF3,48,CLK005         //START IN MORN OR AFTERNOON?
      LOGIC C    MORN                  //YES; MORNING
      BLET      PL3=(48-PF3)*15        //TIME AM/PM SWITCH
      TRANSFER   ,CLK010
CLK005      LOGIC S    MORN              //NO;AFTERNOON
      BLET      PL3=(96-PF3)*15
CLK010      BLET      PF4=LS(MORN)+1    //AM/PM POINTER
WRITE      MACRO     DST,&AMP(PF4)      //AM/PM INDICATOR

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        BLET          PL1=(PL1/12+PL2/720)*130.85 //HOUR HAND OFFSET
        BLET          PL2=(PL2/60)*130.85 //MIN. HAND OFFSET
PLONAT  MACRO        'MHND',TYMM,PL2 //INITIAL SET MINUTE HAND
PLONAT  MACRO        'HHND',TYMH,PL1 //INITIAL SET MINUTE HAND
        ADVANCE      PL3 //INITIAL TIME TO AM/PM SWITCH
CLK020  LOGIC I      MORN //INVERT AM/PM
        BLET          PF4=LS(MORN)+1 //AM/PM POINTER
WRITE   MACRO        DST,&AMPM(PF4) //AM/PM INDICATOR
        ADVANCE      720 //NEXT 12 HRS
        TRANSFER     ,CLK020

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 * MODULE OPERATION CONTROL

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TMR000  TEST G      &EFMIN(PFSMOD),0,TMRSTP //MOD IN OPERATION?
        BLET        PF(SHFT)=&MSHIFT(PFSMOD) //YES;GET INITIAL SHIFT
        TEST NE     PF(MOD),1,JOPO00
        TEST NE     PF(SHFT),0,TMRADV //ACTIVE SHIFT?
        BLET        PF(OPER1)=MH(TCH1,PFSMOD,PFSHFT) //FIRST FACILITY
        BLET        PF(OPERL)=MH(TCHL,PFSMOD,PFSHFT) //LAST FACILITY
FUNAVAIL PF(OPER1)-PF(OPERL) //SHUT EVERYONE OFF
        BLET        PF(CTR)=&CLKS/15+1 //STARTING SEGMENT
        BLET        PF(CTR)=FN(PCNVRT)
        BLET        PF(PTR)=MH(HPS,PF(MOD),PF(CTR)) //CURRENT SEGMENT VALUE
        TEST G      PF(PTR),0,TMRINT //CHECK FOR START/STOP
        TEST LE     PF(PTR),3,TMRINT //IN OPERATION?
        FAVAIL      PF(OPER1)-PF(OPERL) //PUT IN PLAY
TRANSFER SBR,FACLR,SUBRSPF //CHANGE OPER COLORS
TMRADV  ADVANCE      15 //TIME ADVANCE
TMR010  BLET        PF(CTR)=PF(CTR)+1 //BUMP SEGMENT
        BLET        PF(CTR)=FN(PCNVRT) //YES;RESET
        TRANSFER     ,FN(TMDIR) //PROCEED
*
TMRINT  TEST NE     PF(PTR),-2,TMRBEG //@ START SHIFT
        FAVAIL      PF(OPER1)-PF(OPERL) //PUT IN PLAY
TRANSFER SBR,FACLR,SUBRSPF //CHANGE TECH COLORS
TRANSFER ,FN(TMDIR) //PROCEED
*
* START OF SHIFT
*
TMRBEG  TEST E      &SDAY@&WEEK,0,*+2 //END OF WEEK?
        TEST E      &WDAYS(PFSMOD),&WEEK,TMRWKE //YES;WORK THE WEEKEND?
        BLET        &ACNOOP(PFSMOD)=&ACNOOP(PFSMOD)+&SALOW //START-UP
        BLET        &ACNOOP(PFSMOD)=&ACNOOP(PFSMOD)+MPSWAITSPL //OFFTIME
        BLET        PF(PTR)=MH(HPS,PF(MOD),PF(CTR)) //CURRENT SEGMENT VALUE
        ADVANCE      &SALOW //DO STARTUP ALLOWANCE
        BLET        PF(SHFT)=PF(CTR) //CURRENT POSITION
TMR015  BLET        PF(SHFT)=PF(SHFT)+1 //BUMP POINTER
        TEST E      PF(SHFT),97,*+2 //END OF ROAD?
        BLET        PF(SHFT)=1 //YES;REST TO 1
        TEST G      MH(HPS,PFSMOD,PFSHFT),0,TMR015 //IN OPERATION?
        TEST LE     MH(HPS,PFSMOD,PFSHFT),3,TMR015 //NOT A BREAK?
        BLET        PF(SHFT)=MH(HPS,PFSMOD,PFSHFT) //FOUND NEXT SHIFT
        TEST NE     PF(MOD),1,JOPO10 //564 MODULE
        BLET        PF(OPER1)=MH(TCH1,PFSMOD,PFSHFT) //FIRST FACILITY
        BLET        PF(OPERL)=MH(TCHL,PFSMOD,PFSHFT) //LAST FACILITY
        FAVAIL      PF(OPER1)-PF(OPERL) //START-UP
TRANSFER SBR,FACLR,SUBRSPF //CHANGE TECH COLOR
        BLET        &MD=PF(MOD) //SAVE MODULE
        BLET        &SF=PF(SHFT) //SAVE SHIFT
        UNLINK      IPOOL,TMR030,ALL,BVSSFTCO //SHIFT CHANGE-OVER
TMR020  ADVANCE      15-&SALOW //PROCEED
        TRANSFER     ,TMR010
*
TMR030  TEST E      &MODID(PFSMOD),'569',TMR040
        SPLIT       1,ATS000 //DETERMINE ACTIVE CELLS
        TRANSFER     ,TCH160
*
TMR040  TEST E      &MODID(PFSMOD),'569S',TCH160
        TEST NE     PF(PLOC),2,TCH400

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SPLIT      1,ATS000                //DETERMINE ACTIVE CELLS
TRANSFER   ,TCH160

*
TMRBRK    FUNAVAIL PF(OPER1)-PF(OPERL) //OPERATOR BREAK
TRANSFER   SBR,FUNCLR,SUBRS$PF //CHANGE TECH COLOR
TMR050    TEST E    MH(HPS,PF(MOD),PF(CTR)),15,SBREK //MIN TMRBRK?
          BLET     &ACNOOP(PFSMOD) =&ACNOOP(PFSMOD)+15
          ADVANCE  15 //DO 15 MIN. TMRBRK
          BLET     PF(CTR)=PF(CTR)+1 //BUMP SEGMENT
          BLET     PF(CTR)=FN(PCNVRT) //YES;RESET
          TEST NE  MH(HPS,PF(MOD),PF(CTR)),99,TMR055 //STILL ON BREAK?
          TEST LE  MH(HPS,PF(MOD),PF(CTR)),3,TMR050 //STILL ON BREAK?
TMR055    FAVAIL   PF(OPER1)-PF(OPERL) //NO;BACK IN OPERATION
TRANSFER   SBR,FACLR,SUBRS$PF
TRANSFER   ,FN(TMDIR)

*
SBREK     ADVANCE  MH(HPS,PF(MOD),PF(CTR)) //SHORT TMRBRK
          BLET     &ACNOOP(PFSMOD) =&ACNOOP(PFSMOD)+MH(HPS,PF(MOD),PF(CTR))
          FAVAIL   PF(OPER1)-PF(OPERL) //BACK IN OPERATION
TRANSFER   SBR,FACLR,SUBRS$PF
ADVANCE  15-MH(HPS,PF(MOD),PF(CTR)) //RESUME
TRANSFER   ,TMR010

*
TMREND    TEST E    &MODID(PFSMOD), '569', *+2
          UNLINK   ACELLS,ACTS100,ALL //ACTIVE CELLS
          ADVANCE  15-&CALOW //CLEAN-UP ALLOWANCE
          TEST NE  PF(MOD),1,JOP130 //564 CONTROL?
          UNLINK   PDLAY,TMR100,ALL,MODSPF,PFSMOD //REORDER WAITING XACTS
          UNLINK   NOTCH,TMR100,ALL,MODSPF,PFSMOD //REORDER WAITING XACTS
          LOGIC C  MATCH
          TEST NE  &MODID(PFSMOD), '569S',TMR091
          BLET     PF(LCTR)=PF(OPERL)-PF(OPER1)+1 // # OPERATORS
          BLET     PFSJNDX=PF(OPER1) //STARTING OPR. INDEX
TMR080    BLET     PFSJNDX=&OPXID(PFSJNDX-TCHNS) //GET OBJECT ID
          TEST G   PF(INDX),0,TMR085
SCOLOR    MACRO    PFSJNDX, 'BAC'
          PREEMPT PF(JNDX),,TMR200.CYCLESPL //INTERRUPT TECH IN ACTION
          PRIORITY -1,YIELD
          PRIORITY 0
          RETURN   PF(JNDX)
TMR085    BLET     PFSJNDX=PFSJNDX+1 //BUMP POINTER
          LOOP     LCTRSPF,TMR080 //CONTINUE
          UNLINK   APOOL,TMR300,ALL,MODSPF,PFSMOD
          UNLINK   HOLD,TMR150,ALL //RELEASE HELD XACTS
TMR090    FUNAVAIL PF(OPER1)-PF(OPERL) //OPERATOR TMRBRK
          ADVANCE  &CALOW //DO CLEAN-UP
          BLET     &ACNOOP(PFSMOD) =&ACNOOP(PFSMOD)+&CALOW
          MARK     WAITSPL //COLLECT STOPPAGE TIME
          BLET     PF(PTR)=0
          TRANSFER ,TMR010

*
TMR091    BLET     PF(JNDX)=PF(OPERL)
          BLET     PF(LCTR)=1
          TRANSFER ,TMR080

*
* SHIFT CHANGEOVER LOGIC
*
TMR100    LINK     HOLD,FIFO //STAGE TEMPORARILY
TMR150    LINK     NOTCH,FIFO //REORDER

*
TMR200    ALTERUCH E INPRO,1,CYCLESPL,PLSCYCLE,CLOCSPF,PFSCLC
          ALTERUCH E INPRO,1,OPNUMSPF,PFSOPNUM,CLOCSPF,PFSCLC
          REMOVE   ATECHS
          RELEASE  PF(TECHN)+TCHNS //NO;RELEASE
          BLET     PL(CMPEST)=0
          UNLINK   INPRO,TMR150,1,CLOCSPF,PFSCLC
PLON      MACRO    XID1,TECHSTG
TMR300    LINK     IPOOL,FIFO

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TMRSWG  UNLINK E  APOOL,TCH500,1,TECHNSPF,(PFSOPER1-TCHNS),TMR400
TRANSFER ,TMRADV
TMR400  ALTER E  ATECHS,1,OPER1SPF,-99,TECHNSPF,(PFSOPER1-TCHNS)
TRANSFER ,TMRADV
*
* WEEKEND STOPPAGE
*
TMRWKE  BLET      PFI=&SDAY
ADVANCE 1440
TEST NE  PFI,&SDAY
TRANSFER ,TMRBEG
*
* DETERMINE ACTIVE CELLS
*
ATS000  BLET      PF(LCTR)=2 //CHECK 1ST 2 ASNS ONLY
ATS010  BLET      PF(DELRT)=PF(20+PFSLCTR) //POINT TO POSSIBLE STA
TEST G   PF(DELRT),40,ATS020 //TEST CELL STATION
TEST LE  PF(DELRT),63,ATS020 //MAX. TEST CELL
SPLIT   1,ATS050
ATS020  LOOP      LCTRSPF,ATS010
ATS030  TERMINATE
*
ATS050  GATE LC   PF(DELRT),ATS030 //ALREADY ACTIVE?
LOGIC S  PF(DELRT) //NO;NOW IS
GATE LS  81,*-2
LOGIC C  81
GATE LS  87,*-2
LOGIC C  87
BLET     PF(DELRT)=PF(DELRT)-40 //ADJUST POINTER
LINK     ACELLS,FIFO //ON ACTIVE CHAIN
ATS100  LOGIC C  PF(DELRT)-40 //RESET TO INACTIVE
TERMINATE
*
* TECHNICIAN COLOR SUBROUTINES
*
FACLR   TEST NE  PF(MOD),1,JOP120 //564?
BLET    PF(LCTR)=PF(OPERL)-PF(OPER1)+1 //# OPERATORS
BLET    PFSJNDX=PF(OPER1) //STARTING OPR. INDEX
CLR010  BLET     PFSJNDX=&OPXID(PFSJNDX-TCHNS) //GET OBJECT ID
TEST G  PF(INDX),0,CLR015
SCOLOR  MACRO    PFSJNDX,&COPR(PFSJNDX-TCHNS)
CLR015  BLET     PFSJNDX=PFSJNDX+1 //BUMP POINTER
LOOP    LCTRSPF,CLR010 //CONTINUE
TRANSFER ,PF(SUBR)+1 //RETURN
*
FUNCLR  TEST NE  PF(MOD),1,JOP110 //564?
BLET    PF(LCTR)=PF(OPERL)-PF(OPER1)+1 //# OPERATORS
BLET    PFSJNDX=PF(OPER1) //STARTING OPR. INDEX
CLR020  BLET     PFSJNDX=&OPXID(PFSJNDX-TCHNS) //GET OBJECT ID
TEST G  PF(INDX),0,CLR025
SCOLOR  MACRO    PFSJNDX,'LAYOUT'
CLR025  BLET     PFSJNDX=PFSJNDX+1 //BUMP POINTER
LOOP    LCTRSPF,CLR020 //CONTINUE
TRANSFER ,PF(SUBR)+1 //RETURN
*
TMRSTP  TERMINATE //INACTIVE MODULE
*
* KEY OBJECT CREATION
*
KEY000  BLET      &KEYCNT=&KEYCNT+1
CREATE  MACRO     KEY,XID1
WRITEO  MACRO     KEYID,XID1,&CUSTMR(PFSLOC1)
SCOLOR  MACRO     XID1,&ECLR(PFSLOC1)
BLET    PF(LOC2)=250-(10*&KEYCNT)
PLACEAT MACRO     XID1,0,PFSLOC2
TERMINATE
*
* 564 SPECIAL CONTROL
*

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```

JOP000  BLET      PF(OPER1)=200                //FIXED 1ST
        BLET      PF(OPERL)=260                //FIXED LAST
        BLET      PF(CTR)=&CLKS/15+1          //STARTING SEGMENT
        BLET      PF(CTR)=FN(PCNVRT)
        BLET      PF(PTR)=MH(HPS,PF(MOD),PF(CTR)) //CURRENT SEGMENT VALUE
        FUNAVAIL  PF(OPER1)-PF(OPERL)
SPSPD   MACRO     JHK6,0
SPSPD   MACRO     JHK7,0
        BLET      &SSP=&JHSPD(1)                //INITIAL SPEED
        TEST NE   PF(PTR),0,TMRADV              //OFFSHIFT START
        TEST LE   PF(PTR),3,FN(TMDIR)          //ON BREAK START
        TEST NE   PF(PTR),-2,TMRBEG           //@BEGINNING SHIFT START
        FAVAIL    PF(OPER1)-PF(OPERL)          //ALL ELSE IN PLAY
        BLET      &SSP=&JHSPD(PFSSHFT)         //SET SPEED
SPSPD   MACRO     JHK6,&SSP
SPSPD   MACRO     JHK7,&SSP
        TRANSFER  ,FN(TMDIR)
*
JOP010  BLET      PF(LCTR)=260
        FAVAIL    PF(OPER1)-PF(OPERL)          //PUT IN PLAY
JOP020  TEST GE   PF(LCTR),212,JOP030
        PREEMPT  PF(LCTR),,JOP100,CYCLESPL    //PREEMPT & SAVE CYCLE
        LOOP     LCTR$PF,JOP020
JOP030  PRIORITY -1,YIELD
        PRIORITY 0
        BLET      PF(LCTR)=260                //RETURN CONTROL
JOP040  TEST GE   PF(LCTR),212,JOP050
        RETURN   PF(LCTR)
        LOOP     LCTR$PF,JOP040
JOP050  ALTERUCH NE 212,ALL,SHFT$PF,PFSSHFT,SHFT$PF,PFSSHFT
        BLET      &CYADJ=&SSP/&JHSPD(PFSSHFT) //ADJUST TO NEW LS
        UNLINK   212,JOP060,ALL
        BLET      &SSP=&JHSPD(PFSSHFT)
SPSPD   MACRO     JHK6,&SSP
SPSPD   MACRO     JHK7,&SSP
        TRANSFER  ,TMR020                    //RETURN
*
JOP060  BLET      PL(CYCLE)=PL(CYCLE)*&CYADJ  //ADJUST TIME
        TEST E    PL(ETIME),1,JHK035          //DIRECT ACCORDING TO STATUS
        TRANSFER  ,JHK031
*
JOP100  LINK      212,FIFO
*
JOP110  ADVANCE   0
SPSPD   MACRO     JHK6,0
SPSPD   MACRO     JHK7,0
        TRANSFER  ,PF(SUBR)+1
*
JOP120  ADVANCE   0
SPSPD   MACRO     JHK6,&SSP
SPSPD   MACRO     JHK7,&SSP
        TRANSFER  ,PF(SUBR)+1
*
JOP130  ADVANCE   0
SPSPD   MACRO     JHK6,0
SPSPD   MACRO     JHK7,0
        TRANSFER  ,TMR090
*
*  INITIALIZATION STATUS
*
ITT000  ENTER     SOUT
CREATE  MACRO     LBR,XID1
SCOLOR  MACRO     XID1,&ECLR(PF$ENGINE)
PLON    MACRO     XID1,OUT
*      TRANSFER  ,ITT100
*
ITC000  ENTER     SP1
CREATE  MACRO     LBR,XID1
SCOLOR  MACRO     XID1,&ECLR(PF$ENGINE)

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PLON      MACRO      XID1,P1
*         TRANSFER   ,CNV100
*
ITR000    LOGIC S    260
          ENTER      260
          ENTER      SPO
CREATE    MACRO      LBR,XID1
          TEST NE    PF(ENGINE),0,ITR010
SCOLOR    MACRO      XID1,&ECLR(PFSENGINE)
*         TRANSFER   ,RPH001
ITR010    ADVANCE    0
SCOLOR    MACRO      XID1,'WHITE'
*         TRANSFER   ,RPH001
*
ITE000    ENTER      PF(CVSEC)
CREATE    MACRO      LBR,XID1
PLON3     MACRO      XID1,P,PF(CVSEC)
*         TRANSFER   ,EMPO50
*
-----
* CREATION OF ACTIVE TECHNICIAN XACTS
-----
TCH000    BLET       &OPXID(PFSTECHN)=XID1 //SAVE XACT#
CREATE    MACRO      TECH,XID1
WRITE0    MACRO      TID,XID1,PF(TECHN)
PLON      MACRO      XID1,TECHSTG
          TEST E     PF(SHFT),&MSHIFT(PFSMOD),TCH010
          BLET       &COPR(PFSTECHN)='LAY'
SCOLOR    MACRO      XID1,'LAY'
          TEST NE    PF(PLOC),2,TCH400 //2ND ASSIGNMENT
          SPLIT     1,ATS000 //ACTIVE CELL LOGIC
          LINK       APOOL,FIFO //PLACE IN ACTIVE POOL
TCH010    BLET       &COPR(PFSTECHN)='BAC'
SCOLOR    MACRO      XID1,'BAC'
PLON      MACRO      XID1,TECHSTG
          LINK       IPOOL,FIFO //PLACE IN INACTIVE POOL
TCH100    SEIZE     PF(TECHN)+TCHNS //GRAB OPERATOR
          BLET       PF(OPNUM)=-1 //ASSIGNED
          JOIN       ATECHS //IN ACTIVE GROUP
          TEST E     PL(CMPEST),0,*+2
          BLET       PL(CMPEST)=PL(CYCLE)+AC1
          MARK       WAIT$PL
          BLET       PL(ACMBRK)=&ACNOOP(PFSMOD)
          BLET       &COPR(PFSTECHN)='GREEN' //SET CURRENT COLOR
SCOLOR    MACRO      XID1,'GREEN' //IN OPERATION
PLON3     MACRO      XID1,STA,PF(CLOC)
TCH110    TEST NE    PF(CLOC),PNTTC,TCH600 //NEW PAINT PROCESS?
          ADVANCE    PL(CYCLE) //WORK ELEMENT
SCOLOR    MACRO      XID1,'WHITE'
TCH115    BLET       &COPR(PFSTECHN)='WHITE'
          TEST NE    PL(CMPEST),-1,TCH120 //HELPER DOESN'T ADJUST COUNT
          BLET       &TECHC(PF$CLOC)=&TECHC(PF$CLOC)-1
          UNLINK     INPRO,PRO220,1,CLOCSPF,PF$CLOC //FREE ELEMENT
          PRIORITY   -1,YIELD
          PRIORITY   0
TCH120    RELEASE   PF(TECHN)+TCHNS //NO;RELEASE
          BLET       PL(CMPEST)=0 //RESET HELPER INDICATOR
          REMOVE     ATECHS
*
          BLET       PLSWAIT=MPSWAIT$PL-(&ACNOOP(PFSMOD)-PLSACMBRK) //OP TIME
          BLET       PF(NOOPR)=26
TCH130    TEST NE    PF(CLOC),PF(PFSNOOPR),TCH140
          LOOP       NOOPR$PF,TCH130
TCH140    BLET       PF(NOOPR)=PF(NOOPR)-20
          BLET       ML(TECHBD,PFSTECHN,PFSNOOPR)=ML(TECHBD,PFSTECHN,PFSNOOPR)+PL$WAIT
          BLET       ML(TECHBD,PFSTECHN,7)=ML(TECHBD,PFSTECHN,7)+PL$WAIT
          TEST NE    PF(OPER1),-99,TCH500 //TAGGED TO MOVE?
*
TCH160    TEST NE    CH(NOTCH),0,TCH300 //NO;ANY DELINQUENT UNITS?
          GATE LC    MATCH

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LOGIC S MATCH
BLET &LOC(1)=PFSLOC1
BLET &LOC(2)=PFSLOC2
BLET &LOC(3)=PFSLOC3
BLET &LOC(4)=PFSLOC4
BLET &LOC(5)=PFSLOC5
BLET &LOC(6)=PFSLOC6
* UNLINK NOTCH,PRO305,1,BVSDLAY1,,TCH320
BLET PF(LCTR)=6
TCH161 TEST G &LOC(PFSLCTR),0,TCH162 //NON 0 LOC?
UNLINK NOTCH,PRO305,1,CLOCSPF,&LOC(PFSLCTR),TCH162 //FIND MATCH LOC
BLET PL(CPEST)=0 //ONE DISCOVERED
TRANSFER ,TCH163 //GET OUT OF LOOP
TCH162 LOOP LCTRSPF,TCH161
TRANSFER ,TCH320
TCH163 GATE LC MATCH
UNLINK PDLAY,PRO310,1,CLOCSPF,PFSLOC1,TCH170
BLET PF(OPNUM)=PF(LOC1)*1000
LINK APOOL,FIFO
TCH170 UNLINK PDLAY,PRO310,1,CLOCSPF,PFSLOC2,TCH180
BLET PF(OPNUM)=PF(LOC2)*1000
LINK APOOL,FIFO
TCH180 UNLINK PDLAY,PRO310,1,CLOCSPF,PFSLOC3,TCH190
BLET PF(OPNUM)=PF(LOC3)*1000
LINK APOOL,FIFO
TCH190 UNLINK PDLAY,PRO310,1,CLOCSPF,PFSLOC4,TCH200
BLET PF(OPNUM)=PF(LOC4)*1000
LINK APOOL,FIFO
TCH200 UNLINK PDLAY,PRO310,1,CLOCSPF,PFSLOC5,TCH210
BLET PF(OPNUM)=PF(LOC5)*1000
LINK APOOL,FIFO
TCH210 UNLINK PDLAY,PRO310,1,CLOCSPF,PFSLOC6,TCH300
BLET PF(OPNUM)=PF(LOC6)*1000
TCH300 BLET PL(CPEST)=0 //ZERO OUT HELPER ID
TEST NE &MODID(PFSMOD),'570',TCH550 //570 HELPS
TEST NE &MODID(PFSMOD),'571',TCH550
TCH310 LINK APOOL,FIFO //BACK IN TECH POOL
*
TCH320 LOGIC C MATCH //DELAY NOT FOUND
TRANSFER ,TCH300 //GO BACK ON POOL
*
TCH400 LINK SWING,FIFO //STAGE 2ND OPS
TCH410 SPLIT 1,ATS000 //PUT INTO PLAY
TRANSFER ,TCH160 //GO LOOK FOR WORK
*
TCH500 UNLINK SWING,TCH410,1,PLOCSPF,2 //RELEASE ALTER EGO
SCOLOR MACRO XID1,'BAC'
PLON MACRO XID1,TECHSTG
BLET PF(OPER1)=0 //RESET TAG
BLET PF(LCTR)=6 //SEARCH ASSIGNMENTS
TCH510 BLET PF(DELRT)=PF(PFSLCTR+20) //FIND ASSIGNMENT
TEST G PF(DELRT),40,TCH520 //CHECK FOR CELLS & RTQ
TEST LE PF(DELRT),63,TCH520
UNLINK ACELLS,ATS100,1,DELRTSPF,(PFSDELRT-40)
TCH520 LOOP LCTRSPF,TCH510
LINK IPOOL,FIFO //ORIGINAL GOES INACTIVE
*
* TECHNICIAN HELPING LOGIC
*
TCH550 LOGIC C SMSTA
BLET PF(LCTR)=0 //ZERO FOR SEARCH
TCH560 BLET PF(LCTR)=PF(LCTR)+1
BLET PL(CPEST)=0 //ZERO OUT
TEST LE PF(LCTR),6,TCH310 //END OF SEARCH?
BLET &SVAR=FN(TLOC2) //NO;GET ELEMENT ASSIST#
TEST G &SVAR,0,TCH560 //NOT ASSIGNED HERE?
SCAN E ATECHS,CLOCSPF,&SVAR,TECHNSPF,CTRSPF,TCH560 //GET TECH#
SCAN E ATECHS,CLOCSPF,&SVAR,CMPESTSPL,CMPESTSPL
TEST G PL(CPEST),0,TCH560

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PREEMPT PF(CTR)+TCHNS,,TCH110,CYCLESPL //DELAY TECH
SCAN E ATECHS,CLOCSPF,&SVAR,CYCLESPL,CYCLESPL //REMAINING CYCLE
SCAN E ATECHS,CLOCSPF,&SVAR,CLOCSPF,CLOCSPF //GROUP #
BLET PL(CYCLE)=PL(CYCLE)/2.0 //ADJUST
ALTER ATECHS,1,CYCLESPL,PLSCYCLE,CLOCSPF,&SVAR //PASS CYCLE TIME
ALTER ATECHS,1,CMPESTSPL,0,CLOCSPF,&SVAR //PASS CYCLE TIME
RETURN PF(CTR)+TCHNS
BLET PL(CMPEST)=-1
BLET PF(CLOC)=-&SVAR
TRANSFER ,TCH100
*
* NEW PAINT PROCESS
*
TCH600 BLET PF(LCTR)=3 //3 LOOPS
TCH610 ADVANCE 0
PLON MACRO XIDL,PTPASS
ADVANCE PL(CYCLE) //LOOP PAST TWO LOADS
LOOP LCTRSPF,TCH610
PLON3 MACRO XIDL,STA,PF(CLOC)
SCOLOR MACRO XIDL,'WHITE'
TRANSFER ,TCH115
*-----
* PROCESS SURROUTINES
*-----
PRO000 BLET PF(LCTR)=0 //LOOP COUNTER TO 0
PRO100 BLET PF(LCTR)=PF(LCTR)+1 //BUMP
TEST LE PF(LCTR),6,PRO300 //END OF SEARCH?
TRANSFER ,FN(TLOC1)
*
PRO110 ADVANCE 0
FNDTCH MACRO LOC1$PF
TRANSFER ,PRO200
*
PRO120 ADVANCE 0
FNDTCH MACRO LOC2$PF
TRANSFER ,PRO200
*
PRO130 ADVANCE 0
FNDTCH MACRO LOC3$PF
TRANSFER ,PRO200
*
PRO140 ADVANCE 0
FNDTCH MACRO LOC4$PF
TRANSFER ,PRO200
*
PRO150 ADVANCE 0
FNDTCH MACRO LOC5$PF
TRANSFER ,PRO200
*
PRO160 ADVANCE 0
FNDTCH MACRO LOC6$PF
PRO200 BLET &TECHC(PFSCLOC)=-&TECHC(PFSCLOC)+1 //FOUND TECH
PRO210 LINK INPRO,FIFO //IN PROCESS
PRO220 TRANSFER ,PF(SUBR)+1
*
PRO300 MARK WAIT$PL //NO TECHS - COLLECT WAIT
BLET PL(ACMBRK)=-&ACNOOP(PF$MOD) //ACCUM BREAK TIME
LINK NOTCH,FIFO //NO TECH CHAIN
PRO305 LOGIC C MATCH //1ST DELAY FOUND/FREE MATCH
* PRO305 SPLIT 1,NDL000
LINK PDLAY,FIFO //AWAIT 2ND CALL
PRO310 ALTERUCH E APOOL,1,CLOCSPF,PFSCLOC,OPNUMSPF,PFSCLOC*1000 //PASS ID
ALTERUCH E APOOL,1,CYCLESPL,PLSCYCLE,OPNUMSPF,PFSCLOC*1000 //PASS CYCLE
* ALTERUCH E APOOL,1,OPNUMSPF,PF$OPNUM,CLOCSPF,PFSCLOC //PASS OPNUM
BLET PL(CMPEST)=PLSCYCLE+AC1 //ESTIMATE COMPLETION
UNLINK APOOL,TCH100,1,OPNUMSPF,PFSCLOC*1000 //GET TECH
BLET PF(OPNUM)=-1 //STOP PICKUP
TRANSFER ,PRO200
*-----

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* ASSEMBLY LAUNCH

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-----
LIN000  SPLIT      1,CLB000                //CREATE JHOOK LOAD BARS
        BLET      &J=0                    //FOR SHIP SCHEDULE POINTER
        BLET      &SSP=&JHSPD(1)
SPSPD   MACRO     JHK6,&SSP
SPSPD   MACRO     JHK7,&SSP
* READ SCHEDULE LINEUP IN
        BLET      PF(CVSEC)=1              //SET STARTING POINT
LIN010  BLET      PF(SEQNM)=PF(SEQNM)+1    //BUMP SCHEDULE
        TEST E    MX(SHIPS,PFSSEQNM,1),0,*+2 //SCHEDULE EOF?
        BLET      PF(SEQNM)=1              //YES;RESET
*
        TERMINATE
        BLET      PF(ENGINE)=MX(SHIPS,PFSSEQNM,1) //GET ENGINE
        BLET      PF(TSEQN)=MX(SHIPS,PFSSEQNM,4) //TRUCK#
        BLET      PF(LCTR)=MX(SHIPS,PFSSEQNM,2) // # IN RUN
LIN020  BLET      PF(SSEQN)=PF(SSEQN)+1    //GRAND SEQ.
        GATE SE   200                      //1ST OPEN
        SPLIT    1,BLK000                  //YES;CREATE BLOCK
        GATE SNE  200                      //WAIT FOR IT
        LOOP     LCTRSPF,LIN020            //CONTINUE W/ RUN
        TRANSFER ,LIN010                  //GET NEXT RUN
*
* BLOCK LINE - DEPT. 566
*
BLK000  ENTER     200
        LINK     ASMLD,FIFO                //AWAIT ASSEMBLY LOAD
LDBLK   LEAVE     200
        TERMINATE
*
-----
* J-HOOK ASSEMBLY LINE
*
-----
CLB000  BLET      PF(LCTR)=&LBCTJHK       //J-HOOK LOAD BARS
        BLET      PF(CVSEC)=9              //STARTING POINT
CLB010  GATE LC   PF(CVSEC)+JHOOK         //FIRST OPEN?
        SPLIT    1,JHK000                  //CREATE CARRIER
        ADVANCE  .5                          //DELAY
        LOOP     LCTRSPF,CLB010
        TERMINATE
*
JHK000  GATE LC   PF(CVSEC)+JHOOK         //CLEARANCE SECTION
        LOGIC S   PF(CVSEC)+JHOOK
        ENTER    PF(CVSEC)+JHOOK          //ZONE
CREATE  MACRO     JHLB,XID1
WRITEO  MACRO     JID,XID1,'EMPTY'
SCOLOR  MACRO     XID1,'WHITE'
PLON3   MACRO     XID1,JHK,PF(CVSEC)
JHK010  ADVANCE  8.0/&FSP                  //CLEAR LOAD BAR
        LOGIC C   PF(CVSEC)+JHOOK
        ADVANCE  (&APATH(PF&CVSEC)-8.0)/&FSP //TRAVEL
        TEST LE   PF(CVSEC),5,JHK020      //STILL ON FAST TRACK
        SEIZE    PF(CVSEC)+JHOOK          //YES;GRAB STATION
        ADVANCE  PL(CYCLE)*&ASMMAX/&SSP    //PROPORTION
        RELEASE  PF(CVSEC)+JHOOK
JHK020  BLET      PF(PLOC)=PF(CVSEC)       //UPDATE
        BLET      PF(CVSEC)=PF(CVSEC)+1    //BUMP
        TEST NE   PF(CVSEC),10,JHK060     //END OF CONV.
        TEST NE   PF(CVSEC),9,JHK050     //@END OF JHOOK?
        GATE LC   PF(CVSEC)+JHOOK         //CLEARANCE SECTION
        LOGIC S   PF(CVSEC)+JHOOK         //CLEARANCE SECTION
        ENTER    PF(CVSEC)+JHOOK          //ZONE
        LEAVE    PF(PLOC)+JHOOK
PLON3   MACRO     XID1,JHK,PF(CVSEC)
        TEST G    PF(CVSEC),5,JHK010     //FAST TRACK?
        TEST NE   PF(CVSEC),6,JHK040     //AT SLOW CHAIN?
        TEST NE   PF(CVSEC),9,JHK010     //FAST RETURN CHECK
JHK030  BLET      PL(CYCLE)=8.0/&SSP       //CLEARANCE @ SLOW
        BLET      PL(ETIME)=1
JHK031  ADVANCE  PL(CYCLE)

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LOGIC C      PF(CVSEC)+JHOOK
BLET        PL(CYCLE)=(&APATH(PF$CVSEC)-8.0)/&SSP    //TRAVEL @ SLOW
BLET        PL(ITIME)=0
JHK035     ADVANCE  PL(CYCLE)
TRANSFER    ,JHK020                                //KEEP LOOKING
*
JHK040     GATE LC   212
SELECT NU   PTRSPF,212,260                          //SELECT A FACILITY
SEIZE      PF(PTR)                                    //GRAB IT
JHKTOT     BLET     PL(CYCLE)=14.0/&SSP                //CLEARANCE @ SLOW
BLET      PL(ITIME)=1
TEST NE    &EFAM(&ECLASI(PF$ENGINE)),&PRVENG,JHK031
JHKCHG     ADVANCE  &JHKCO
BLET      &JHKCOTIM=&JHKCOTIM+&JHKCO
BLET      &PRVENG=&EFAM(&ECLASI(PF$ENGINE))
TRANSFER    ,JHK031
*
* TRANSFER TO MAIN CONVEYOR
*
JHK050     GATE LS   (PF(CVSEC)+JHOOK),JHK055        //END OF LINE STOPPED?
SPSPD     MACRO     JHK6,0
SPSPD     MACRO     JHK7,0
LOGIC S    212
FUNAVAIL   212-260                                    //STOP SLOW TRACK
GATE LC    PF(CVSEC)+JHOOK
SPSPD     MACRO     JHK6,&SSP
SPSPD     MACRO     JHK7,&SSP
FAVAIL     212-260                                    //STOP SLOW TRACK
JHK054     LOGIC C   212
JHK055     GATE LC   PF(CVSEC)+JHOOK                //CLEARANCE SECTION
LOGIC S    PF(CVSEC)+JHOOK
ENTER      PF(CVSEC)+JHOOK                            //ZONE
LEAVE      PF(PLOC)+JHOOK
RELEASE    PF(PTR)
PLON3     MACRO     XID1,JHK,PF(CVSEC)
ADVANCE    &APATH(PF$CVSEC)/&FSP                    //TRAVEL
GATE LC    451                                        //J-HOOK DELAY?
SEIZE      210                                        //JHOOK UNLOADER
ADVANCE    &JHKUL/&PERF(1)                          //UNLOAD TIME
RELEASE    210
BLET      &INPROC=&INPROC+1                          //COUNT ENGINE IN PROCESS
BLET      &EPROD(1)=&EPROD(1)+1                    //COUNT ENGINE RATE
BLET      &PRORATE(1)=&PRORATE(1)+1
BARG      MACRO     RT1, TOP, &PRORATE(1)
ENTER      EWIPQ
ENTER      TOTALQ
MARK       LAPTIMSPL                                //START TIMING
LOGIC S    ASMUL                                    //SIGNAL UNLOAD
LINK       ASMUL, FIFO                              //AWAIT INTERFACE
ULASM     LOGIC C   PF(CVSEC)+JHOOK
SCOLOR    MACRO     XID1, 'WHITE'
WRITEO    MACRO     JID, XID1, 'EMPTY'
TRANSFER    ,JHK020
*
JHK060     BLET     PF(CVSEC)=1                      //AT FIRST
GATE LC    PF(CVSEC)+JHOOK                          //CLEARANCE SECTION
LOGIC S    PF(CVSEC)+JHOOK
ENTER      PF(CVSEC)+JHOOK                            //ZONE
LEAVE      PF(PLOC)+JHOOK
PLON3     MACRO     XID1,JHK,PF(CVSEC)
ADVANCE    &APATH(PF$CVSEC)/&FSP                    //TRAVEL
GATE SNE   200                                        //BLOCK THERE?
SCANUCH G  ASMLD, SSEQNSPF, 0, SSEQNSPF, SSEQNSPF
SCANUCH E  ASMLD, SSEQNSPF, PF$SSEQN, ENGINESPF, ENGINESPF
SCANUCH E  ASMLD, SSEQNSPF, PF$SSEQN, TSEQNSPF, TSEQNSPF
SCANUCH E  ASMLD, SSEQNSPF, PF$SSEQN, SEQNSPF, SEQNSPF
BLET      PL(CYCLE)=440.0/&PRODVOL(1)/&PERF(1)
SEIZE      PF(CVSEC)+JHOOK
ADVANCE    PL(CYCLE)*&ASMMAX/&SSP                    //UNLOAD TIME

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        RELEASE PF(CVSEC)+JHOOK
        UNLINK  ASMLD,LDBLK,1           //GRAB BLOCK
SCOLOR  MACRO   XID1,'GREEN'
WRITEO  MACRO   JID,XID1,&PARTNO(PFSENGINE)
        LOGIC C  PF(CVSEC)+JHOOK
        TRANSFER ,JHK020
*-----*
* Initialize empty load bars in main loop.
*-----*
CNV000  GATE SNF 18                     //ZONE FULL?
        SPLIT  1,CNV010                 //NO;CREATE
        ADVANCE .12                      //CLEAR
        LOOP   LCTRS$PF,CNV000
        TERMINATE
*
CNV010  ENTER   18
CREATE  MACRO   LBR,XID1
WRITEO  MACRO   LBRID,XID1,'EMPTY'
SCOLOR  MACRO   XID1,'WHITE'
BARG    MACRO   PQ1, TOP, 100.0*S(18)/(S(18)+R(18))
*
GOPF1   ADVANCE 0
PLON    MACRO   XID1,BB18
        ADVANCE 11.22
GOPF2   LINK    18,FIFO,GOPF2A
GOPF2A  SEIZE   SPF2
        ENTER   SPF2
PLON    MACRO   XID1,PF2
        ADVANCE .1
        LEAVE   18
BARG    MACRO   PQ1, TOP, 100.0*S(18)/(S(18)+R(18))
        ADVANCE .94
GOPF3   RELEASE SPF2
        UNLINK  18,GOPF2A,1
PLON    MACRO   XID1,PF3
        ADVANCE .90
*
        ENTER   SPL
        LEAVE   SPF2
PLON    MACRO   XID1,PL
        ADVANCE .17
*
* Now wait for a raw engine to be ready to be transferred.
* Wait on switch, while matching engine is transferred.
*
        GATE LC  SPF1
        GATE LS  ASMUL,BLU100           //GO TEST BLUBIRD IF NO J-HOOK
GOPF4A  GATE LS  ASMUL                 //AWAIT JHOOK ENGINE?
        SCANUCH G ASMUL,SSEQNS$PF,0,SSEQNS$PF,SSEQNS$PF //GET GRAND SEQ#
        SCANUCH E ASMUL,SSEQNS$PF,PFSSSEQN,ENGINES$PF,ENGINES$PF //GET ENGINE#
        SCANUCH E ASMUL,SSEQNS$PF,PFSSSEQN,LAPTIMS$PL,LAPTIMS$PL
        SCANUCH E ASMUL,SSEQNS$PF,PFSSSEQN,TSEQNS$PF,TSEQNS$PF
        SCANUCH E ASMUL,SSEQNS$PF,PFSSSEQN,SEQNMS$PF,SEQNMS$PF
        UNLINK  ASMUL,ULASM,1         //RELEASE
        LOGIC C  ASMUL                 //AWAIT NEXT ENGINE
WRITEO  MACRO   LBRID,XID1,&PARTNO(PFSENGINE)
SCOLOR  MACRO   XID1,&ECLR(PFSENGINE)
*
* MAIN DELIVERY CONVEYOR
*
GOPF5   SEIZE   SPO
        ENTER   SPO
PLON    MACRO   XID1,P0
        ADVANCE .1
        RELEASE SPO
        LEAVE   SPL
        LOGIC C  SPF1
        ADVANCE .55
        LINK    211,FIFO,CNV020

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CNV020 SEIZE      211                                //LEAK TESTER
      BLET      PF(RJCT)=0                          //ZERO REJECT PARM
      BLET      PF(PCODE)=0                          //ZERO OUT PROCESS CODE
      TEST NE   PF(DELRT),568,RPH000                 //COMING FROM FLOOR
      BLET      PF(DELRT)=0                          //ZERO OUT
      TEST G    &BTRIM(PFSENGINE),0,CNV030           //BLUEBIRD?
      BLET      PF(PCODE)=PNTSYS                     //YES;DIRECT TO PAINT
      TRANSFER  ,CNV050                              //PROCEED
CNV030 TEST G    &CTRIM(PFSENGINE),0,CNV040           //CARB TRIM
      BLET      &OPCNT(PFSENGINE)=&OPCNT(PFSENGINE)+1
      BLET      PF(CTR)=&OPCNT(PFSENGINE)           //SAVE
      BLET      PF(PCT)=&COPTN(PFSENGINE)*100
      TRANSFER  SBR,RPCT00,SUBRSPF                   //DETERMINE %
      BLET      PF(DELRT)=PF(RJCT)
      BLET      PF(RJCT)=0
CNV040 ADVANCE  &LEAKTST(1)/&PERF(1)                //NO LEAK TEST
      BLET      &GBCNT(1)=&GBCNT(1)+1              //REJECT COUNT
      BLET      PF(CTR)=&GBCNT(1)                   //SAVE COUNT
      BLET      PF(PCT)=&LEAKRJ(1)*100              //SAVE PCT
      TRANSFER  SBR,RPCT00,SUBRSPF                   //DETERMINE REJECT
      TEST E    PF(RJCT),0,RPH000                    //PASS TEST?
      TEST E    PF(DELRT),0,RPH000                    //YES;CARB TRIM JOB?
      BLET      PF(PCODE)=CLTEST                      //REST TO TEST
CNV050 BLET      PF(CVSEC)=1                          //STARTING SECTION
      GATE LC   PF(CVSEC)                             //ZONE CLEAR
      LOGIC S   PF(CVSEC)                             //SHUT OFF
      BLET      &DUM='569'                            //GOING 569
      TRANSFER  SBR,FNDMOD,SUBRSPF                   //FIND MOD #
      ENTER     PF(CVSEC)                             //MERGE ZONE
PLON3  MACRO    XID1,MBB,PF(CVSEC)
      ADVANCE  ML(CSECT,PFSCVSEC,12)                 //MERGE ZONE
      LOGIC C   PF(CVSEC)                             //CLEARANCE
      LEAVE     SPO                                   //FREE PREVIOUS
      RELEASE  211
      UNLINK   211,CNV020,1
PLON3  MACRO    XID1,BB,PF(CVSEC)
      TRANSFER  ,BBD060
-----
* BACKBONE DELIVERY CONVEYOR
-----
BBD000 GATE LC   PF(CVSEC)                            //SWITCH CLEAR
      LOGIC S   PF(CVSEC)                             //1@TIME
      TEST NE   &BMRG(PFSCVSEC),1,BBD050             //MERGE ZONE?
      ENTER     PF(CVSEC)                             //NO;GET ZONE
PLON3  MACRO    XID1,BB,PF(CVSEC)
      ADVANCE  .12                                    //CLEARANCE ZONE
      TEST E    PF(CVSEC),18,*+2
      TRANSFER  SBF,BBD090,SUBRSPF
      LOGIC C   PF(CVSEC)                             //OPEN CLEARANCE
      LEAVE     PF(PLOC)                              //FREE PREVIOUS
      TEST E    PF(PLOC),3,*+2
      UNLINK   PF(PLOC),BBD000,1
      TEST E    PF(PLOC),33,*+2
      UNLINK   PF(PLOC),TLC3320,1
      ADVANCE  ML(CSECT,PFSCVSEC,1)-.12              //ZONE
BBD010 TEST NE   PF(CVSEC),1,BBD0100                 //GO TO RC?
      TEST NE   PF(CVSEC),3,BBD0300                 //ALL TEST CELLS
      TEST NE   PF(CVSEC),4,BBD0400                 //ALL TEST CELLS
      TEST NE   PF(CVSEC),5,BBD0500                 //TEST CELLS 7-18
      TEST NE   PF(CVSEC),9,BBD0900                 //SPECIAL
      TEST NE   PF(CVSEC),11,BBD1100                //SPECIAL
      TEST NE   PF(CVSEC),13,TLC000                  //EXIT TEST CELL LOOP?
      TEST NE   PF(CVSEC),16,BBD1600                //BACKBONE LIMIT CHECK
      TEST NE   PF(CVSEC),17,BBD1700                //EXIT FOR PAINT, TRIM, EMPTY
      TEST NE   PF(CVSEC),18,GOPF2                  //EMPTY LOAD BAR RETURN
BBD020 BLET      PF(PLOC)=PF(CVSEC)                  //BUMP PREVIOUS LOC
      BLET      PF(CVSEC)=PF(CVSEC)+1                //NEXT ZONE
      TRANSFER  ,BBD000
-----

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BBD050 ENTER PF(CVSEC) //MERGE ZONE
PLON3 MACRO XID1, BBM, PF(CVSEC)
ADVANCE ML(CSECT, PF$CVSEC, 11) //MERGE ZONE
TEST E PF(CVSEC), 18, *+2
TRANSFER SBR, BBD090, SUBRSPF
BBD055 LOGIC C PF(CVSEC) //CLEARANCE
LEAVE PF(PLOC) //FREE PREVIOUS
TEST E PF(PLOC), 3, *+2
UNLINK PF(PLOC), BBD000, 1
TEST E PF(PLOC), 33, *+2
UNLINK PF(PLOC), TLC3320, 1
PLON3 MACRO XID1, BB, PF(CVSEC)
BBD060 ADVANCE ML(CSECT, PF$CVSEC, 1) //ZONE TRAVEL
TRANSFER , BBD010
*
BBD090 LOGIC C BBSWT
UNLINK PF(PLOC), BBD1710, 1
LEAVE BACKBCNT
BARG MACRO PQ1, TOP, 100.0*S(18)/(S(18)+R(18))
TEST L S(BACKBCNT), &BBLIM, PF(SUBR)+1
LOGIC C BACKBCNT
TRANSFER , PF(SUBR)+1
*
BBD0100 ENTER BACKUP
GATE LC RECR1 //GRAB SWITCH
LOGIC S RECR1
GATE SNF RECR10
TEST E BV(NOBACKUP), 1, *+2 //BACKUP CONDITION?
UNLINK BACKUP, RCL1005, 1 //YES; RELEASE TO ATTIC
TEST E PF(PCODE), CLTEST, BBD0110
GATE SE RECR1, RCL1000 //ANYTHING IN ATTIC?
BBD0105 GATE LC COUNT, BBD0120
BBD0106 BLET XF(COUNT)=XF(COUNT)+1
TEST GE XF(COUNT), &MAX, *+2
LOGIC S COUNT
JOIN GCLTEST
BBD0110 GATE LC PF(CVSEC)+1 //UPDATE
LEAVE BACKUP
LOGIC C RECR1
TRANSFER , BBD020
*
BBD0120 GATE SE RECR1, RCL1000 //GO RECIRC IF ATTIC NOT EMPTY
GATE SNF BACKUP, RCL1000 //GO ATTIC IF BACKUP FULL
GATE SNF BACKUP
GATE LC COUNT
TRANSFER SIM, BBD0105, RCL1000 //RETEST IF TRUE/GO ATTIC IF NOT
*
BBD0300 BLET PF(PLOC)=PF(CVSEC) //BUMP PREVIOUS LOC
BLET PF(CVSEC)=PF(CVSEC)+1 //NEXT ZONE
LINK PF(PLOC), FIFO, BBD000
TRANSFER , BBD000
*
BBD0400 TEST E PF(PCODE), CLTEST, BBD020 //TEST CELL CODE?
SCAN MIN GCLTEST, TSEQNSPF, , TSEQNSPF, DELRTSPF, CEL006 //FIND LOWEST TRK GRID#
TEST LE PF$TSEQN, PFSDELRT, BBD020 //AM I LOWEST?
TRANSFER , CEL006
*
BBD0500 TEST E PF(PCODE), CLTEST, BBD020 //TEST CELL CODE?
GATE SNF 36, BBD020 //ZONE CLEAR?
SCAN MIN GCLTEST, TSEQNSPF, , TSEQNSPF, DELRTSPF, CEL013 //FIND LOWEST TRK GRID#
TEST LE PF$TSEQN, PFSDELRT, BBD020 //AM I LOWEST?
TRANSFER , CEL013
*
BBD1600 LINK BACKBCNT, FIFO, BBD1610 //ACCUMULATE BEHIND STOP
BBD1610 GATE LC BACKBCNT //STOP OPEN?
ENTER BACKBCNT //GRAB ZONE
TEST GE S(BACKBCNT), &BBLIM, BBD1620
LOGIC S BACKBCNT
BBD1620 ADVANCE .01

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        UNLINK      BACKBCNT,BBD1610,1
        TRANSFER    ,BBD020
*
BBD1700 LINK        PF(CVSEC),FIFO,BBD1710      //ACCUMULATE BEHIND STOPS
BBD1710 GATE LC      BBSWT
        LOGIC S      BBSWT
        TEST NE     PF(PCODE),0,BBD020          //EMPTY?
        GATE SNF    SSTG0                       //NO;STAGE POSITION OPEN
        GATE LC      SSTG0                       //YES;INDEX IN
        LOGIC S      SSTG0                       //ONE AT TIME
        ENTER       SSTG0                       //ENTER ZONE
PLON    MACRO       XID1,STG0
        ADVANCE     .12                        //INDEX IN
        LOGIC C      BBSWT
        UNLINK      PF(CVSEC),BBD1710,1
        LOGIC C      SSTG0
        LEAVE       PF(CVSEC)                  //LEAVE PREVIOUS ZONE
        LEAVE       BACKBCNT                  //LEAVE BACKBONE
        TEST L      S(BACKBCNT),&BBLIM,*+2    //LESS THAN CHOKE LIMIT?
        LOGIC C      BACKBCNT                 //YES; FREE ZONE
        ADVANCE     .40                        //INDEX
        LINK        SSTG0,FIFO,BBD1730
BBD1730 TEST NE     PF(PCODE),PNTSYS,PST000    //DESTINED TO PAINT
        TRANSFER    ,TRM000
*
* TEST CELL LEG
*
TLC000  BLET        PF(PLOC)=PF(CVSEC)          //KEEP PREV
        BLET        PF(CVSEC)=31
        TEST G      PF(ENGINE),0,TLC010        //EMPTY?
        TEST G      PF(PCODE),10,TLC010        //10.5/12.5?
        BLET        PF(PCODE)=PF(PCODE)-10     //YES;NOW AVAILABLE
        JOIN        PF(PCODE)                  //IN GROUP
TLC010  GATE LC      PF(CVSEC)                  //SWITCH CLEAR
        LOGIC S      PF(CVSEC)                  //1@TIME
        TEST NE     &BBMRG(PFSCVSEC),1,TLC050 //MERGE ZONE?
        ENTER       PF(CVSEC)                  //NO;GET ZONE
PLON3   MACRO       XID1,TL,PFSCVSEC-30        //GET ON PATH
        ADVANCE     .13                        //CLEARANCE ZONE
        LOGIC C      PF(CVSEC)                  //OPEN CLEARANCE
        LEAVE       PF(PLOC)                   //FREE PREVIOUS
        TEST E      PF(PLOC),32,*+2
        UNLINK      PF(PLOC),TLC3205,1
        ADVANCE     ML(CSECT,PFSCVSEC,1)-.13  //ZONE
TLC020  TEST NE     PF(CVSEC),32,TLC3200        //GO TO RETORQ?
        TEST NE     PF(CVSEC),33,TLC3300        //EXIT TL OR REPAIRS
TLC030  BLET        PF(PLOC)=PF(CVSEC)         //BUMP PREVIOUS LOC
        BLET        PF(CVSEC)=PF(CVSEC)+1     //NEXT ZONE
        TRANSFER    ,TLC010
*
TLC050  ENTER       PF(CVSEC)                  //MERGE ZONE
PLON3   MACRO       XID1,TLM,PFSCVSEC-30
        ADVANCE     ML(CSECT,PFSCVSEC,11)     //MERGE ZONE
TLC055  LOGIC C      PF(CVSEC)                  //CLEARANCE
        LEAVE       PF(PLOC)                   //FREE PREVIOUS
        TEST E      PF(PLOC),32,*+2
        UNLINK      PF(PLOC),TLC3205,1
PLON3   MACRO       XID1,TL,PFSCVSEC-30
TLC060  ADVANCE     ML(CSECT,PFSCVSEC,1)       //ZONE TRAVEL
        TRANSFER    ,TLC020
*
TLC3200 LINK        PF(CVSEC),FIFO,TLC3205
TLC3205 GATE SNF    RTORKQ,TLC030              //ZONE FULL?
        BLET        PF(PLOC)=PF(CVSEC)         //SAVE PREVIOUS LOCATION
        TEST NE     PF(ENGINE),0,RTQ000        //EMPTY EXITS
        TEST G      PF(PCODE),REPAIRS,TLC030  //REPAIRS STAY ON LOOP?
        TEST L      PF(PCODE),10,TLC030        //1ST PASS 10.5/12.5 STAY ON
        SCAN MIN    PFSPCODE,TSEQNSPF,,TSEQNSPF,DELRTSPF,TLC3210
        TEST LE     PFSTSEQN,PF$DELRT,TLC030

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TLC3210 GATE SNF (294+PF$PCODE),TLC030
        ENTER (294+PF$PCODE)
BARG4  MACRO PQ, (PF$PCODE-3),TOP,100.0*S(294+PF$PCODE)/(S(294+PF$PCODE)+_
        R(294+PF$PCODE))
        TRANSFER ,RTQ000
*
TLC3300 BLET PF(PLOC)=PF(CVSEC) //SAVE PREVIOUS LOCATION
        TEST E PF(PCODE),REPAIRS,TLC3310 //REPAIR PC?
        GATE SNF REPRQ,TLC3310
        SCAN MIN GREPAIRS,TSEQNSPF,,TSEQNSPF,DELRT$PF,RPR000
        TEST LE PFSTSEQN,PF$DELRT,TLC3310
        REMOVE GREPAIRS
        TRANSFER ,RPR000
*
TLC3310 ADVANCE .08
        LINK PF(PLOC),FIFO,TLC3320
TLC3320 BLET PF(CVSEC)=3 //CONV. SECTION
        GATE LC PF(CVSEC)
        LOGIC S PF(CVSEC)
        ENTER PF(CVSEC)
PLON  MACRO XID1,MBB3
        ADVANCE .14
        TRANSFER ,BBD055
*-----*
* BLUEBIRD AND REAR PTO FLOOR QUEUE
*-----*
BLU000 ADVANCE 5 //5 MIN DELIVERY ASSUMED
        QUEUE BLUBFQ //FLOOR QUEUE
BARG  MACRO BBFG,RIGHT,Q(BLUBFQ)
WRITE MACRO BBFM,Q(BLUBFQ)
        LOGIC S BLUBFQ //INDICATE HERE
        LINK BLUBFQ,FIFO
BLU010 TEST E CH(BLUBFQ),0,*+2 //EMPTY YET?
        LOGIC C BLUBFQ //BLUEBIRD NOT THERE?
        DEPART BLUBFQ
BARG  MACRO BBFG,RIGHT,Q(BLUBFQ)
WRITE MACRO BBFM,Q(BLUBFQ)
        TERMINATE
*
BLU100 GATE LS BLUBFQ,GOPF4A //BLUEBIRD THERE?
        TEST E BV(BMTR),1,GOPF4A //YES;CONVEYOR FULL?
        SCANUCH G BLUBFQ,SSEQNSPF,0,SSEQNSPF,SSEQNSPF //GET GRAND SEQ#
        SCANUCH E BLUBFQ,SSEQNSPF,PFSSSEQN,ENGINESPF,ENGINESPF //GET ENGINE#
        SCANUCH E BLUBFQ,SSEQNSPF,PFSSSEQN,LAPTIMSPL,LAPTIMSPL
        SCANUCH E BLUBFQ,SSEQNSPF,PFSSSEQN,TSEQNSPF,TSEQNSPF
        SCANUCH E BLUBFQ,SSEQNSPF,PFSSSEQN,SEQNMSPF,SEQNMSPF
        UNLINK BLUBFQ,BLU010,1 //RELEASE
SCOLOR MACRO XID1,&ECLR(PF$ENGINE)
WRITE0 MACRO LBRID,XID1,&PARTNO(PF$ENGINE)
        BLET PF(DELRT)=568 //TAG TO GO TO 568
        TRANSFER ,GOPF5
*-----*
* 568 REPAIR AND TRIM
*-----*
RPH000 BLET &DUM='568' //NEW MODULE
        TRANSFER SBR,FNDMOD,SUBRSPF //FIND CORRESPONDING #
        GATE LC 260 //CLEARING ZONE
        LOGIC S 260 //STOP
        RELEASE 211 //FREE TEST ZONE
        UNLINK 211,CNV020,1
        TEST E PF(RJCT),1,RPH100 //NEED REPAIR?
SCOLOR MACRO XID1,'RED'
        SELECT SNF CLOCSPF,261,263 //OPEN REPAIR SPUR
RPH002 ENTER PF(CLOC)
PLON3  MACRO XID1,RS,PF(CLOC)-260
        ADVANCE .28 //CLEARING
        LOGIC C 260 //CLEARED
        LEAVE SPO
        ADVANCE 1.0 //TO SPUR

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        BLET      PL(CYCLE)=%LEAKRPR(1) //REPAIR TIME
        TRANSFER  SBR, PRO000, SUBRSPF //PROCESS
SCOLOR  MACRO    XID1, &ECLR(PF$ENGINE)
        GATE LC   LEAKQ //EXIT CLEAR?
        LOGIC S   LEAKQ //YES; TIE UP
        LEAVE     PF(CLOC)
PLON3   MACRO    XID1, RF, PF(CLOC) -260
        ADVANCE  .41+.20*(263-PF$CLOC)
RPH005  ENTER    LEAKQ
        LOGIC C   LEAKQ
PLON    MACRO    XID1, LEAKTQ
        ADVANCE  1.38
        LINK     LEAKQ, FIFO, RPH010
RPH010  ENTER    LKTST2 //LEAK TEST ZONE
PLON    MACRO    XID1, LKT2 //PATH
        ADVANCE  .14
        LEAVE     LEAKQ
        BLET     PF(CLOC)=LKTEST2 //NEW STATION
        BLET     PL(CYCLE)=%LEAKTST(2)
        TRANSFER SBR, PRO000, SUBRSPF //PROCESS
        BLET     PF(PCODE)=CLTEST //CELL TEST IS NEXT
        BLET     PF(DELRT)=0 //ZERO OUT DEL. ROUTE
        BLET     PF(PLOC)=270 //LEAK TEST #2
        BLET     PF(CVSEC)=19 //SET ZONE
        GATE LC   PF(CVSEC) //MERGE CLEAR
        LOGIC S   PF(CVSEC) //YES; TIE UP
        ENTER    PF(CVSEC)
        BLET     &DUM='569'
        TRANSFER SBR, FNDMOD, SUBRSPF
        UNLINK    LEAKQ, RPH010, 1
PLON    MACRO    XID1, BB19
        ADVANCE  .12
        BLET     &EPROD(2)=%EPROD(2)+1 //COUNT ENGINE IN PROCESS
        LOGIC C   PF(CVSEC)
        LEAVE     PF(PLOC)
        ADVANCE  .92 //CLEAR
        BLET     PF(PLOC)=PF(CVSEC)
        BLET     PF(CVSEC)=1
        TRANSFER , BBD000 //BACK TO MAIN
*-----*
* BLUEBIRD & COMPRESSOR TRIM
*-----*
RPH100  ADVANCE  0
PLON    MACRO    XID1, BCTRM0
        ADVANCE  .28 //CLEARANCE
        LOGIC C   260 //CLEAR ZONE
        ENTER    271
        LEAVE     SPO
RPH110  ADVANCE  0
PLON    MACRO    XID1, BCTRM1
        ADVANCE  .79 //TIME
        BLET     PF(CLOC)=271 //START OF TRIM LINE
        GATE LC   PF(CLOC) //@ ASM STATION
        LOGIC S   PF(CLOC)
        BLET     PL(CYCLE)=%CTRM(PF$ENGINE)/6/&PERF(PF$MOD)
        TEST E    PL(CYCLE), 0, *+2 //NOT CARB?
        BLET     PL(CYCLE)=%BTRM(PF$ENGINE)/6/&PERF(PF$MOD)
RPH120  TRANSFER SBR, PRO000, SUBRSPF //PROCESS
        BLET     PF(PLOC)=PF(CLOC) //SAVE PREVIOUS
        BLET     PF(CLOC)=PF(CLOC)+1 //BUMP LOCATION
        TEST NE   PF(CLOC), 277, RPH150 //END OF LINE?
        ENTER    PF(CLOC)
PLON3   MACRO    XID1, BCTRM, PF(CLOC) -270
        ADVANCE  .15 //MOVE INTO NEXT
        LOGIC C   PF(PLOC)
        LEAVE     PF(PLOC)
        GATE LC   PF(CLOC) //STATION CLEAR
        LOGIC S   PF(CLOC) //TIE UP
        TRANSFER , RPH120

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RPH150  GATE LC   PF(CLOC)
        LOGIC S   PF(CLOC)
        PLON     MACRO  XID1,RBC
        ADVANCE  .14
        LOGIC C   PF(PLOC)
        LEAVE    PF(PLOC)           //EXIT LINE
        ADVANCE  .14
        GATE LC   LEAKQ
        LOGIC S   LEAKQ
        LOGIC C   PF(CLOC)
        TRANSFER ,RPH005

RPH200  BLET     PF(PLOC)=PF(CVSEC) //KEEP SEGMENT
        GATE SF   271,RPH210       //QUEUE FULL?
        BLET     PF(CVSEC)=1       //YES;RESET CONV. SEC
        TRANSFER ,BBD000         //BACK TO BACKBONE
RPH210  ENTER    271              //GET SEGMENT
        GATE LC   260              //SEGMENT ZONE OPEN
        LOGIC S   260
        PLON     MACRO  XID1,BCTRM
        ADVANCE  .1
        LEAVE    PF(PLOC)         //FREE BB
        ADVANCE  .19             //SWITCH IN
        LOGIC C   260
        TRANSFER ,RPH110

-----
* TEST RECIRCULATOR #1
-----
RCL1000 TEST G    &ATHEAD,0,RCL1005
        TEST L    PF(TSEQN),&ATHEAD,RCL1005 //LOWER TRUCK #
        LINK     BACKUP,FIFO
RCL1005 BLET     PF(PCODE)=RCRQ1
        ENTER    RECR1           //GRAB RC
BARG    MACRO    PQ2, TOP, 100.0*S(RECR1)/(S(RECR1)+R(RECR1))
        BLET     PF(PCODE)=CLTEST
PLON    MACRO    XID1,RC11
        ADVANCE  .12             //CLEAR SWITCH
        LEAVE    PF(CVSEC)       //EXIT BB
        LEAVE    BACKUP          //EXIT BACKUP
        LOGIC C   RECR1         //CLEAR ENTRY
        ADVANCE  7.53           //UP THE VERTICAL
        TEST E   CH(RECR1),0,*+2
        BLET     &ATHEAD=PF(TSEQN) //AT HEAD OF LINK
        LINK     RECR1,FIFO
RCL1010 LINK     RECR10,FIFO,RCL1020 //YES;PUT BACK
RCL1020 ENTER    RECR10
        LEAVE    RECR1
BARG    MACRO    PQ2, TOP, 100.0*S(RECR1)/(S(RECR1)+R(RECR1))
PLON    MACRO    XID1,RC12
        BLET     &ATHEAD=0
        SCANUCH G RECR10,TSEQNSPF,0,TSEQNSPF,DELRTSPF,RCL1030
        TRANSFER ,RCL1040
RCL1030 SCANUCH G RECR1,TSEQNSPF,0,TSEQNSPF,DELRTSPF,RCL1050
RCL1040 PLET     &ATHEAD=PF(DELRT)
RCL1050 ELET     PF(DELRT)=0
        ADVANCE  1.3
        BLET     PF(CVSEC)=2
        GATE LC   PF(CVSEC)
        LOGIC S   PF(CVSEC)
        ENTER    PF(CVSEC)
        BLET     XF(COUNT)=XF(COUNT)+1
        TEST GE  XF(COUNT),&MAX,*+2
        LOGIC S   COUNT
        PLON     MACRO  XID1,MBB2
        ADVANCE  .14
        LEAVE    RECR10
        UNLINK   RECR10,RCL1020,1
        PLON     MACRO  XID1,BB2

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LOGIC C      PF(CVSEC)
ADVANCE     ML(CSECT,PFSCVSEC,1)      //ON BACKBONE
JOIN        GCLTEST
TRANSFER    ,BBD010
-----
* TEST CELL LOGIC
-----
CEL006  GATE SNF  34,CEL012
SCANUCH LE ACELLS,DELRTSPF,6,,CEL012 //ANY ACTIVE HERE?
TEST G    &TCRTE(PFSENGINE),0,CEL010 //YES;ANY CELL WORK?
TEST LE   &TCRTE(PFSENGINE),6,CEL012 //NO;RIGHT RANGE?
BLET      PF(LOC1)=1                //YES;CLEARANCE INDICATOR
CEL010  ENTER    34                  1ST BANK CELL
        LEAVE    PFSCVSEC
        REMOVE   GCLTEST
CEL011  BLET     PF(CVSEC)=34
PLON    MACRO    XID1,P34
        ADVANCE  .33
        LINK     21,FIFO,FIRST
-----
CEL012  GATE SNF  35,BBD020
SCANUCH G ACELLS,DELRTSPF,6,,BBD020 //ANY ACTIVE HERE?
TEST G    &TCRTE(PFSENGINE),0,CEL020 //YES;ANY CELL WORK?
TEST G    &TCRTE(PFSENGINE),6,BBD020 //NO;RIGHT RANGE?
BLET      PF(LOC1)=7
CEL020  ENTER    35                  //CAPTURE EXIT STORAGE
        LEAVE    PFSCVSEC           //LEAVE ZONE
        REMOVE   GCLTEST
        BLET     PF(CVSEC)=35
PLON    MACRO    XID1,P35
        ADVANCE  .98                //INDEX
        TRANSFER ,CEL040
-----
CEL013  GATE SNF  36,BBD020
SCANUCH G ACELLS,DELRTSPF,6,,BBD020 //ANY ACTIVE HERE?
TEST G    &TCRTE(PFSENGINE),0,CEL030 //YES;ANY CELL WORK?
TEST G    &TCRTE(PFSENGINE),6,BBD020 //NO;RIGHT RANGE?
BLET      PF(LOC1)=7
CEL030  ENTER    36                  //CAPTURE EXIT STORAGE
        LEAVE    PFSCVSEC           //LEAVE ZONE
        REMOVE   GCLTEST
        BLET     PF(CVSEC)=36
PLON    MACRO    XID1,P36
        ADVANCE  .62                //INDEX
-----
* TEST CELL LOGIC
-----
CEL040  PRIORITY 10
        LINK     22,FIFO,FIRST
FIRST   GATE LC   PFSCVSEC
        LOGIC S  PFSCVSEC
        TEST G   &TCRTE(PFSENGINE),0,TSC050 //GENERAL ASSIGNMENT?
        BLET     PF(DELRT)=&TCRTE(PFSENGINE) //NO SPECIFIC
TSC000  GATE FS   PF(DELRT)+80        //GRAB CELL?
        GATE LS  PF(DELRT)+40        //ACTIVE?
        TRANSFER SIM,TSC100,TSC000   //NO;PROCEED
TSC050  TEST E    PF(CVSEC),34,TSC080 //NOT;SPECIFIC 1ST DAY RANGE
        BLET     PF(LOC1)=1          //1ST CELL
        BLET     PF(LOC2)=6          //LAST CELL
        TRANSFER ,TSC090            //YES;PROCEED
TSC080  BLET     PF(LOC1)=7          //1ST CELL
        BLET     PF(LOC2)=13         //LAST CELL
TSC090  SELECT E DELRTSPF,PF$LOC1,PF$LOC2,1,BV
        TEST E   PF(DELRT),0,TSC100  //FOUND HOME?
        LOGIC S  PF(LOC1)+80         //NO
        GATE LC  PF(LOC1)+80         //AWAIT OPENING
        TRANSFER ,TSC090
TSC100  SEIZE    PF(DELRT)+80        //ASSIGN CELL
        SEIZE    FN7                 //PATH WAY

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LOGIC C    PFSCVSEC
UNLINK    FN2, FIRST, 1          //TAKE NEXT
LEAVE     PFSCVSEC              //CLEAR ZONE
TEST NE   PF(CVSEC), 34, FBAYS
PLON3     MACRO  XID1, FR, PFSCVSEC
ADVANCE   .12
FBAYS     BLET   XF(COUNT)=XF(COUNT)-1
TEST L    XF(COUNT), &MAX, TSC102
LOGIC C    COUNT
UNLINK    BACKUP, BBD0106, 1, , , TSC101
TRANSFER  , TSC102
TSC101    UNLINK  RECR1, RCL1010, 1
TSC102    ADVANCE 0
PLON3     MACRO  XID1, IN, PF(DELRT)
ADVANCE   FN4
RELEASE   FN7
BLET      PF(CLOC)=PF(DELRT)+40      //LOCATION - DO HOOK-UP
BLET      PL(CYCLE)=(&HOOK(PFSENGINE)+&RHOOK(PFSENGINE))&PERF(PFSMOD)
TRANSFER  SBR, PRO000, SUBRSPF      //HOOK UP
GATE LC   PFSDELRT+451             //CELL DELAY UNDERWAY
.
* CELL DELAY TEST
.
BLET      &GBCNT(2)=&GBCNT(2)+1      //REJECT COUNT
BLET      PF(CTR)=&GBCNT(2)          //SAVE COUNT
BLET      PF(PCT)=&CRPRRJ*100        //SAVE PCT
TRANSFER  SBR, RPCT00, SUBRSPF      //DETERMINE REJECT
TEST NE   PF(RJCT), 0, TSC105       //NEED CELL REPAIR?
SCOLOR    MACRO  XID1, 'RED'
ADVANCE   &CRPRTIM                  YES; DOWNTIME
SCOLOR    MACRO  XID1, &ECLR(PFSENGINE)
TSC105    SEIZE  PFSDELRT+100        RUN TIME STATISTICS
ADVANCE   &CTEST(PFSENGINE)-&RHOOK(PFSENGINE)&PERF(PFSMOD) //TEST TIME
BLET      ML(PROD, 100, 8)=ML(PROD, 100, 8)+1
RELEASE   PFSDELRT+100             RUN TIME STATISTICS
* MAJOR REPAIR TEST 1ST
.
TEST L    PFSRETEST, 2, TSC130      2ND TEST?
BLET      PF(RETEST)=PF(RETEST)+1    //BUMP COUNT
TEST E    PF(RETEST), 1, TSC110
BLET      &ENGCL(PFSENGINE)=&ENGCL(PFSENGINE)+1 //REJECT COUNT
BLET      PF(CTR)=&ENGCL(PFSENGINE)  //SAVE COUNT
BLET      PF(PCT)=&TRJT1(PFSENGINE)*100 //SAVE PCT
TRANSFER  SBR, RPCT00, SUBRSPF      //DETERMINE REJECT
TRANSFER  , TSC120
* MAJOR REPAIR TEST 2ND
.
TSC110    BLET   &ENGCL2(PFSENGINE)=&ENGCL2(PFSENGINE)+1 //REJECT COUNT
BLET      PF(CTR)=&ENGCL2(PFSENGINE) //SAVE COUNT
BLET      PF(PCT)=&TRJT2(PFSENGINE)*100 //SAVE PCT
TRANSFER  SBR, RPCT00, SUBRSPF      //DETERMINE REJECT
TSC120    TEST NE PF(RJCT), 1, TSC200 //NEED CELL REPAIR?
BLET      PF(RETEST)=0              //NO; ELIMINATE RETEST NEED
* MINOR REPAIR TEST
.
BLET      &GBCNT(3)=&GBCNT(3)+1      //REJECT COUNT
BLET      PF(CTR)=&GBCNT(3)          //SAVE COUNT
BLET      PF(PCT)=&LRPRRJ*100        //SAVE PCT
TRANSFER  SBR, RPCT00, SUBRSPF      //DETERMINE REJECT
TEST E    PF(RJCT), 0, TSC200       //NEED CELL REPAIR?
TSC130    BLET   PF(RETEST)=0         //CLEAR PARMS
TSC200    MSAVEVALUE PROD+, PFSENGINE, PFSRETEST+3, 1, ML COLLECT TEST
MSAVEVALUE PROD+, 100, PFSRETEST+3, 1, ML //STATS
TEST E    PF(RJCT), 1, TSC210       //LAST PHASE
SCOLOR    MACRO  XID1, 'RED'
TSC210    BLET   PL(CYCLE)=&UNHK(PFSENGINE)&PERF(PFSMOD)
TRANSFER  SBR, PRO000, SUBRSPF      //HOOK UP
SEIZE     FN11                       //EXIT PATH CLEAR
PLON3     MACRO  XID1, OUTB, PF(DELRT)

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ADVANCE .14
RELEASE PF(DELRT)+80 //RELEASE CELL
LOGIC C PF(LOC1)+80 //SIGNAL OPENING
PLON3 MACRO XID1,OUT,PF(DELRT)
ADVANCE FN5
BLET PF(CVSEC)=FN3 //32 OR 33
BLET PF(PCODE)=CSTRIM //DEFAULT TO CUSTOM TRIM
TEST E &TCOAT(PFSENGINE),0,*+2 //ANY PAINT STD?
BLET PF(PCODE)=FNTRIM //NO;PC=FINAL TRIM
TEST E PF(RJCT),1,TSC215 //REJECT?
BLET PF(PCODE)=REPAIRS //YES;ROUTE TO REPAIRS
TRANSFER ,TSC220
TSC215 ENTER TSTLCOUT
BARG MACRO PQ3, TOP, 100.0*S(TSTLCOUT)/(S(TSTLCOUT)+R(TSTLCOUT))
TEST E BV(ENG105),1,TSC220 //10.5/12.5'S?
BLET PF(PCODE)=PF(PCODE)+10 //YES;RESET PROCESS CODE
TSC220 GATE LC 80 //METER
LOGIC S 80 //CLOSE OFF
GATE LC PF(CVSEC) //CLEARANCE
LOGIC S PF(CVSEC) //ZONE CLEAR
ENTER PF(CVSEC)
PLON3 MACRO XID1,MTL,(PFSCVSEC-30)
ADVANCE ML(CSECT,PFSCVSEC,12)
RELEASE FN11 //EXIT
LOGIC C 80
LOGIC C PF(CVSEC)
TEST L PF(PCODE),10,*+2 //10.5-12.5 DON'T JOIN HERE
JOIN PF(PCODE) //JOIN GROUP
PLON3 MACRO XID1,TL,PFSCVSEC-30
TRANSFER ,TLC060 //ENTER CONV. LOOP
*-----
* RETORQUE AREA
*-----
RTQ000 GATE LC RTORKQ //RETORQUE QUEUE
LOGIC S RTORKQ
ENTER RTORKQ
REMOVE PF(PCODE)
TEST NE BV(RTQBYP),1,RTQ010 //EMPTY OR PAINT?
LEAVE TSTLCOUT
BARG MACRO PQ3, TOP, 100.0*S(TSTLCOUT)/(S(TSTLCOUT)+R(TSTLCOUT))
RTQ010 ADVANCE 0
PLON MACRO XID1,RTQ0
ADVANCE .12
LEAVE PF(PLOC) //FREE RETORQUE INPUT
LOGIC C RTORKQ
UNLINK PF(PLOC),TLC3205,1
ADVANCE .75
BLET PF(PLOC)=37
LINK RTORKQ,FIFO,RTQ050
RTQ050 TEST NE BV(RTQBYP),1,RTQ100 //BYPASS?
SELECT LC CVSECSPF,38,39 //PICK PATH
LOGIC S PF(CVSEC)
TEST NE BV(RTQUL),1,*+2
UNLINK RTORKQ,RTQ050,1
PLON3 MACRO XID1,RTQ,(PFSCVSEC-37) //IN TRAVEL
ADVANCE .15 //CONV. TRAVEL
LEAVE PF(PLOC) //STOP 20 REOPENED
ADVANCE ML(CSECT,PFSCVSEC,1) //QUEUE POSITION
ENTER PF(CVSEC)
PLON3 MACRO XID1,RTS,(PFSCVSEC-37)
ADVANCE .14 //MOVE IN
LOGIC C PF(CVSEC)
UNLINK RTORKQ,RTQ050,1 //MAKE OPENING
BLET PF(CLOC)=PF(CVSEC)+23 //STATION ID 61/62
BLET PL(CYCLE)=&RTORK(PFSENGINE)/&PERF(PFSSMOD)/2.0
TRANSFER SBR,PRO000,SUBR$PF //PROCESS
SCOLOR MACRO XID1,&ECLR(PFSENGINE)
BLET PF(PLOC)=PF(CVSEC) //SAVE LOCATION
BLET PF(CVSEC)=40 //BUMP LOCATION

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GATE LC PF(CVSEC)
LOGIC S PF(CVSEC)
ENTER PF(CVSEC)
ADVANCE .12
LOGIC C PF(CVSEC)
LEAVE PF(PLOC)
ADVANCE ML(CSECT,PF$PLOC,11)-.12 //REMAINING TRAVEL
BLET PF(PLOC)=PF(CVSEC)
BLET PF(CVSEC)=15
BLET &EPROD(3)=&EPROD(3)+1 //COUNT ENGINE IN PROCESS
BLET &PRORATE(2)=&PRORATE(2)+1 //COUNT ENGINE RATE
BARG MACRO RT2, TOP, &PRORATE(2)
BLET &DUM='570'
TRANSFER SBR, FNDMOD, SUBR$PF
GATE LC PF(CVSEC)
LOGIC S PF(CVSEC)
ENTER PF(CVSEC)
PLON3 MACRO XID1, MBB, PF(CVSEC)
ADVANCE ML(CSECT, PF$CVSEC, 12) //MERGE ZONE
TRANSFER , BBD055 //RETURN TO BB
*
RTQ100 BLET PF(CVSEC)=14 //BACKBONE BYPASS
GATE LC PF(CVSEC)
LOGIC S PF(CVSEC)
ENTER PF(CVSEC)
PLON MACRO XID1, BB14
ADVANCE .12 //CLEARANCE
LOGIC C PF(CVSEC)
LEAVE PF(PLOC)
UNLINK RTORKQ, RTQ050, 1 //TAKE NEXT
ADVANCE ML(CSECT, PF$CVSEC, 1) -.12
TRANSFER , BBD020
*-----
* 569 REPAIRS
*-----
RPR000 GATE LC REPRQ //REPAIR QUEUE
LOGIC S REPRQ
ENTER REPRQ
PLON MACRO XID1, RPQ
ADVANCE .12
LEAVE PF(PLOC)
LOGIC C REPRQ
ADVANCE .66
RPR005 SELECT NU CVSEC$PF, 119, 122 //OPEN SPUR
TEST E PF(CVSEC), 0, RPR010
LINK 34, FIFO //AWAIT
RPR010 SEIZE PF(CVSEC) //GET SPUR
ENTER EREPR //EXIT PATH
PLON3 MACRO XID1, IN, PF(CVSEC)
ADVANCE .1 //CLEARANCE
LEAVE REPRQ //FREE QUEUE
ADVANCE .2 //REMAINING PATH
LEAVE EREPR //CLEAR PATH
BLET PF(CLOC)=PF(CVSEC)-118+265 //LOCATION
TEST E PF(RETEST), 0, RPR050 //MAJOR REPAIR?
BLET PL(CYCLE)=&LRPRTIM //TIME
BLET PF(PCODE)=CSTRIM //DEFAULT TO CUSTOM TRIM
TEST E &TCOAT(PF$ENGINE), 0, *+2 //ANY PAINT STD?
BLET PF(PCODE)=FNTRIM //NO; PC=FINAL TRIM
TRANSFER , RPR100
RPR050 BLET PL(CYCLE)=&HRPRTIM //HEAVY REPAIR
BLET PF(PCODE)=CLTEST
RPR100 TRANSFER SBR, PRO000, SUBR$PF //PROCESS TIME
BLET PF(RJCT)=0 //NOT REJECT
RCOLOR MACRO XID1, &ECLR(PF$ENGINE)
ENTER EREPR //PATH CLEAR?
PLON3 MACRO XID1, OUTB, PF(CVSEC) //YES
ADVANCE .09 //BACKOUT
RELEASE PF(CVSEC) //FREE SPUR

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PLON3    UNLINK      34,RPR005,1          //TAKE NEXT
         MACRO      XID1,OUT,PF(CVSEC)  //OUTBOUND PATH
         ADVANCE    .3
         TEST NE    PF(PCODE),CLTEST,RPR110
XXX002   ENTER      TSTLCOUT
BARG     MACRO      PQ3,TOP,100.0*S(TSTLCOUT)/(S(TSTLCOUT)+R(TSTLCOUT))
RPR110   BLET      PF(PLOC)=259          //EXIT PATH
         BLET      PF(CVSEC)=4          //BACKBONE ENTRY
         GATE LC    PF(CVSEC)
         LOGIC S    PF(CVSEC)
         ENTER      PF(CVSEC)
         TEST E    PF(PCODE),CLTEST,RPR150
         BLET      XF(COUNT)=XF(COUNT)+1
         TEST GE    XF(COUNT),&MAX,+2    //COUNT OUT
         LOGIC S    COUNT
RPR150   JOIN      PF(PCODE)            //JOIN NEXT GROUP
PLON3    MACRO      XID1,MBB,PF(CVSEC)
         ADVANCE    ML(CSECT,PFSCVSEC,12) //MERGE ZONE
         TRANSFER   ,BBD055            //RETURN TO BB
-----
* TRIM CONVEYOR
-----
TRM000   GATE LC    STRMI                //INPUT ZONE
         LOGIC S    STRMI                //SHUT OFF ZONE
         ENTER      STRMI                //ENTER ZONE
PLON     MACRO      XID1,TRMI
         ADVANCE    .12                  //INDEX IN
         LOGIC C    STRMI                //CLEAR
         LEAVE      SSTG0                //FREE STAGE
         UNLINK     SSTG0,BBD1730,1
         ADVANCE    1.87
         BLET      PF(CVSEC)=PF(PCODE)*20 //TRIM ZONE
         LINK       STRMI,FIFO,TRM020
TRM020   ENTER      PF(CVSEC)
         ENTER      STRM1
PLON     MACRO      XID1,TRM1
         ADVANCE    .23
         LEAVE      STRMI
         LEAVE      STRM1
         UNLINK     STRMI,TRM020,1
TRM030   TEST E    PF(PCODE),CSTRIM,FNT000 //CUSTOM OR FINAL
-----
* CUSTOM TRIM
-----
PLON     MACRO      XID1,CTC
         ADVANCE    2.15
         BLET      PF(PLOC)=PF(CVSEC)
         BLET      PF(INDX)=1
         BLET      PF(CVSEC)=PF(CVSEC)+1
         LINK       PF(CVSEC),FIFO,CST000
CST000   ENTER      PF(CVSEC)
PLON3    MACRO      XID1,CT,PF(INDX)
         ADVANCE    .12
         LEAVE      PF(PLOC)
         LEAVE      CSTRMCNT
BARG     MACRO      PQ4,TOP,100.0*S(CSTRMCNT)/(S(CSTRMCNT)+R(CSTRMCNT))
         ADVANCE    .15
CST010   TEST LE    PF(INDX),&CSTLS,CST020
         BLET      PF(CLOC)=CTRIM1-1+PF(INDX) //POSITION
         BLET      PL(CYCLE)=ML(CUSTRM,&ECLASI(PFSENGINE),PFSINDX)/&PERF(PFSMOD)
         TEST G     PL(CYCLE),0,CST020
         TRANSFER   SBR,PRO000,SUBRSPF
CST020   BLET      PF(PLOC)=PF(CVSEC)
         BLET      PF(INDX)=PF(INDX)+1
         BLET      PF(CVSEC)=PF(CVSEC)+1
         ENTER      PF(CVSEC)
         LEAVE      PF(PLOC)
PLON3    MACRO      XID1,CT,PF(INDX)
         TEST E    PFSINDX,2,CST030

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CST030  UNLINK      PF$PLOC,CST000,1
        TEST NE    PF(CVSEC),149,CST110
        ADVANCE    .27
        TRANSFER   ,CST010
*
CST110  ADVANCE    .93
        BLET      PF(PCODE)=PNTSYS
        TEST G    &BTRIM(PF$ENGINE),0,*+2
        BLET      PF(PCODE)=FNTRIM
        LINK      PF(CVSEC),FIFO,CST120
CST120  ENTER      (294+PF$PCODE)
BARG4   MACRO      PQ,(PF$PCODE-3),TOP,100.0*S(294+PF$PCODE)/(S(294+PF$PCODE)+_
        R(294+PF$PCODE))
        BLET      &PRORATE(3)=&PRORATE(3)+1 //COUNT ENGINE IN PROCESS
BARG    MACRO      RT3,TOP,&PRORATE(3)
        GATE LC   TRMOUT
        LOGIC S   TRMOUT
        ENTER     TRMOUT
PLON    MACRO      XID1,TRMOM
        ADVANCE    .12
        LEAVE     PF(CVSEC)
        BLET      &EPROD(4)=&EPROD(4)+1 //COUNT ENGINE IN PROCESS
        UNLINK    PF(CVSEC),CST120,1
TRM100  LOGIC C    TRMOUT
PLON    MACRO      XID1,TRMO
        ADVANCE    1.39
        BLET      PF(PLOC)=158 //EXIT PATH
        BLET      PF(CVSEC)=17 //BACKBONE ENTRY
        GATE LC   PF(CVSEC)
        LOGIC S   PF(CVSEC)
        ENTER     PF(CVSEC)
        ENTER     BACKBCNT //BACKBONE ZONE
        TEST GE   S(BACKBCNT),&BBLIM,*+2 //AT CHOKE LIMIT
        LOGIC S   BACKBCNT //CLOSE OFF ZONE
PLON3   MACRO      XID1,MBB,PF(CVSEC)
        ADVANCE    ML(CSECT,PF$CVSEC,12) //MERGE ZONE
        TRANSFER   ,BBD055
*-----
* FINAL TRIM
*-----
FNT000  BLET      &DUM='571'
        TRANSFER  SBR,FNDMOD,SUBRSPF
PLON    MACRO      XID1,FTO
        ADVANCE    1.58
        BLET      PF(PLOC)=PF(CVSEC)
        BLET      PF(INDX)=1
        BLET      PF(CVSEC)=PF(CVSEC)+1
        LINK      PF(CVSEC),FIFO,FNT010
FNT010  ENTER     PF(CVSEC)
PLON3   MACRO      XID1,FT,PF(INDX)
        ADVANCE    .12
        LEAVE     PF(PLOC)
        LEAVE     FNTRMCNT
BARG    MACRO      PQ5,TOP,100.0*S(FNTRMCNT)/(S(FNTRMCNT)+R(FNTRMCNT))
        ADVANCE    .15
FNT020  TEST NE    PF(DELRT),99,FNT030
        TEST LE    PF(INDX),&FNTPS,FNT030
        BLET      PF(CLOC)=FTRIM1-1+PF(INDX) //POSITION
        BLET      PL(CYCLE)=ML(FNLTRM,&ECLASI(PF$ENGINE),PFSINDX)/&PERF(PF$MOD)
        TEST G    PL(CYCLE).0,FNT030
        TRANSFER  SBR,PRO000,SUBRSPF
FNT030  BLET      PF(PLOC)=PF(CVSEC)
        BLET      PF(INDX)=PF(INDX)+1
        BLET      PF(CVSEC)=PF(CVSEC)+1
        ENTER     PF(CVSEC)
        LEAVE     PF(PLOC)
PLON3   MACRO      XID1,FT,PF(INDX)
        TEST E    PFSINDX,2,FNT040
        UNLINK    PF$PLOC,FNT010,1

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FNT040  TEST NE    PF(CVSEC),169,FNT110
        ADVANCE   .27
        TRANSFER  ,FNT020
*
FNT110  ADVANCE   .13
        BLET      PF(CLOC)=FTRIM1-1+PF(INDX) //POSITION
        BLET      PL(CYCLE)=ML(FNLTRM,&ECLASI(PFSENGINE),PFSINDX)/&PERF(PFSMOD)
        TEST G    PL(CYCLE),0,FNT120
        TRANSFER  SBR,PRO000,SUBR$PF
FNT120  SPLIT     1,FIN000 //SEND TO INSPECTION
SCOLOR  MACRO     XID1,'WHITE'
WRITEO  MACRO     LBRID,XID1,'EMPTY'
        RLET      &PRORATE(4)=&PRORATE(4)+1 //COUNT ENGINE IN PROCESS
BARG    MACRO     RT4, TOP, &PRORATE(4)
        BLET      PF(ENGINE)=0
        BLET      PF(PCODE)=0
        BLET      PF(DELRT)=0
        ENTER     TRMOUT
        GATE LC   TRMOUT
        LOGIC S   TRMOUT
PLON    MACRO     XID1,MTRMO
        ADVANCE   .23
        LEAVE     PF(CVSEC)
        TRANSFER  ,TRM100
.....
* PAINT SYSTEM
.....
PST000  GATE LC   SPNT1 //ENTER PAINT
        LOGIC S   SPNT1
        ENTER     SPNT1
        BLET      &DUM='570P'
        TRANSFER  SBR,FNDMOD,SUBR$PF
PLON    MACRO     XID1,PNT1
        ADVANCE   .12 //CLEAR LIMIT
        LEAVE     SSTG0
        LOGIC C   SPNT1
        UNLINK    SSTG0,BBD1730,1
        ADVANCE   2.35
*
* Washer process chain.
*
PST010  LINK      SPNT1,FIFO,PST010
        GATE LC   SPNT2 //TRANSITION TO PROCESS CHAIN
        LOGIC S   SPNT2
PLON    MACRO     XID1,PXFR
        ADVANCE   .13
        ENTER     SPNT2
        LEAVE     SPNT1 //FREE INPUT QUEUE
        LEAVE     PAINTCNT
BARG    MACRO     PQ6, TOP, 100.0*S(PAINTCNT)/(S(PAINTCNT)+R(PAINTCNT))
PLON    MACRO     XID1,PNT2
        ADVANCE   8.02/&PNTSSP //TIME TO INDEX INTO PAINT
        LOGIC C   SPNT2
        UNLINK    SPNT1,PST010,1
        ADVANCE   49.70/&PNTSSP //REMAINING TRAVEL
        GATE LC   SPNT3 //TRANSITION TO PROCESS CHAIN
        LOGIC S   SPNT3
        ENTER     SPNT3
PLON    MACRO     XID1,PNT3
        ADVANCE   .12
        LEAVE     SPNT2
        LOGIC C   SPNT3
        ADVANCE   .25 //TIME TO INDEX INTO PAINT
        GATE LC   SPNT4 //TRANSITION TO PROCESS CHAIN
        LOGIC S   SPNT4
        BLET      PF(CLOC)=PMASK
        BLET      PL(CYCLE)=(&MASK(PFSENGINE)+&BLOWO(PFSENGINE))/&PERF(PFSMOD)
        TRANSFER  SBR,PRO000,SUBR$PF
        SPLIT     1,PST100 //THROUGH PREP

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        LOGIC C      SPNT4
        LINK         SPNT3,FIFO
PST020  ENTER       SPNT4
        LEAVE       SPNT3
PLON    MACRO      XID1,PNT4
        ADVANCE     .20                //TIME TO INDEX INTO PAINT
        BLET        PF(CLOC)=PPRIM
        GATE SF     SPNT5,PST030       //SECOND STOP OPEN?
        BLET        PF(CLOC)=0        //NO TAG AS SECOND LOAD BAR
        LINK       SPNT4,FIFO
PST030  ENTER       SPNT5                //Enter initial section of oven.
        LEAVE       SPNT4
PLON    MACRO      XID1,PNT5
        ADVANCE     .14                //Delay for path time.
        TEST NE    PF(CLOC),0,PST040
        BLET        PF(CLOC)=PNTTC
        BLET        PL(CYCLE)=5.0
        TRANSFER   SBR,PRO000,SUBR$PF
        GATE LC    464                //PAINT DELAY UNDERWAY
        UNLINK     SPNT4,PST030,1
PST040  MARK       DELAYSPL           //START FLASHOFF TIME
        ENTER      SPNT6
        LEAVE      SPNT5
        TEST E     PF(CLOC),0,*+2
        SPLIT     1,PST100
PLON    MACRO      XID1,PNT6
        ADVANCE     1.5                //TRAVEL TIME
        LINK       SPNT6,FIFO,PST042
PST042  GATE LC    SPNT6                //CAPTURE EXIT STOP
        LOGIC S    SPNT6
        BLET        PL(CYCLE)=&FLASH-MPSDELAYSPL //AWAIT FLASH-OFF
        TEST G     PL(CYCLE),0,*+2
        ADVANCE    PL(CYCLE)           //AWAIT FLASH-OFF
.
. Oven.
.
        ENTER      SPNT7
        LEAVE      SPNT6
        LOGIC C    SPNT6
        UNLINK     SPNT6,PST042,1
PLON    MACRO      XID1,PNT7
        ADVANCE     .69
        LINK       SPNT7,FIFO,PST044
PST044  GATE LC    SPNT7                //CAPTURE EXIT STOP
        LOGIC S    SPNT7
        BLET        PL(CYCLE)=&TIMEOVEN-MPSDELAYSPL //AWAIT BAKE
        TEST G     PL(CYCLE),0,*+2
        ADVANCE    PL(CYCLE)           //AWAIT OVEN TIME
        ENTER      SPNT8
        LEAVE      SPNT7
        LOGIC C    SPNT7
        UNLINK     SPNT7,PST044,1
PLON    MARK       DELAYSPL           //START COOLDOWN
        MACRO      XID1,PNT8           //COOL DOWN ZONE
        ADVANCE    2.45
        BLET        &EPROD(7)=&EPROD(7)+1 //COUNT ENGINE IN PROCESS
        BLET        &PRORATE(5)=&PRORATE(5)+1 //COUNT ENGINE IN PROCESS
BARG    MACRO      RT5,TOP,&PRORATE(5)
        GATE LC    SPNT8                //CAPTURE EXIT STOP
        LOGIC S    SPNT8
        BLET        PL(CYCLE)=&COOL-MPSDELAYSPL //AWAIT COOLDOWN
        TEST G     PL(CYCLE),0,*+2
        ADVANCE    PL(CYCLE)           //AWAIT COOLING
        LOGIC C    SPNT8
        BLET        PF(PCODE)=FNTRIM //PC=FINAL TRIM
        TEST G     &BTRIM(PF$ENGINE),0,*+2
        BLET        PF(DELRT)=99      //TAG AS BLUEBIRD
        BLET        PF(CVSEC)=PF(PCODE)*20 //BACKBONE ENTRY

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LINK          SPNT8, FIFO, PST050
PST050 ENTER  (294+PF$PCODE)
BARG4  MACRO  PQ, (PF$PCODE-3), TOP, 100.0*S(294+PF$PCODE)/(S(294+PF$PCODE)+_
R(294+PF$PCODE))
          ENTER CVSEC)
          ENTER STRM1
PLON   MACRO  XID1, MTRM1
          ADVANCE .55 //MERGE ZONE
          LEAVE SPNT8
          LEAVE STRM1
          UNLINK SPNT8, PST050, 1
          TRANSFER , TRM030 //RETURN TO BB
*
PST100 TEST E  BV(P$BATCH), 1, PST120
          BLET  PF(LCTR)=2
PST110 UNLINK SPNT3, PST020, 1
          ADVANCE .1
          LOOP  LCTR$PF, PST110
PST120 TERMINATE
*
* FINISHED ENGINE DATA
*
FIN000 TEST NE PF(DELRT), 99, BLU000 //BLUEBIRD ENGINE?
          BLET  &OFLDENG$=&OFLDENG$+1
          BLET  ML(PROD, PF$ENGINE, 2)=ML(PROD, PF$ENGINE, 2)+1
          BLET  ML(PROD, 100, 2)=ML(PROD, 100, 2)+1
          BLET  &FTRMENG$=&FTRMENG$+1
          BLET  ML(PROD, PF$ENGINE, 2)=ML(PROD, PF$ENGINE, 2)+1
          BLET  ML(PROD, 100, 2)=ML(PROD, 100, 2)+1
          BLET  &EPROD(5) = &EPROD(5) + 1 //COUNT ENGINE IN PROCESS
          BLET  &INV572(PF$ENGINE) = &INV572(PF$ENGINE) + 1 //COUNT IN
          BLET  &INV572(100) = &INV572(100) - 1 //COUNT IN TOTAL
          BLET  &INPROC = &INPROC - 1 //COUNT OUT
          LEAVE EWIPQ
WRITE  MACRO  INP, &INPROC
BARG  MACRO  IPB, RIGHT, &INPROC
WRITE  MACRO  IV572, &INV572(100)
BARG  MACRO  IVB, RIGHT, &INV572(100)
          TEST G PL(LAPTIM), 0, FIN010 //NON-INITIAL LOAD?
* COLLECT TIME BY ENGINE
          BLET  ML(PROTIME, PF$ENGINE, 1) = ML(PROTIME, PF$ENGINE, 1) + MPSLAPTIMSPL
          BLET  ML(PROTIME, PF$ENGINE, 2) = ML(PROTIME, PF$ENGINE, 2) + 1
          BLET
ML(PROTIME, PF$ENGINE, 1) = ML(PROTIME, PF$ENGINE, 1) / ML(PROTIME, PF$ENGINE, 2)
          TEST E ML(PROTIME, PF$ENGINE, 2), 1, *+3
          BLET  ML(PROTIME, PF$ENGINE, 4) = MPSLAPTIMSPL //MAX
          BLET  ML(PROTIME, PF$ENGINE, 5) = MPSLAPTIMSPL //MIN
          TEST G MPSLAPTIMSPL, ML(PROTIME, PF$ENGINE, 4), *+2
          BLET  ML(PROTIME, PF$ENGINE, 4) = MPSLAPTIMSPL //MAX
          TEST L MPSLAPTIMSPL, ML(PROTIME, PF$ENGINE, 5), *+2
          BLET  ML(PROTIME, PF$ENGINE, 5) = MPSLAPTIMSPL //MIN
* COLLECT TIME IN TOTAL
          BLET  ML(PROTIME, 100, 1) = ML(PROTIME, 100, 1) + MPSLAPTIMSPL
          BLET  ML(PROTIME, 100, 2) = ML(PROTIME, 100, 2) + 1
          BLET  ML(PROTIME, 100, 3) = ML(PROTIME, 100, 1) / ML(PROTIME, 100, 2)
          TEST E ML(PROTIME, 100, 2), 1, *+3
          BLET  ML(PROTIME, 100, 4) = MPSLAPTIMSPL //MAX
          BLET  ML(PROTIME, 100, 5) = MPSLAPTIMSPL //MIN
          TEST G MPSLAPTIMSPL, ML(PROTIME, 100, 4), *+2
          BLET  ML(PROTIME, 100, 4) = MPSLAPTIMSPL //MAX
          TEST L MPSLAPTIMSPL, ML(PROTIME, 100, 5), *+2
          BLET  ML(PROTIME, 100, 5) = MPSLAPTIMSPL //MIN
          WRITE MACRO SYST, (ML(PROTIME, 100, 3) / 60.0)
* PROCESS COUNT
FIN010 BLET  ML(ESYS$PRF, 1, 2) = ML(ESYS$PRF, 1, 2) + 1
          TEST E ML(ESYS$PRF, 1, 2), 1, *+2
          BLET  ML(ESYS$PRF, 1, 5) = &INPROC //MIN
          TEST L &INPROC, ML(ESYS$PRF, 1, 5), *+2
          BLET  ML(ESYS$PRF, 1, 5) = &INPROC //MIN

```

```

* FINISH SEQUENCE
  BLET      &FINORD=&FINORD+1                //FINISH ORDER
  BLET      ML (SEQVAR, PFSENGINE, 1) =ML (SEQVAR, PFSENGINE, 1) +V$FINSEQ
  BLET      ML (SEQVAR, PFSENGINE, 2) =ML (SEQVAR, PFSENGINE, 2) +1
  BLET      ML (SEQVAR, PFSENGINE, 3) =ML (SEQVAR, PFSENGINE, 1) /ML (SEQVAR, PFSENGINE, 2)
  TEST E    ML (SEQVAR, PFSENGINE, 2) , 1 , *+3
  BLET      ML (SEQVAR, PFSENGINE, 4) =V$FINSEQ //MAX
  BLET      ML (SEQVAR, PFSENGINE, 5) =V$FINSEQ //MIN
  TEST G    V$FINSEQ, ML (SEQVAR, PFSENGINE, 4) , *+2
  BLET      ML (SEQVAR, PFSENGINE, 4) =V$FINSEQ //MAX
  TEST L    V$FINSEQ, ML (SEQVAR, PFSENGINE, 5) , *+2
  BLET      ML (SEQVAR, PFSENGINE, 5) =V$FINSEQ //MIN

* FINISH SEQUENCE IN TOTAL
  BLET      ML (SEQVAR, 100, 1) -ML (SEQVAR, 100, 1) -V$FINSEQ
  BLET      ML (SEQVAR, 100, 2) =ML (SEQVAR, 100, 2) +1
  BLET      ML (SEQVAR, 100, 3) =ML (SEQVAR, 100, 1) /ML (SEQVAR, 100, 2)
  TEST E    ML (SEQVAR, 100, 2) , 1 , *+3
  BLET      ML (SEQVAR, 100, 4) =V$FINSEQ //MAX
  BLET      ML (SEQVAR, 100, 5) =V$FINSEQ //MIN
  TEST G    V$FINSEQ, ML (SEQVAR, 100, 4) , *+2
  BLET      ML (SEQVAR, 100, 4) =V$FINSEQ //MAX
  TEST L    V$FINSEQ, ML (SEQVAR, 100, 5) , *+2
  BLET      ML (SEQVAR, 100, 5) =V$FINSEQ //MIN

FIN050 MARK LAPTMSPL //TIME IN TRUCK GRID
  BLET      PF (LOC2) =0 //ZERO OUT
  SELECT E  LOC1$PF, 51, 300, PFSTSEQN, XH, FIN055
  JOIN      PFSLOC1
  TEST E    G (PFSLOC1) , &TRKLD (PFSTSEQN) , FIN060
  SPLIT     1, SHP000
  TRANSFER  , FIN060

FIN055 SELECT E  LOC1$PF, 51, 300, 0, XH
  BLET      XH (PFSLOC1) =PFSTSEQN
  JOIN      PFSLOC1
  BLET      PFSLOC2=1
  QUEUE     TGRIDS

FIN060 LINK FINV, FIFO //GO INTO INVENTORY
FIN080 LEAVE TOTALQ
  REMOVE    PFSLOC1
  BLET      &INV572 (PFSENGINE) =&INV572 (PFSENGINE) -1
  BLET      &INV572 (100) =&INV572 (100) -1

* WAREHOUSE COUNT-MINIMUM
  BLET      ML (ESYSRPF, 2, 2) =ML (ESYSRPF, 2, 2) +1
  TEST E    ML (ESYSRPF, 2, 2) , 1 , *+2
  BLET      ML (ESYSRPF, 2, 5) =CH (FINV) //MIN
  TEST L    CH (FINV) , ML (ESYSRPF, 2, 5) , *+2
  BLET      ML (ESYSRPF, 2, 5) =CH (FINV) //MIN

* TOTAL COUNT-MINIMUM
  BLET      ML (ESYSRPF, 3, 2) =ML (ESYSRPF, 3, 2) +1
  TEST E    ML (ESYSRPF, 3, 2) , 1 , *+2
  BLET      ML (ESYSRPF, 3, 5) =S (TOTALQ) //MIN
  TEST L    S (TOTALQ) , ML (ESYSRPF, 3, 5) , *+2
  BLET      ML (ESYSRPF, 3, 5) =S (TOTALQ) //MIN

* COLLECT WAREHOUSE TIME BY ENGINE
FIN090 TEST G PL (LAPTIM) , 0, FIN095
  BLET      ML (WHSETIM, PFSENGINE, 1) =ML (WHSETIM, PFSENGINE, 1) +MPSLAPTMSPL
  BLET      ML (WHSETIM, PFSENGINE, 2) =ML (WHSETIM, PFSENGINE, 2) +1
  BLET      ML (WHSETIM, PFSENGINE, 3) =ML (WHSETIM, PFSENGINE, 1) /ML (WHSETIM, PFSENGINE, 2)
  TEST E    ML (WHSETIM, PFSENGINE, 2) , 1 , *+3
  BLET      ML (WHSETIM, PFSENGINE, 4) =MPSLAPTMSPL //MAX
  BLET      ML (WHSETIM, PFSENGINE, 5) =MPSLAPTMSPL //MIN
  TEST G    MPSLAPTMSPL, ML (WHSETIM, PFSENGINE, 4) , *+2
  BLET      ML (WHSETIM, PFSENGINE, 4) =MPSLAPTMSPL //MAX
  TEST L    MPSLAPTMSPL, ML (WHSETIM, PFSENGINE, 5) , *+2
  BLET      ML (WHSETIM, PFSENGINE, 5) =MPSLAPTMSPL //MIN

* COLLECT WAREHOUSE TIME IN TOTAL
  BLET      ML (WHSETIM, 100, 1) =ML (WHSETIM, 100, 1) +MPSLAPTMSPL
  BLET      ML (WHSETIM, 100, 2) =ML (WHSETIM, 100, 2) +1
  BLET      ML (WHSETIM, 100, 3) =ML (WHSETIM, 100, 1) /ML (WHSETIM, 100, 2)

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TEST E      ML(WHSETIM,100,2),1,*+3
BLET       ML(WHSETIM,100,4)=MPSLAPTIMSPL           //MAX
BLET       ML(WHSETIM,100,5)=MPSLAPTIMSPL           //MIN
TEST G      MPSLAPTIMSPL,ML(WHSETIM,100,4),*+2
BLET       ML(WHSETIM,100,4)=MPSLAPTIMSPL           //MAX
TEST L      MPSLAPTIMSPL,ML(WHSETIM,100,5),*+2
BLET       ML(WHSETIM,100,5)=MPSLAPTIMSPL           //MIN

* DAILY SHIPMENTS
FIN095     BLET      MH(DSHIPS,PFSENGINE,&SDAY)=MH(DSHIPS,PFSENGINE,&SDAY)+1
BLET      MH(DSHIPS,PFSENGINE,21)=MH(DSHIPS,PFSENGINE,21)+1
BLET      MH(DSHIPS,100,&SDAY)=MH(DSHIPS,100,&SDAY)+1
BLET      MH(DSHIPS,100,21)=MH(DSHIPS,100,21)+1
WRITE     MACRO     IV572,&INV572(100)
BARG     MACRO     IVB,RIGHT,&INV572(100)
WRITE     MACRO     SPE,MH(DSHIPS,100,21)
BARG     MACRO     SPB,RIGHT,MH(DSHIPS,100,21)
BLET      &EPROD(6)=&EPROD(6)+1                     //COUNT ENGINE IN PROCESS
TEST E      PF(LOC2),1,FIN100
DEPART    TGRIDS
BLET      PF(JNDX)=MX(SHIPS,PFSSEQNM,5)             //CUSTOMER#
BLET      XH(PFSLOC1)=0
BLET      MH(TSHIPS,PFSJNDX,&SDAY)=MH(TSHIPS,PFSJNDX,&SDAY)+1
BLET      MH(TSHIPS,PFSJNDX,21)=MH(TSHIPS,PFSJNDX,21)+1
BLET      MH(TSHIPS,100,&SDAY)=MH(TSHIPS,100,&SDAY)+1
BLET      MH(TSHIPS,100,21)=MH(TSHIPS,100,21)+1

* COLLECT GRID TIME BY CUSTOMER
BLET      ML(GRIDTIM,PFSJNDX,1)=ML(GRIDTIM,PFSJNDX,1)-MPSLAPTIMSPL
BLET      ML(GRIDTIM,PFSJNDX,2)=ML(GRIDTIM,PFSJNDX,2)-1
BLET      ML(GRIDTIM,PFSJNDX,3)=ML(GRIDTIM,PFSJNDX,1)/ML(GRIDTIM,PFSJNDX,2)
TEST E      ML(GRIDTIM,PFSJNDX,2),1,*+3
BLET      ML(GRIDTIM,PFSJNDX,4)=MPSLAPTIMSPL           //MAX
BLET      ML(GRIDTIM,PFSJNDX,5)=MPSLAPTIMSPL           //MIN
TEST G      MPSLAPTIMSPL,ML(GRIDTIM,PFSJNDX,4),*+2
BLET      ML(GRIDTIM,PFSJNDX,4)=MPSLAPTIMSPL           //MAX
TEST L      MPSLAPTIMSPL,ML(GRIDTIM,PFSJNDX,5),*+2
BLET      ML(GRIDTIM,PFSJNDX,5)=MPSLAPTIMSPL           //MIN

* COLLECT GRID TIME IN TOTAL
BLET      ML(GRIDTIM,100,1)=ML(GRIDTIM,100,1)-MPSLAPTIMSPL
BLET      ML(GRIDTIM,100,2)=ML(GRIDTIM,100,2)+1
BLET      ML(GRIDTIM,100,3)=ML(GRIDTIM,100,1)/ML(GRIDTIM,100,2)
TEST E      ML(GRIDTIM,100,2),1,*+3
BLET      ML(GRIDTIM,100,4)=MPSLAPTIMSPL           //MAX
BLET      ML(GRIDTIM,100,5)=MPSLAPTIMSPL           //MIN
TEST G      MPSLAPTIMSPL,ML(GRIDTIM,100,4),*+2
BLET      ML(GRIDTIM,100,4)=MPSLAPTIMSPL           //MAX
TEST L      MPSLAPTIMSPL,ML(GRIDTIM,100,5),*+2
BLET      ML(GRIDTIM,100,5)=MPSLAPTIMSPL           //MIN

FIN100     TERMINATE

*-----*
* SHIPPING SCHEDULE
*-----*
SHP000     BLET      PF(DELRT)=0                     //STARTING TRUCK
GATE LC    DINIT,SHP010                             //1ST ONE HERE?
SPLIT      1,SIMC90                                  //YES;CREATE SIMULATION CONTROL
GATE LS     DINIT
SHP010     BLET      PF(INDX)=0                     //RESET INDEX
MARK       LAPTIMSPL
BLET      PF(PTR)=0                                  //ZERO OUT
BLET      &DUM='572'
TRANSFER   SBR,FNDMOD,SUBRSPF
BLET      PF(CLOC)=SHIPR                             //SHIPPER LOCATES ENGINES
BLET      PL(CYCLE)=&SHPTIM(1)
TRANSFER   SBR,PRO000,SUBRSPF                       //PROCESS TIME
BLET      PF(CLOC)=ANALYST                           //ANALYSIS PRINTS TAGS
BLET      PL(CYCLE)=&SHPTIM(2)
TRANSFER   SBR,PRO000,SUBRSPF                       //PROCESS TIME
BLET      PF(CLOC)=SHIPR                             //SHIPPER TAGS ENGINES
BLET      PL(CYCLE)=&SHPTIM(3)
TRANSFER   SBR,PRO000,SUBRSPF                       //PROCESS TIME

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ENTER      DOCKS                                //YES;OPEN DOCK DOOR?
BLET      PF(CLOC)=TRCK572                       //TRUCKERS LOAD TRUCK
BLET      PL(CYCLE)=&SHPTIM(4)
TRANSFER  SBR,PRO000,SUBR$PF                     //PROCESS TIME
BLET      PF(CLOC)=CLERK                         //TRUCKERS LOAD TRUCK
BLET      PL(CYCLE)=&SHPTIM(5)
TRANSFER  SBR,PRO000,SUBR$PF                     //PROCESS TIME
LEAVE     DOCKS                                  //TRUCK LEAVES DOCK
UNLINK    FINV,FIN080,ALL,TSEQNSPF,PFTSEQN
BLET      XH(PF$LOC1)=0
* COLLECT TRUCK LOAD TIME BY CUSTOMER
BLET      PF(JNDX)=MX(SHIPS,PFSSEQNM,5)          //CUSTOMER#
BLET      ML(TRKLDTIM,PFSJNDX,1)=ML(TRKLDTIM,PFSJNDX,1)+MPSLAPTIM$SPL
BLET      ML(TRKLDTIM,PFSJNDX,2)=ML(TRKLDTIM,PFSJNDX,2)+1
BLET      ML(TRKLDTIM,PFSJNDX,3)=ML(TRKLDTIM,PFSJNDX,1)/ML(TRKLDTIM,PFSJNDX,2)
TEST E    ML(TRKLDTIM,PFSJNDX,2),1,*+3
BLET      ML(TRKLDTIM,PFSJNDX,4)=MPSLAPTIM$SPL //MAX
BLET      ML(TRKLDTIM,PFSJNDX,5)=MPSLAPTIM$SPL //MIN
TEST G    MPSLAPTIM$SPL,ML(TRKLDTIM,PFSJNDX,4),*-2
BLET      ML(TRKLDTIM,PFSJNDX,4)=MPSLAPTIM$SPL //MAX
TEST L    MPSLAPTIM$SPL,ML(TRKLDTIM,PFSJNDX,5),*-2
BLET      ML(TRKLDTIM,PFSJNDX,5)=MPSLAPTIM$SPL //MIN
* COLLECT TRUCK LOAD TIME IN TOTAL
BLET      ML(TRKLDTIM,100,1)=ML(TRKLDTIM,100,1)+MPSLAPTIM$SPL
BLET      ML(TRKLDTIM,100,2)=ML(TRKLDTIM,100,2)+1
BLET      ML(TRKLDTIM,100,3)=ML(TRKLDTIM,100,1)/ML(TRKLDTIM,100,2)
TEST E    ML(TRKLDTIM,100,2),1,*+3
BLET      ML(TRKLDTIM,100,4)=MPSLAPTIM$SPL //MAX
BLET      ML(TRKLDTIM,100,5)=MPSLAPTIM$SPL //MIN
TEST G    MPSLAPTIM$SPL,ML(TRKLDTIM,100,4),*-2
BLET      ML(TRKLDTIM,100,4)=MPSLAPTIM$SPL //MAX
TEST L    MPSLAPTIM$SPL,ML(TRKLDTIM,100,5),*-2
BLET      ML(TRKLDTIM,100,5)=MPSLAPTIM$SPL //MIN
TERMINATE
*
* REJECT % SUBROUTINE
*
RPCT00    TEST LE    PF(PCT),50,RPCT50            //>100%
RPCT10    TEST E    PF$CTR@FN12,0,RPCT70         //NO;REJECT?
BLET      PF(RJCT)=1                             //YES;TAG
TRANSFER  ,PF(SUBR)+1                            //RETURN
RPCT50    TEST NE    PF(PCT),100,(PF$SUBR+1)     //100%
TEST E    PF$CTR@2,0,RPCT60                     //50% GET REJECT
RPCT55    BLET      PF(RJCT)=1                   //YES;TAG
TRANSFER  ,PF(SUBR)-1                            //RETURN
RPCT60    BLET      PF(PCT)=PF(PCT)-50          //REDUCE ORIGINAL BY 50%
TRANSFER  ,RPCT10
RPCT70    TEST G    FN13,0,(PF$SUBR+1)          //2NDARY REJECT ADD?
TEST E    PF$CTR@FN13,0,(PF$SUBR+1)            //NO;REJECT?
BLET      PF(RJCT)=1                             //YES;TAG
TRANSFER  ,PF(SUBR)+1                            //RETURN
*
* FIND MODULE # SUBROUTINE
*
FNDMOD    BLET      PF(MOD)=0                    //ZERO OUT
FNDM00    BLET      PF(MOD)=PF(MOD)+1           //BUMP
TEST NE    &MODID(PF$MOD),&DUM,(PF$SUBR+1)    //RETURN IF MATCH
TRANSFER  ,FNDM00
*-----*
* DOWN TIME LOGIC
*-----*
DWT000    TEST NE    PF(JNDX),0,DWT100          //ANY DELAY TIME SPECIFIED?
LINK      FAILR,FIFO
DWT010    ADVANCE    &DELAY1(PFSINDX)          //HOLD FAILURE PULSES
DWT020    LOGIC S    450+PF(INDX)              //TIME UNTIL 1ST DELAY
SCOLOR3   MACRO     DOBJ,PFSINDX,'RED'
ADVANCE    &DTIM(PFSINDX)                      //DELAY TIME
SCOLOR3   MACRO     DOBJ,PFSINDX,'BAC'
LOGIC C    450+PF(INDX)                        //REMOVE BLOCKAGE

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                ADVANCE    &MTBF(PFSINDX)           //MEAN TIME BETWEEN FAILURE
                LOOP       LCTRS$PF,DWT020         //CONTINUE W/ #DELAYS
DWT100  TERMINATE                                     //NUMBER COMPLETE
*
* DAY DEFINITION AND SIMULATION DURATION
*
SIMC00  BLET          &SDAY=1                     //STARTING DAY
        LOGIC S      DINIT                         //RELEASE REST
        TRANSFER    ,SIMC15
SIMC10  BPUTPIC      &SDAY                       //INDICATE MODEL STATUS
        Simulating Production Day: **
WRITE   MACRO        DAY,&SDAY
SIMC15  ADVANCE      1440
        SPLIT       1,SIMC99                     //CREATE TERMINATION PULSE
        PRIORITY    -1,YIELD                     //LET IT GET THER
        PRIORITY    0
        TEST G      NSSIMC10,0,SIMC10
        BLET        &SDAY=&SDAY-1                 //BUMP DAY
        TEST LE     &SDAY,&RUNDAYS,SIMC20
        TRANSFER    ,SIMC10                     //REPEAT
SIMC20  TERMINATE
*
* RATE COLLECTION/PLOTTING LOGIC
*
PLT000  BLET          PF(CLOC)=0
        BLET        PF(LCTR)=6
PLT010  BLET          PL(PF$LCTR)=0
        LOOP        LCTRS$PF,PLT010
        BLET        PF(LOC1)=0
        SPLIT       5,PLT020,LOC1$PF
PLT020  BLET          PF(PLOC)=PF(CLOC)
        BLET        PF(CLOC)=PF(CLOC)+1
        TEST E      PF(CLOC),25,PLT030
        BLET        PF(CLOC)=1
        BLET        PF(PLOC)=0
PLT030  BLET          &NUM=&ITOCCHAR(PF$CLOC)
        BLET        &NUM='#'||&NUM
        TEST NE     PF(LOC1),6,PLT040
PLOT4   MACRO        RTPLT,PF$LOC1,&NUM,PF$PLOC,PL(PF$LOC1),PF$CLOC,_
                &PRORATE(PF$LOC1),&PCLR(PF$LOC1+1)
        TRANSFER    SBR,FLOW00,SUBR$PF
PLT040  ADVANCE      0
PLOT4   MACRO        PQPLT,PF$LOC1,&NUM,PF$PLOC,PL$CMPEST,PF$CLOC,_
                FNSPROCQ,&PCLR(PF$LOC1)
        TRANSFER    SBR.KEYQ00,SUBR$PF
        BLET        PL(PF$LOC1) =&PRORATE(PF$LOC1)
        BLET        PL(CMPEST) =FN(PROCQ)
        BLET        &PRORATE(PF$LOC1)=0           //ZERO OUT
        TEST NE     PF(LOC1),6,PLT050
BARG4   MACRO        RT,PF$LOC1,TOP,&PRORATE(PF$LOC1)
PLT050  ADVANCE      60                           //WAIT NEXT HOUR
        TRANSFER    ,PLT020
*
* FLOW METER DATA COLLECTION
*
FLOW00  TEST G      &PRORATE(PF$LOC1),0,(PF$SUBR+1)
        BLET        ML(FLOWRT,PF$LOC1,1)=ML(FLOWRT,PF$LOC1,1)-&PRORATE(PF$LOC1)
        BLET        ML(FLOWRT,PF$LOC1,2)=ML(FLOWRT,PF$LOC1,2)+1
        BLET        ML(FLOWRT,PF$LOC1,3)=ML(FLOWRT,PF$LOC1,1)/ML(FLOWRT,PF$LOC1,2)
        TEST E      ML(FLOWRT,PF$LOC1,2),1,*+3
        BLET        ML(FLOWRT,PF$LOC1,4) =&PRORATE(PF$LOC1)           //MAX
        BLET        ML(FLOWRT,PF$LOC1,5) =&PRORATE(PF$LOC1)           //MIN
        TEST G      &PRORATE(PF$LOC1),ML(FLOWRT,PF$LOC1,4),*+2
        BLET        ML(FLOWRT,PF$LOC1,4) =&PRORATE(PF$LOC1)           //MAX
        TEST L      &PRORATE(PF$LOC1),ML(FLOWRT,PF$LOC1,5),*+2
        BLET        ML(FLOWRT,PF$LOC1,5) =&PRORATE(PF$LOC1)           //MIN
        TRANSFER    ,(PF$SUBR+1)
*

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* CRITICAL QUEUE DATA COLLECTION
*
KEYQ00  BLET      ML (KEYQUE, PFSLOC1, 1) =ML (KEYQUE, PFSLOC1, 1) +FN (PROCQ)
        BLET      ML (KEYQUE, PFSLOC1, 2) =ML (KEYQUE, PFSLOC1, 2) +1
        BLET      ML (KEYQUE, PFSLOC1, 3) =ML (KEYQUE, PFSLOC1, 1) /ML (KEYQUE, PFSLOC1, 2)
TEST E   ML (KEYQUE, PFSLOC1, 2), 1, *+3
        BLET      ML (KEYQUE, PFSLOC1, 4) =FN (PROCQ)           //MAX
        BLET      ML (KEYQUE, PFSLOC1, 5) =FN (PROCQ)           //MIN
TEST G   FN (PROCQ), ML (KEYQUE, PFSLOC1, 4), *+2
        BLET      ML (KEYQUE, PFSLOC1, 4) =FN (PROCQ)           //MAX
TEST L   FN (PROCQ), ML (KEYQUE, PFSLOC1, 5), *+2
        BLET      ML (KEYQUE, PFSLOC1, 5) =FN (PROCQ)           //MIN
TRANSFER , (PFSSUBR+1)

SIMC90  SPLIT    1, SIMC00           //DONE INITIALIZING
        SPLIT    1, PLT000
SIMC99  TERMINATE 1

        START    2, NP
        RESET
        LET      &EPROD(1)=0
        LET      &EPROD(2)=0
        LET      &EPROD(3)=0
        LET      &EPROD(4)=0
        LET      &EPROD(5)=0
        LET      &EPROD(6)=0
        LET      &EPROD(7)=0
        LET      &EPROD(8)=0
        LET      &PRORATE(1)=0
        LET      &PRORATE(2)=0
        LET      &PRORATE(3)=0
        LET      &PRORATE(4)=0
        LET      &PRORATE(5)=0
        LET      &PRORATE(6)=0
        LET      &JHKCOTIM=0
        INITIAL  MLSPROD(1-100, 2-9), 0
        INITIAL  MLSESYSPRF(1-10, 1-5), 0
        INITIAL  MHSDSHIPS(1-100, 1-21), 0
        INITIAL  MHSTSHIPS(1-100, 1-21), 0
        INITIAL  MLSFLOWRT(1-6, 1-5), 0
        INITIAL  MLSKEYQUE(1-6, 1-5), 0
        START    &RUNDAYS
        PUTPIC   &SDAY

Simulation Completed!

        REPORT
        OUTPUT

        PUTPIC   FILE=OUT, LINES=5, CURDATE

-----
ENGINE WORKS TEST, TRIM, PAINT & SHIP SIMULATION
*****
-----
INPUT CONDITIONS:
PUTPIC   FILE=OUT, LINES=10, (&TESTID, &TESTDSCR, _
        &PRODVOL(1), &PRODVOL(2), &PRODVOL(3), _
        &LBCTMAIN, &HRPRTIM, &LRPRTIM, &LRPRRJ*100.0, _
        &CRPRTIM, &CRPRRJ*100.0, &DOCK)

TEST: *
SCENARIO: *
AVG. LINE RATE-1ST:   ***.* ENGINES/SHIFT
AVG. LINE RATE-2ND:   ***.* ENGINES/SHIFT
AVG. LINE RATE-3RD:   ***.* ENGINES/SHIFT
# LOAD BARS - MAIN:   ***
HEAVY REPAIR:         ***.* MINS.
LIGHT REPAIR:         ***.* MINS. @ ***% REJECT RATE
CELL DELAY:           ***.* MINS. @ ***% DELAY RATE
# EFFECTIVE DOCKS:    **
PUTPIC   FILE=OUT, LINES=8, (&SDAY)

```

RESULTS AFTER: ** SIMULATION DAYS

ENGINE PRODUCTION SUMMARY:

PUTPIC FILE=OUT,LINES=9,&EPROD(1),FLT(&EPROD(1)/&SDAY),_
(&EPROD(&J),FLT(&EPROD(&J)/&SDAY),&J=3,5),_
&EPROD(7),FLT(&EPROD(7)/&SDAY),_
MH(DSHIPS,100,21),FLT(MH(DSHIPS,_
100,21))/FLT(&SDAY),MH(TSHIPS,100,21),FLT(MH(TSHIPS,100,21))/_
FLT(&SDAY)

Table with 2 columns: Category and Value. Categories include J-HOOK PRODUCTION, TEST PRODUCTION, CUSTOM TRIM PRODUCTION, FINAL TRIM PRODUCTION, PAINT PRODUCTION, ENGINE SHIPPED, TRUCKS SHIPPED. Values are represented by asterisks.

PUTPIC FILE=OUT,LINES=11,(SA(EWIPQ),SM(EWIPQ),ML(ESYSPRF,1,5),_
S(EWIPQ),CA(FINV),CM(FINV),ML(ESYSPRF,2,5),CH(FINV),_
QA(TGRIDS),QM(TGRIDS),Q(TGRIDS),SA(TOTALQ),SM(TOTALQ),_
ML(ESYSPRF,3,5),S(TOTALQ),SA(DOCKS),SM(DOCKS),S(DOCKS))

ENGINE PROCESS SUMMARY:

Table with 5 columns: Category, AVG., MAX., MIN., CURRENT. Categories include # ENGINES IN PROCESS/ J-HOOK TO 572, # ENGINES IN 572 (TRUCK GRIDS), # TRUCK GRIDS, TOTAL ENGINES AFTER J-HOOK, TRUCK DOCK USAGE SUMMARY.

PUTPIC FILE=OUT,LINES=4,((ML(PROTIME,100,&J)/1440.0,&J=3,5),_
(ML(WHSETIM,100,&J)/1440.0,&J=3,5),(ML(TRKLDTIM,100,&J)/1440.0,_
&J=3,5))
PROCESS TIME IN DAYS/ J-HOOK TO 572:
WAREHOUSE TIME IN DAYS:
TRUCK LOAD TIME IN DAYS:

PUTPIC FILE=OUT,LINES=8,(ML(SEQVAR,100,&J),&J=3,5)
ENGINE FINISH SEQUENCE VARIATION:

FLOW RATE BY DEPARTMENT:

Table with 7 columns: DEPARTMENT (MINS/ENGINE), TOTAL PRODUCED, # ENGINES /DAY, #SHIFT /DAY, DAYS/ WEEK, EFFECTIVE MINS./DAY, CALCULATED FLOW RATE. Includes conditional logic for department selection.

```

J-HOOK CHANGEOVERS                TOTAL          AVG. /DAY
-----
# CHANGEOVERS:                    ****          ***.*
CHANGEOVER TIME (HOURS):          ***.*          ***.*
% CHANGEOVER:                      ***.* %          ----
    
```

HOURLY FLOW METER SUMMARY (UNITS/HOUR)

```

AREA                                AVG.          MAX.          MIN.
-----
DO                                  &I=1,5
IF                                  &I=1
LET                                  &DUM='JHOOK'
ELSEIF                              &I=2
LET                                  &DUM='TEST'
ELSEIF                              &I=3
LET                                  &DUM='CUSTOM TRIM'
ELSEIF                              &I=4
LET                                  &DUM='FINAL TRIM'
ELSE
LET                                  &DUM='PAINT'
ENDIF
PUTPIC                              FILE=OUT,&DUM,(ML(FLOWRT,&I,&J),&J=3,5)
*****
ENDDO
PUTPIC                              FILE=OUT,LINES=5
    
```

CRITICAL QUEUE SUMMARY

```

AREA                                AVG.          MAX.          MIN.
-----
DO                                  &I=1,6
IF                                  &I=1
LET                                  &DUM='EMPTY'
ELSEIF                              &I=2
LET                                  &DUM='ATTIC'
ELSEIF                              &I=3
LET                                  &DUM='TEST LOOP'
ELSEIF                              &I=4
LET                                  &DUM='CUSTOM TRIM'
ELSEIF                              &I=5
LET                                  &DUM='FINAL TRIM'
ELSE
LET                                  &DUM='PAINT'
ENDIF
PUTPIC                              FILE=OUT,&DUM,(ML(KEYQUE,&I,&J),&J=3,5)
*****
ENDDO
PUTPIC                              FILE=OUT,LINES=7,&DUM
    
```

ENGINE PRODUCTION DETAIL:

```

DAILY ENGINES SHIPPED:
PRODUCTION DAYS:
ENGINE    1    2    3    4    5    6    7    8    9    10    TOTAL
-----
DO        &I=1,99
IF        MH(DSHIPS,&I,21)>0
PUTPIC    FILE=OUT,&PARTNO(&I),(MH(DSHIPS,&I,&J),&J=1,10),_
          MH(DSHIPS,&I,21)
*****
          ***  ***  ***  ***  ***  ***  ***  ***  ***  ***  *****
ENDIF
ENDDO
PUTPIC    FILE=OUT,LINES=7,(MH(DSHIPS,100,&J),&J=1,10),_
          MH(DSHIPS,100,21)
-----
TOTAL    ***  ***  ***  ***  ***  ***  ***  ***  ***  ***  *****
    
```

DAILY TRUCK SHIPMENT BY CUSTOMER:

```

PRODUCTION DAYS:
CUSTOMER      1    2    3    4    5    6    7    8    9    10    TOTAL
-----
DO            &I=1,99
IF            MH(TSHIPS,&I,21)>0
PUTPIC       FILE=OUT,&CUSTID(&I),(MH(TSHIPS,&I,&J),&J=1,10),_
              MH(TSHIPS,&I,21)
*****
ENDIF
ENDDO
PUTPIC       FILE=OUT,LINES=8,(MH(TSHIPS,100,&J),&J=1,10),_
              MH(TSHIPS,100,21)
-----
TOTAL        ****

```

ENGINE PROCESS DETAIL:

PROCESS TIME BETWEEN J-HOOK & 572 (IN HOURS):

```

ENGINE        # COMPLETE    AVG.    MAX.    MIN.
-----
DO            &I=1,99
IF            ML(PROTIME,&I,1)>0
PUTPIC       FILE=OUT,&PARTNO(&I),ML(PROTIME,&I,2),_
              (ML(PROTIME,&I,&J)/60.0,&J=3,5)
*****
ENDIF
ENDDO
PUTPIC       FILE=OUT,LINES=6,ML(PROTIME,100,2),_
              (ML(PROTIME,100,&J)/60.0,&J=3,5)
-----
TOTAL:       ****

```

WAREHOUSE TIME (IN HOURS):

```

ENGINE        # COMPLETE    AVG.    MAX.    MIN.
-----
DO            &I=1,99
IF            ML(WHSETIM,&I,1)>0
PUTPIC       FILE=OUT,&PARTNO(&I),ML(WHSETIM,&I,2),_
              (ML(WHSETIM,&I,&J)/60.0,&J=3,5)
*****
ENDIF
ENDDO
PUTPIC       FILE=OUT,LINES=6,ML(WHSETIM,100,2),_
              (ML(WHSETIM,100,&J)/60.0,&J=3,5)
-----
TOTAL:       ****

```

TRUCK GRID TIME (AWAITING SHIPMENT) IN HOURS:

```

CUSTOMER      # COMPLETE    AVG.    MAX.    MIN.
-----
DO            &I=1,49
IF            ML(GRIDTIM,&I,1)>0
PUTPIC       FILE=OUT,&CUSTID(&I),ML(GRIDTIM,&I,2),_
              (ML(GRIDTIM,&I,&J)/60.0,&J=3,5)
*****
ENDIF
ENDDO
PUTPIC       FILE=OUT,LINES=6,ML(GRIDTIM,100,2),_
              (ML(GRIDTIM,100,&J)/60.0,&J=3,5)
-----
TOTAL:       ****

```

TRUCK LOAD TIME IN HOURS:

```

CUSTOMER      # COMPLETE    AVG.    MAX.    MIN.
-----
DO            &I=1,49
IF            ML(TRKLDTIM,&I,1)>0
PUTPIC       FILE=OUT,&CUSTID(&I),ML(TRKLDTIM,&I,2),_
              (ML(TRKLDTIM,&I,&J)/60.0,&J=3,5)

```

```

*****
ENDIF
ENDDO
PUTPIC FILE=OUT,LINES=6,ML(TRKLDTIM,100,2),_
(ML(TRKLDTIM,100,&J)/60.0,&J=3,5)
-----
TOTAL: *****
FINISH SEQUENCE VARIANCE:
ENGINE # COMPLETE AVG. MAX. MIN.
-----
DO &I=1,99
IF ML(SEQVAR,&I,2)>0
PUTPIC FILE=OUT,&PARINO(&I),(ML(SEQVAR,&I,&J),&J=2,5)
*****
ENDIF
ENDDO
PUTPIC FILE=OUT,LINES=9,(ML(SEQVAR,100,&J),&J=2,5),&WDAYS(2)
-----
TOTAL: *****

```

TECHNICIAN PERFORMANCE BY DEPARTMENT
DEPT: 568
OPERATING DAYS/WEEK: *

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
DO	&I=301,400			
LET	&K=&I-300			
IF	MX(TCHASN,&K,1)=2			
PUTPIC	FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I),FT(&I),_ FRV(&I)/10.0			
*****	*	*****	***.*	***.* %
ENDIF				
ENDDO				
PUTPIC	FILE=OUT,LINES=6,&WDAYS(3)			

DEPT: 569
OPERATING DAYS/WEEK: *

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
DO	&I=301,400			
LET	&K=&I-300			
IF	(MX(TCHASN,&K,1)=3)OR(MX(TCHASN,&K,1)=8)			
PUTPIC	FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I),FT(&I),_ FRV(&I)/10.0			
*****	*	*****	***.*	***.* %
ENDIF				
ENDDO				
PUTPIC	FILE=OUT,LINES=6,&WDAYS(4)			

DEPT: 570
OPERATING DAYS/WEEK: *

TECHNICIAN	SHIFT	# ENGINES PROCESSED	AVG. TIME/ ENGINE	% ULT.
DO	&I=301,400			
LET	&K=&I-300			
IF	MX(TCHASN,&K,1)=4			
PUTPIC	FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I),FT(&I),_ FRV(&I)/10.0			
*****	*	*****	***.*	***.* %
ENDIF				
ENDDO				
PUTPIC	FILE=OUT,LINES=6,&WDAYS(5)			

DEPT: 571
OPERATING DAYS/WEEK: *

```

TECHNICIAN      SHIFT      # ENGINES
PROCESSED      AVG. TIME/
ENGINE      % ULT.
-----
DO              &I=301,400
LET            &K=&I-300
IF            MX(TCHASN,&K,1)=5
PUTPIC        FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I),FT(&I),_
FRV(&I)/10.0
*****        *          *****          ***.*          ***.* %
ENDIF
ENDDO
PUTPIC        FILE=OUT,LINES=6,&WDAYS(6)

DEPT: 5/2
OPERATING DAYS/WEEK: *

TECHNICIAN      SHIFT      # TRUCKS
PROCESSED      AVG. TIME/
TRUCK      % ULT.
-----
DO              &I=301,400
LET            &K=&I-300
IF            MX(TCHASN,&K,1)=6
PUTPIC        FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I),FT(&I),_
FRV(&I)/10.0
*****        *          *****          ***.*          ***.* %
ENDIF
ENDDO
PUTPIC        FILE=OUT,LINES=6,&WDAYS(6)

DEPT: 570 PAINT
OPERATING DAYS/WEEK: *

TECHNICIAN      SHIFT      # ENGINES
PROCESSED      AVG. TIME/
ENGINE      % ULT.
-----
DO              &I=301,400
LET            &K=&I-300
IF            MX(TCHASN,&K,1)=7
IF            (MX(TCHASN,&K,3)=PNTTC)OR(MX(TCHASN,&K,4)=PNTTC)
PUTPIC        FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I)*2,FT(&I)/2.0,_
FRV(&I)/10.0
*****        *          *****          ***.*          ***.* %
ELSE
PUTPIC        FILE=OUT,&TCHNM(&K),MX(TCHASN,&K,2),FC(&I),FT(&I),_
FRV(&I)/10.0
*****        *          *****          ***.*          ***.* %
ENDIF
ENDIF
ENDDO
*
* Test Summary
*
PUTPIC        FILE=TSUM,&TESTID,&TESTDSCR,CURDATE,FLT(&EPROD(1)/&SDAY),_
(FLT(&EPROD(&J)/&SDAY),&J=3,5),FLT(&EPROD(7)/&SDAY),_
FLT(MH(DSHIPS,100,21))/FLT(&SDAY),SA(EWIPQ),SM(EWIPQ),_
CA(FINV),CM(FINV),SA(TOTALQ),SM(TOTALQ),_
(ML(PROTIME,100,&J)/1440.0,&J=3,4),_
(ML(GRIDTIM,100,&J)/1440.0,&J=3,4),(ML(SEQVAR,100,&J),&J=3,5)
*****
*****
CLOSE        TSUM
END

```

APPENDIX C

Snapshot of Animated Simulation Run

